

Topics on Hyperbolic Function Theory in Geometric Algebra with a Positive Signature

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Abstract. In this paper we study geometric algebra valued null solutions of the equation

$$D_\ell f - \frac{k}{x_0} Q_0 f = 0$$

on the upper half $\mathbb{R}^{n+1} \cap \{x_0 > 0\}$, where D_ℓ is the Dirac operator and Q_0 is a projection-type mapping. Null solutions are called hypergenic functions. We will also study their local properties and integral representations.

Keywords. Hypergenic function, Cauchy formula, Borel-Pompeiu formula, multivector function.

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1. Preliminaries

Let $\{e_0, \dots, e_n\}$ be the standard basis in \mathbb{R}^{n+1} . The Clifford (geometric) algebra $\mathcal{C}\ell_{n+1}$ is a free associative algebra with a unit generated by the standard basis vectors together with the defining relations

$$e_i e_j + e_j e_i = 2\delta_{ij}$$

for each $i, j = 0, \dots, n$.

The Clifford algebra $\mathcal{C}\ell_{n+1}$ has dimension 2^{n+1} and the canonical basis is given by $e_A = e_{a_1} \cdots e_{a_k}$ where $A = \{a_1, \dots, a_k\} \subset N = \{0, \dots, n\}$ and $a_1 < \dots < a_k$. Especially $e_\emptyset = 1$ and $e_{\{j\}} = e_j$.

A space of k -vectors is defined by $\mathcal{C}\ell_n^k = \text{span}\{e_A : |A| = k\}$. Any $a \in \mathcal{C}\ell_{n+1}$ admits the multivector decomposition:

$$a = [a]_0 + [a]_1 + \cdots + [a]_{n+1}$$

with $[a]_k \in \mathcal{C}\ell_{n+1}^k$. The space of 0-vectors is identified with the set of real numbers \mathbb{R} and the set of 1-vectors is identified with the Euclidean space \mathbb{R}^{n+1} .

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The *main involution* is the algebra automorphism

$$': \mathcal{C}\ell_{n+1} \rightarrow \mathcal{C}\ell_{n+1}$$

defined by the relations

$$e'_j = -e_j \quad \text{and} \quad (ab)' = a'b'$$

for $a, b \in \mathcal{C}\ell_{n+1}$.

Assume that Ω is an open subset of \mathbb{R}^{n+1} . In the canonical basis every function $f: \Omega \rightarrow \mathcal{C}\ell_{n+1}$ admits the representation

$$f = \sum_{A \subset N} e_A f_A$$

where each f_A is a real valued function on Ω . A function f is called differentiable in Ω if each f_A is differentiable in Ω . If f is differentiable we define the left Dirac operator by

$$D_\ell f = \sum_{k=0}^n e_k \frac{\partial f}{\partial x_k}$$

and the right Dirac operator by

$$D_r f = \sum_{k=0}^n \frac{\partial f}{\partial x_k} e_k.$$

It is easy to see that the square of the Dirac operator is the Laplacian:

$$\Delta := D_\ell D_\ell = D_r D_r = \sum_{j=0}^n \frac{\partial^2}{\partial x_j^2}.$$

The upper half space is the Riemannian manifold $\mathbb{R}_+^{n+1} = \mathbb{R}^{n+1} \cap \{x_0 > 0\}$ with the metric

$$g_k = \frac{dx_0^2 + \cdots + dx_n^2}{x_0^{2k/(n-1)}}.$$

In the upper half space the coordinate x_0 has a special role. Thus we generate the Clifford algebra $\mathcal{C}\ell_n$ by $\{e_1, \dots, e_n\}$. Using the Clifford algebra $\mathcal{C}\ell_n$ the Clifford algebra $\mathcal{C}\ell_{n+1}$ admits the following decomposition

$$\mathcal{C}\ell_{n+1} = \mathcal{C}\ell_n \oplus e_0 \mathcal{C}\ell_n.$$

Thus, if $a \in \mathcal{C}\ell_{n+1}$ there exist $b, c \in \mathcal{C}\ell_n$ such that

$$a = b + e_0 c.$$

Let us denote $P_0 a := b$ and $Q_0 a := c$ and use the abbreviations $(P_0 a)' = P'_0 a$ and $(Q_0 a)' = Q'_0 a$ for each $a \in \mathcal{C}\ell_{n+1}$. Hence if $a \in \mathcal{C}\ell_{n+1}$ we obtain the “projector” decomposition

$$a = P_0 a + e_0 Q_0 a.$$

Using the above decomposition we may define the algebra automorphism

$$\hat{\cdot}: \mathcal{C}\ell_{n+1} \rightarrow \mathcal{C}\ell_{n+1}$$

by

$$\widehat{a} = P_0a - e_0Q_0a.$$

This automorphism is called the *hat involution*. If $a, b \in \mathcal{C}\ell_{n+1}$ it is straightforward to deduce that $\widehat{ab} = \widehat{a}\widehat{b}$. Also $\widehat{e}_j = (-1)^{\delta_{j,0}}e_j$ for $j = 0, \dots, n$.

Let Ω be an open subset of the upper half-space \mathbb{R}_+^{n+1} . The *left modified Dirac operator* on Ω is defined by

$$H_k^\ell f = D_\ell f - \frac{k}{x_0}Q_0f,$$

and similarly the *right modified Dirac operator* is defined by

$$H_k^r f = D_r f - \frac{k}{x_0}Q'_0f$$

(cf. [5, 6, 7]) where k is an arbitrary real number.

Null solutions of the left (resp. right) modified Dirac operator are called *left* (resp. *right*) k -*hypergenic functions*.

We shall also use the abbreviated notations $H^\ell := H_{(n-1)}^\ell$ and $H^r := H_{(n-1)}^r$ for the index $k = n - 1$. Null solutions of the previous operators are called *left* (resp. *right*) *hypergenic functions*.

As a technical tool we will need the P_0 - and Q_0 -parts of the operators H_k^ℓ and H_k^r .

Lemma 1. *Let $f: \Omega \rightarrow \mathcal{C}\ell_{n+1}$ be a differentiable function. Then*

$$(a) \quad P_0(H_k^\ell f) = D_1P_0f + \frac{\partial Q_0f}{\partial x_0} - \frac{k}{x_0}Q_0f,$$

$$(b) \quad Q_0(H_k^\ell f) = \frac{\partial P_0f}{\partial x_0} - D_1Q_0f,$$

$$(c) \quad P_0((H_k^\ell)^2 f) = \Delta P_0f - \frac{k}{x_0} \frac{\partial P_0f}{\partial x_0},$$

$$(d) \quad Q_0((H_k^\ell)^2 f) = \Delta Q_0f - \frac{k}{x_0} \frac{\partial Q_0f}{\partial x_0} + \frac{k}{x_0^2}Q_0f,$$

where

$$D_1 = e_1 \frac{\partial}{\partial x_1} + \dots + e_n \frac{\partial}{\partial x_n}.$$

Proof. We will prove only (a) and (b) since the proofs for (c) and (d) are available in the proof of [5, Thm. 1.8]. Assume a function $f = P_0f + e_0Q_0f$ is differentiable. Since

$$D_1 = e_1 \frac{\partial}{\partial x_1} + \dots + e_n \frac{\partial}{\partial x_n}$$

we obtain

$$D_\ell(P_0f) = e_0 \frac{\partial P_0f}{\partial x_0} + D_1P_0f$$

and

$$D_\ell(e_0Q_0f) = \frac{\partial Q_0f}{\partial x_0} - e_0D_1Q_0f.$$

Previous observations implies that

$$\begin{aligned} H_k^\ell f &= H_k^\ell(P_0f + e_0Q_0f) \\ &= D_\ell(P_0f) + D_\ell(e_0Q_0f) - \frac{k}{x_0}Q_0f \\ &= \left\{ D_1P_0f + \frac{\partial Q_0f}{\partial x_0} - \frac{k}{x_0}Q_0f \right\} + e_0 \left\{ \frac{\partial P_0f}{\partial x_0} - D_1Q_0f \right\}. \end{aligned}$$

The proof is complete. ■

2. Local properties of hypergenic functions

In this section we consider local properties of hypergenic functions. If Ω is an open subset in \mathbb{R}_+^{n+1} the operator

$$\Delta_m h = x_0^2 \left(\Delta h - \frac{k}{x_0} \frac{\partial h}{\partial x_0} \right)$$

is called *the Modified Laplace-Beltrami operator* for a twice continuously differentiable function $h : \Omega \rightarrow \mathcal{C}\ell_{n+1}$. In [5] we obtained the following theorem.

Theorem 2. *Let $\Omega \subset \mathbb{R}_+^{n+1}$ be an open subset and $f : \Omega \rightarrow \mathcal{C}\ell_{n+1}$ be a twice continuously differentiable k -hypergenic function. The function P_0f is a solution of the equation $\Delta_m P_0f = 0$ and Q_0f is a solution of the eigenvalue problem $\Delta_m Q_0f = -kQ_0f$.*

The Euclidean ball with the radius $r > 0$ and with the center a is denoted by $B_r(a)$.

Theorem 3. *Let $\Omega \subset \mathbb{R}_+^{n+1}$ be open. A differentiable function $f : \Omega \rightarrow \mathcal{C}\ell_{n+1}$ is hypergenic if and only if for any $a \in \Omega$ there exists $r > 0$ satisfying $B_r(a) \subset \Omega$ and a map $g : B_r(a) \rightarrow \mathcal{C}\ell_{n,0}$ satisfying*

$$f = D_\ell g \quad \text{and} \quad \Delta_m g = 0.$$

Proof. Assume first that the radius $r > 0$ and the function g exists. Since $f = D_\ell g$ we get in the neighborhood of a

$$H_k^\ell f = \Delta g - \frac{k}{x_0}Q_0(Dg) = \Delta g - \frac{k}{x_0} \frac{\partial g}{\partial x_0} = \frac{1}{x_0^2} \Delta_{LB}g = 0.$$

Let $f : \Omega \rightarrow \mathcal{C}\ell_{n+1}$ be a hypergenic function. Let us denote $x = (x_0, \tilde{x}) \in \mathbb{R} \times \mathbb{R}^n$ and $\Delta_1 := D_1D_1$. Assume that s_A is a solution of the Poisson problem

$$\Delta_1 s_A(\tilde{x}) = (P_0f)_A(a_0, \tilde{x})$$

in $B_r(a) \cap \mathbb{R}^n$ and let $s = \sum_{A \subset \{1, \dots, n\}} s_A$. The solution of the Poisson problem obviously exists (cf. [1]). Then we define

$$g(x) = \int_{a_0}^{x_0} Q_0 f(t, \tilde{x}) s dt + D_1 s(\tilde{x})$$

and obtain

$$D_\ell g(x) = e_0 Q_0 f(x) + \int_{a_0}^{x_0} D_1 Q_0 f(t, \tilde{x}) dt + \Delta_1 s(\tilde{x}).$$

Using Lemma 1 we obtain

$$D_1 Q_0 f = \frac{\partial P_0 f}{\partial x_0}$$

and

$$D_\ell g(x) = e_0 Q_0 f(x) + \int_{a_0}^{x_0} \frac{\partial P_0 f}{\partial x_0}(t, \tilde{x}) dt + P_0 f(a_0, \tilde{x}) = f(x).$$

Similarly we see that

$$0 = D_\ell f - \frac{k}{x_0} Q f = \Delta g - \frac{k}{x_0} \frac{\partial g}{\partial x_0},$$

which completes the proof. ■

3. On the Euler operator in the class of hypergenic functions

An operator

$$E = \sum_{i=0}^n x_i \frac{\partial}{\partial x_i}$$

is called an Euler operator. It is a scalar operator and measures the degree of homogeneity of a function. In this section we shall deduce that the class of hypergenic functions is invariant under the Euler operator. First we recall the following well known result.

Lemma 4. *If D_ℓ is the Dirac operator and E is the Euler operator we have*

$$D_\ell E - E D_\ell = [D_\ell, E] = D_\ell.$$

The similar result holds in the class of hypergenic functions.

Theorem 5. *If H_k^ℓ is the modified Dirac operator and E is the Euler operator we have*

$$H_k^\ell E - E H_k^\ell = [H_k^\ell, E] = H_k^\ell.$$

Proof. Let

$$D_\ell f - \frac{k}{x_0} Q_0 f = 0.$$

Applying E to

$$\frac{k}{x_0} Q_0 f$$

we obtain

$$\frac{k}{x_0} Q_0 E f = \frac{k}{x_0} Q_0 f + E \left(\frac{k}{x_0} Q_0 f \right).$$

Using the previous lemma we obtain

$$\begin{aligned} H_k^\ell E f &= D_\ell E f - \frac{k}{x_0} Q_0 E f \\ &= D_\ell f + E D f - \frac{k}{x_0} Q_0 f - E \left(\frac{k}{x_0} Q_0 f \right) \\ &= D_\ell f - \frac{k}{x_0} Q_0 f + E \left(D f - \frac{k}{x_0} Q_0 f \right) = 0. \end{aligned}$$

The proof is complete. ■

Corollary 6. *Let $f: \Omega \rightarrow \mathcal{C}\ell_{n+1}$ be a differentiable function. If the function f is k -hypergenic then $E f$ is k -hypergenic.*

If f is a hypergenic function then the previous theorem gives us a method how to construct more hypergenic functions.

For every k -hypergenic function $f: \Omega \rightarrow \mathcal{C}\ell_{n+1,0}$ there exists the sequence of hypergenic functions defined by

$$E^m f := \underbrace{E \cdots E}_m f$$

for each $m \in \mathbb{N}$ and $E^0 f = f$. This sequence $\{E^m f: m = 0, 1, \dots\}$ is called the *homogenized sequence* of f .

As an example we consider the monomials

$$X_i = \sum_{j=0}^n (-1)^{\delta_{ij}} x_j e_j$$

where $i = 1, \dots, n$. Since $H^\ell X_i = 0$ the monomials X_i are hypergenic. Moreover, since

$$E X_i = X_i$$

for each $i = 1, \dots, n$, the homogenized sequence of X_i is just $\{X_i\}$.

4. Further representation results

In this section we will consider the improved version of Cauchy’s formula. The “original” Cauchy’s formula is represented in [5]. The second aim is to prove the Borel-Pompeiu formula using the language of the modified Dirac operators.

First we recall briefly some preliminaries from integration theory. Let M be a k -dimensional manifold-with-boundary in \mathbb{R}^{n+1} , see e.g. [14]. The boundary of M is denoted by ∂M . If moreover

$$\Lambda^* M = \bigoplus_{p=0}^{n+1} \Lambda^p M$$

is the exterior algebra over \mathbb{R}^{n+1} with the basis $\{dx_0, dx_1, \dots, dx_n\}$ we then construct the bundle $\mathcal{C}\ell_{n+1} \otimes_{\mathbb{R}} \Lambda^k M$. If $\omega(x)$ is a section of the previous bundle over $x \in M$ it is of the form

$$\omega(x) = \sum_{A,B} \omega_{A,B}(x) e_A dx_B,$$

where $B = \{b_1, \dots, b_k\} \subset N = \{1, \dots, n\}$ and $dx_B = dx_{b_1} \wedge \dots \wedge dx_{b_k}$. The meaning of the symbol $e_A dx_B$ is clear. Furthermore let M be an oriented k -dimensional manifold-with-boundary in \mathbb{R}^{n+1} , then we define

$$\int_M \omega(x) = \sum_{A,B} e_A \int_M \omega_{A,B}(x) dx_B.$$

In this paper M will be $(n + 1)$ dimensional or n -dimensional (i.e. the boundary of M). The $(n + 1)$ -form

$$dV = dx_0 \wedge dx_1 \wedge \dots \wedge dx_n$$

on M is called the (Riemannian) volume element. In surface integrals we shall often use the n -form

$$d\sigma = \sum_{i=0}^n (-1)^i e_i d\tilde{x}_i$$

where

$$d\tilde{x}_i = dx_0 \wedge dx_1 \wedge \dots \wedge dx_{i-1} \wedge dx_{i+1} \wedge \dots \wedge dx_n$$

for each $i = 0, 1, \dots, n$. The exterior derivative d for Clifford algebra valued differential forms is defined componentwise, i.e. if

$$\omega = \sum_{A,B} \omega_A e_B$$

is a k -form then

$$d\omega = \sum_{A,B} d\omega_A e_B.$$

Applying the classical Stokes Theorem (see [14]) it is easy to prove the following theorem.

Theorem 7 (Stokes). *Let ω be a $\mathcal{C}\ell_{n+1}$ -valued k -form on an oriented k -dimensional manifold-with-boundary M . Then*

$$\int_M d\omega = \int_{\partial M} \omega.$$

We recall the following version¹ of Cauchy's formula given in [5].

Theorem 8. *Let Ω be an open subset of \mathbb{R}_+^{n+1} and $f: \Omega \rightarrow \mathcal{C}\ell_{n+1}$ be hypergenic. Let $M \subset \Omega$ be an oriented $(n+1)$ -dimensional manifold-with-boundary. Then*

$$f(y) = \frac{2^{n-1}y_0^{n-1}}{\omega_{n+1}} \int_{\partial M} \frac{(x-y)^{-1}d\sigma(x)f(x) - (\hat{x}-y)^{-1}\widehat{d\sigma}(x)\widehat{f}(x)}{|x-y|^{n-1}|x-\widehat{y}|^{n-1}}$$

where y is an interior point of the manifold M .

If we decompose

$$d\sigma(x)f(x) = P_0(d\sigma(x)f(x)) + e_0Q_0(d\sigma(x)f(x))$$

we obtain

$$\begin{aligned} (1) \quad & (x-y)^{-1}d\sigma(x)f(x) - (\hat{x}-y)^{-1}\widehat{d\sigma}(x)\widehat{f}(x) \\ & = ((x-y)^{-1} - (\hat{x}-y)^{-1})P_0(d\sigma(x)f(x)) \\ & \quad + ((x-y)^{-1} + (\hat{x}-y)^{-1})e_0Q_0(d\sigma(x)f(x)). \end{aligned}$$

If we define the kernel by

$$\Lambda(x, y) := \frac{(x-y)^{-1} - (\hat{x}-y)^{-1}}{|x-y|^{n-1}|x-\widehat{y}|^{n-1}},$$

we obtain the following lemma.

Lemma 9.

$$\frac{(x-y)^{-1} + (\hat{x}-y)^{-1}}{|x-y|^{n-1}|x-\widehat{y}|^{n-1}}e_0x_0 = \Lambda(x, y)(y - Px).$$

Using the identity (1) and the above lemma we obtain

$$\begin{aligned} & \frac{(x-y)^{-1}d\sigma(x)f(x) - (\hat{x}-y)^{-1}\widehat{d\sigma}(x)\widehat{f}(x)}{|x-y|^{n-1}|x-\widehat{y}|^{n-1}} \\ & = \Lambda(x, y)P_0(d\sigma(x)f(x)) + \Lambda(x, y)\frac{y - Px}{x_0}Q_0(d\sigma(x)f(x)). \end{aligned}$$

Hence we obtain the improved version of Cauchy's formula:

¹In this paper we use the Cauchy's formula with the "manifold assumptions". It is easy to see that the proof for it in [5] is exactly the same since, e.g. the outer unit vector field on the boundary of the oriented manifold-with-boundary always exists (cf. [10]).

Theorem 10. Assume that Ω is an open subset of \mathbb{R}_+^{n+1} and $f: \Omega \rightarrow \mathcal{C}\ell_{n+1}$ be hypergenic. Let $M \subset \Omega$ be an oriented $(n + 1)$ -dimensional manifold-with-boundary. Then

$$f(y) = \frac{2^{n-1}y_0^{n-1}}{\omega_{n+1}} \int_{\partial M} \Lambda(x, y) \left(P_0(d\sigma(x)f(x)) + \frac{y - Px}{x_0} Q_0(d\sigma(x)f(x)) \right),$$

where y is an interior point of the manifold M .

Theorem 11 (Borel-Pompeiu). Let $\Omega \subset \mathbb{R}_+^{n+1}$ be open and $f: \Omega \rightarrow \mathcal{C}\ell_{n+1}$ be a differentiable function. Let $M \subset \Omega$ be an oriented $(n + 1)$ -dimensional manifold-with-boundary. Then

$$f(y) = \frac{2^{n-1}y_0^{n-1}}{\omega_{n+1}} \int_{\partial M} \left\{ \frac{1}{x_0^{n-1}} P_0(p(x, y)d\sigma(x)f(x)) + e_0 Q_0(q(x, y)d\sigma(x)f(x)) \right\} + \frac{2^{n-1}y_0^{n-1}}{\omega_{n+1}} \int_M \frac{1}{x_0^{n-1}} \{ P_0(p(x, y)H^\ell f(x)) + e_0 Q_0(q(x, y)H^\ell f(x)) \} dV$$

where y is an interior point of the manifold M . The kernels

$$p(x, y) := x_0^{n-1} \frac{(x - y)^{-1} - (x - \widehat{y})^{-1}}{|x - y|^{n-1}|x - \widehat{y}|^{n-1}},$$

$$q(x, y) := \frac{(x - y)^{-1} + (x - \widehat{y})^{-1}}{|x - y|^{n-1}|x - \widehat{y}|^{n-1}}$$

are hypergenic with respect to x on $\mathbb{R}^{n+1} \setminus \{y, \widehat{y}\}$ for each $y \in \mathbb{R}^{n+1}$.

Remark 1. In the Borel-Pompeiu’s formula hypergenicity has no role. Assuming that f is hypergenic we obtain the original version of Cauchy’s formula.

In order to prove the Borel-Pompeiu’s theorem, let us first state a few basic lemmata. For the proofs we refer to [5].

Lemma 12. The function $x \mapsto p(x, y)$ is right $(n - 1)$ -hypergenic and the function $x \mapsto q(x, y)$ is right $-(n - 1)$ -hypergenic on $\mathbb{R}^{n+1} \setminus \{y, \widehat{y}\}$ for each $y \in \mathbb{R}^{n+1}$.

Lemma 13. Let Ω be an open subset of \mathbb{R}_+^{n+1} and $f, g: \Omega \rightarrow \mathcal{C}\ell_{n+1}$ be differentiable functions. Let $M \subset \Omega$ be an oriented $(n + 1)$ -dimensional manifold-with-boundary. If g is right $-(n - 1)$ -hypergenic then

$$\int_{\partial M} \frac{1}{x_0^{n-1}} P_0(gd\sigma f) = \int_M \frac{1}{x_0^{n-1}} P_0(gH^\ell f) dV$$

and if g is right hypergenic then

$$\int_{\partial M} Q_0(gd\sigma f) = \int_M Q_0(gH^\ell f) dV.$$

Proof. This is a corollary of Lemma 2.6 and Lemma 2.9 in [5]. ■

Lemma 14. *If $f: \Omega \rightarrow \mathcal{C}\ell_{n+1,0}$ is continuous and $B_r(y) \subset \Omega \subset \mathbb{R}_+^{n+1}$ then*

$$\begin{aligned} \frac{2^{n-1}y_0^{n-1}}{\omega_{n+1}} \int_{\partial B_r(y)} \frac{1}{x_0^{n-1}} P_0(p(x,y) d\sigma(x) f(x)) &\rightarrow P_0 f(y), \\ \frac{2^{n-1}y_0^{n-1}}{\omega_{n+1}} \int_{\partial B_r(y)} Q_0(q(x,y) d\sigma(x) f(x)) &\rightarrow Q_0 f(y) \end{aligned}$$

as $r \rightarrow 0$.

Proof. See the proofs of Theorem 2.4 and 2.7 in [5]. ■

Proof of Theorem 11. For each interior point $y \in M$ there exists $r > 0$ such that $\overline{B_r(y)} \subset M$. We denote $M_r(y) := M \setminus B_r(y)$. Then

$$\begin{aligned} (2) \quad &\int_{\partial M} \frac{1}{x_0^{n-1}} P_0(p(x,y) d\sigma(x) f(x)) \\ &+ e_0 \int_{\partial M} Q_0(q(x,y) d\sigma(x) f(x)) \\ &= \int_{\partial M_r(y)} \frac{1}{x_0^{n-1}} P_0(p(x,y) d\sigma(x) f(x)) \\ &+ e_0 \int_{\partial M_r(y)} Q_0(q(x,y) d\sigma(x) f(x)) \\ &+ \int_{\partial B_r(y)} \frac{1}{x_0^{n-1}} P_0(p(x,y) d\sigma(x) f(x)) \\ &+ e_0 \int_{\partial B_r(y)} Q_0(q(x,y) d\sigma(x) f(x)). \end{aligned}$$

Using Lemma 14 we obtain

$$\begin{aligned} &\int_{\partial B_r(y)} \frac{1}{x_0^{n-1}} P_0(p(x,y) d\sigma(x) f(x)) \\ &+ e_0 \int_{\partial B_r(y)} Q_0(q(x,y) d\sigma(x) f(x)) \rightarrow \frac{\omega_{n+1}}{2^{n-1}y_0^{n-1}} f(y) \end{aligned}$$

as $r \rightarrow 0$. Using Lemma 12 and 13 we obtain

$$\begin{aligned} \int_{\partial M_r(y)} \frac{1}{x_0^{n-1}} P_0(p(x,y) d\sigma(x) f(x)) &= \int_{M_r(y)} \frac{1}{x_0^{n-1}} P_0(p(x,y) H^\ell f(x)) dx, \\ \int_{\partial M_r(y)} Q_0(q(x,y) d\sigma(x) f(x)) &= \int_{M_r(y)} Q_0(q(x,y) H^\ell f(x)) dx. \end{aligned}$$

Since $\int_{M_r(y)} \rightarrow \int_M$ as $r \rightarrow 0$, we obtain the result just taking $r \rightarrow 0$ in (2). ■

5. Multivector calculus

In [5] we also studied some connections between Q_0 -operator, H_k^ℓ -operators and the left- and right contraction -operators. In this section we will continue our study. First we recall some notions and properties.

Let $x \in \mathcal{C}\ell_{n+1}^1$ be a vector and $u \in \mathcal{C}\ell_{n+1}$ be an arbitrary Clifford number. The left contraction is defined by

$$(3) \quad x \lrcorner u = \frac{1}{2}(xu - u'x),$$

and the right contraction by

$$u \llcorner x = \frac{1}{2}(ux - xu').$$

Marcel Riesz has introduced in 1958 the exterior product in Clifford algebras by

$$(4) \quad x \wedge u = \frac{1}{2}(xu + u'x).$$

Adding (3) and (4) together we obtain the Clifford product

$$xu = x \lrcorner u + x \wedge u.$$

Moreover, if u is a k -vector we have $u' = (-1)^k u$. In this case we obtain

$$x \lrcorner u = (-1)^{k-1} u \llcorner x$$

and

$$x \wedge u = (-1)^k u \wedge x$$

for each vector x . Historical remarks and more comprehensive introduction to the contraction products and the exterior product, see [13].

Remark 2. If $x, y \in \mathcal{C}\ell_{n+1}^1$, then

$$x \lrcorner y = y \llcorner x = (x, y)$$

where (\cdot, \cdot) is the usual Euclidean inner product.

Next we recall a few handy formulae.

Lemma 15. *If x and y are vectors and u is a k -vector. Then*

- (a) $x \lrcorner (y \wedge u) = (x, y)u - y \wedge (x \lrcorner u),$
- (b) $x \lrcorner (y \lrcorner u) = -y \lrcorner (x \lrcorner u).$

Proof. See [7, 13]. ■

In the case of k -vectors it is convenient to represent P_0 - and Q_0 -operators using the Riesz's products as follows.

Proposition 16. *If $u \in \mathcal{C}\ell_{n+1}$ then*

- (a) $P_0 u = e_0 \lrcorner (e_0 \wedge u)$ and $Q_0 u = e_0 \lrcorner u,$
- (b) $P'_0 u = (e_0 \wedge u) \llcorner e_0$ and $Q'_0 u = u \llcorner e_0.$

Proof. (a) See the proof of $Qu = e_0 \lrcorner u$ in [5]. Using

$$e_0 u + u' e_0 = e_0 P u + Q u + P' u e_0 - e_0 Q' u e_0 = 2e_0 P u$$

we obtain

$$P_0 u = e_0 \frac{1}{2} (e_0 u + u' e_0) = e_0 (e_0 \wedge u) = e_0 \lrcorner (e_0 \wedge u),$$

since $e_0 \wedge e_0 \wedge u = 0$.

(b) Recall $P'_0 u = (P_0 u)'$ and $Q'_0 u = (Q_0 u)'$. Since

$$(e_0 \lrcorner v)' = \frac{1}{2} (e_0 v - v' e_0)' = \frac{1}{2} (v e_0 - e_0 v') = v \lrcorner e_0$$

for each $v \in \mathcal{C}\ell_{n+1}$ we obtain

$$P'_0 u = (e_0 \lrcorner (e_0 \wedge u))' = (e_0 \wedge u) \lrcorner e_0$$

and $Q'_0 u = u \lrcorner e_0$. ■

Let $\mathcal{E}^k(\Omega)$ be the set of k -vector valued functions on Ω . If $f \in \mathcal{E}^k(\Omega)$ is differentiable then the modified Dirac operators are represented in the form

$$\begin{aligned} H^\ell f &= D_\ell f - \frac{n-1}{x_0} e_0 \lrcorner f, \\ H^r f &= D_r f - \frac{n-1}{x_0} f \lrcorner e_0, \end{aligned}$$

on Ω .

We interpret the Dirac operator $D := D_\ell$ as a vector derivative. As in [9] we also interpret Df as a product of a vector and a Clifford number, i.e.,

$$\begin{aligned} D_\ell f &= D \lrcorner f + D \wedge f, \\ D_r f &= f \lrcorner D + f \wedge D. \end{aligned}$$

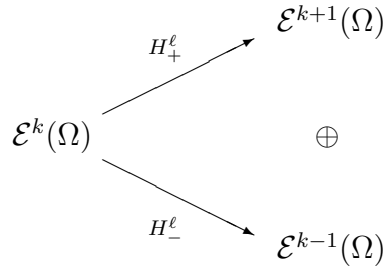
Thus if $f \in \mathcal{E}^k(\Omega)$ we define

$$\begin{aligned} H_+^\ell f &= [H^\ell f]_{k+1} = D \wedge f, \\ H_-^\ell f &= [H^\ell f]_{k-1} = D \lrcorner f - \frac{n-1}{x_0} e_0 \lrcorner f, \\ H_+^r f &= [H^r f]_{k+1} = f \wedge D, \\ H_-^r f &= [H^r f]_{k-1} = f \lrcorner D - \frac{n-1}{x_0} f \lrcorner e_0. \end{aligned}$$

Hence

$$H^\ell = H_+^\ell + H_-^\ell \quad \text{and} \quad H^r = H_+^r + H_-^r.$$

Mapping properties of the operator H^ℓ are illustrated in the following picture:



Theorem 17. *Let $f \in \mathcal{E}^k(\Omega)$ be a differentiable function on open $\Omega \subset \mathbb{R}_+^{n+1}$. Then*

$$\begin{aligned}
 H_-^\ell f &= 0, \\
 H_+^\ell f &= 0
 \end{aligned}$$

if and only if

$$H^\ell f = 0.$$

Proof. Assume

$$H^\ell f = \left(D - \frac{n-1}{x_0} e_0 \right) \lrcorner f + D \wedge f = 0.$$

Since

$$[H^\ell f]_{k-1} = \left(D - \frac{n-1}{x_0} e_0 \right) \lrcorner f = 0$$

and

$$[H^\ell f]_{k+1} = D \wedge f = 0$$

we obtain the result. ■

Proposition 18. *Let $f \in \mathcal{E}^k(\Omega)$ be a differentiable function. Then*

- (a) $(H_+^\ell)^2 = (H_-^\ell)^2 = 0,$
- (b) $H_-^\ell H_+^\ell = \Delta f - D \wedge (D \lrcorner f) - \frac{n-1}{x_0} \frac{\partial f}{\partial x_0} + \frac{n-1}{x_0} D \wedge (e_0 \lrcorner f),$
- (c) $H_+^\ell H_-^\ell = D \wedge (D \lrcorner f) + \frac{n-1}{x_0^2} e_0 \wedge (e_0 \lrcorner f) - \frac{n-1}{x_0} D \wedge (e_0 \lrcorner f).$

Proof. Let $f \in \mathcal{E}^k(\Omega)$ be a twice continuously differentiable function.

(a) First we compute

$$(H_+^\ell)^2 f = \sum_{i,j=0}^n e_i \wedge e_j \wedge \frac{\partial^2 f}{\partial x_j \partial x_i} = \sum_{i < j} e_i \wedge e_j \wedge \left(\frac{\partial^2 f}{\partial x_i \partial x_j} - \frac{\partial^2 f}{\partial x_j \partial x_i} \right) = 0.$$

Since $D \lrcorner D \lrcorner f = 0$ and $e_0 \lrcorner e_0 \lrcorner f = 0$ we have

$$(H_-^\ell)^2 f = -D \lrcorner \left(\frac{n-1}{x_0} e_0 \lrcorner f \right) - \frac{n-1}{x_0} e_0 \lrcorner (D \lrcorner f).$$

Using Lemma 15 we obtain

$$D_{\lrcorner} \left(\frac{n-1}{x_0} e_{0\lrcorner} f \right) = -\frac{n-1}{x_0} e_{0\lrcorner} (D_{\lrcorner} f).$$

Then $(H_{\lrcorner}^{\ell})^2 = 0$.

(b) Using Lemma 15 we have

$$D_{\lrcorner} (D \wedge f) = \Delta f - D \wedge (D_{\lrcorner} f)$$

and

$$e_{0\lrcorner} (D \wedge f) = \frac{\partial f}{\partial x_0} - D \wedge (e_{0\lrcorner} f).$$

Thus

$$\begin{aligned} H_{\lrcorner}^{\ell} H_{\lrcorner}^{\ell} f &= D_{\lrcorner} (D \wedge f) - \frac{n-1}{x_0} e_{0\lrcorner} (D \wedge f) \\ &= \Delta f - D \wedge (D_{\lrcorner} f) - \frac{n-1}{x_0} \frac{\partial f}{\partial x_0} + \frac{n-1}{x_0} D \wedge (e_{0\lrcorner} f). \end{aligned}$$

(c) We compute

$$\begin{aligned} H_{\lrcorner}^{\ell} H_{\lrcorner}^{\ell} f &= D \wedge (D_{\lrcorner} f) - D \wedge \left(\frac{n-1}{x_0} e_{0\lrcorner} f \right) \\ &= D \wedge (D_{\lrcorner} f) + \frac{n-1}{x_0^2} e_0 \wedge (e_{0\lrcorner} f) - \frac{n-1}{x_0} D \wedge (e_{0\lrcorner} f). \end{aligned}$$

■

Corollary 19. *Let $f \in \mathcal{E}^k(\Omega)$ be a differentiable function. Then*

$$(H^{\ell})^2 = H_{\lrcorner}^{\ell} H_{\lrcorner}^{\ell} + H_{\lrcorner}^{\ell} H_{\lrcorner}^{\ell}$$

and especially

$$(H^{\ell})^2 f = \Delta f - \frac{n-1}{x_0} \frac{\partial f}{\partial x_0} + \frac{n-1}{x_0^2} e_0 \wedge (e_{0\lrcorner} f).$$

Above results are formulated and proved only for the left hypergenic functions. In the next theorem we shall see that this is not a shortcoming of the theory.

Theorem 20. *Let $f \in \mathcal{E}^k(\Omega)$ be a differentiable function. The function f is left hypergenic if and only if it is right hypergenic.*

Proof. Let f be a differentiable k -vector-valued function. Then

$$\begin{aligned} H_{\lrcorner}^{\ell} f &= \sum_{j=0}^n e_{j\lrcorner} \frac{\partial f}{\partial x_j} - \frac{n-1}{x_0} e_{0\lrcorner} f \\ &= (-1)^{k-1} \left(\sum_{j=0}^n \frac{\partial f}{\partial x_j} \lrcorner e_j - f \lrcorner e_0 \frac{n-1}{x_0} \right) \\ &= (-1)^{k-1} H_{\lrcorner}^r f. \end{aligned}$$

Similarly

$$H_+^\ell f = \sum_{j=0}^n e_j \wedge \frac{\partial f}{\partial x_j} = (-1)^k \sum_{j=0}^n \frac{\partial f}{\partial x_j} \wedge e_j = (-1)^k H_+^r f.$$

The proof is complete. ■

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