

# An Evolutionary Structure of Convex Quadrilaterals

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We solve the problem of evolution of convex quadrilaterals by applying the inverse weighted Fermat-Torricelli problem, the invariance property of the weighted Fermat-Torricelli point in the plane  $\mathbb{R}^2$ , two-dimensional sphere  $S^2$  and the two-dimensional hyperboloid  $H^2$ . This means that the property of plasticity is inherited by some evolutionary convex quadrilaterals. An important application is the connection of the Fermat-Torricelli point with the fundamental equation of P. de Fermat.

*Keywords:* Fermat-Torricelli problem, inverse Fermat-Torricelli problem, generalized convex quadrilaterals

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## 1. Introduction

Pierre de Fermat in 1643 raised the question: given three points in the Euclidean plane, find the point that the sum of distances to these three points is minimized. Contributions to the problem have been made by E. Torricelli, J. Steiner and this is the main reason that we have named the corresponding point the Fermat-Torricelli point due to the first two contributors. E. Weiszfeld found the generalized weighted Fermat-Torricelli point ( $A_0$ ) for  $n$  given non-collinear points  $A_i(x_i, y_i)$  with non negative weights  $B_i$ ,  $i = 1, 2, \dots, n$  by using an algorithm that minimizes the function  $f(x, y)$  corresponding to the coordinates of  $A_0(x, y)$  (see [5] and [4]). The weighted “Fermat-Torricelli” point of a plane triangle and the inverse weighted “Fermat-Torricelli” problem have been studied in [3]. A unified approach for the weighted “Fermat-Torricelli” point of a given plane, spherical or hyperbolic triangle  $\nabla A_1 A_2 A_3$  with non-negative weights  $B_i$  that correspond to each vertex  $A_i$  respectively is studied in [7]. Concerning the floating case and absorbed case (see below) of the weighted “Fermat-Torricelli” point in  $\mathbb{R}^N$ , see [4] and Chapter II of [1]. For the solution of the problem in any regular surface of  $\mathbb{R}^3$  we refer to the indirect method of [6]. The invariance property of the weighted “Fermat-Torricelli” point holds for any given spherical, hyperbolic and planar (Euclidean) triangle (see [7]) and the inverse weighted “Fermat-Torricelli” problem in  $\mathbb{R}^2$  was also studied in [3]. For the case of the two-dimensional sphere  $S^2$  and two-dimensional hyperboloid  $H^2$  you can consult [7]. In this paper we derive the evolutionary structure of some weighted convex quadrilaterals  $A_1 A_2 A_3 A_4$  in  $\mathbb{R}^2$ ,  $S^2$ ,  $H^2$  under some conditions. The crucial point is to apply the invariance property of the weighted Fermat-Torricelli point and the inverse weighted

Fermat-Torricelli problem of four lines that meet at the weighted Fermat-Torricelli point at  $A_0$ . The connection of the weighted “Fermat-Torricelli point” in  $\mathbb{R}^2$  with the fundamental equation of P. de Fermat is a remarkable result that comes from the inverse weighted Fermat-Torricelli problem of four lines in  $\mathbb{R}^2$ .

## 2. The weighted Fermat-Torricelli point of a convex quadrilateral

Suppose that we have the convex quadrilateral  $A_1A_2A_3A_4$  such that  $B_i$  is the positive weight that corresponds to the vertex  $A_i$ ,  $i = 1, 2, 3, 4$ . We start with the notations: let  $a_i$  be the variable that represents the length of the geodesic segment  $A_0A_i$ ,  $a_{ij}$  be the length of the geodesic segment  $A_iA_j$  and  $\alpha_{ij}$  be the angle between the two geodesics  $A_iA_k$ ,  $A_kA_j$  for  $i, j, k = 1, 2, 3, 4$ ,  $i \neq j \neq k$ . The angles  $\alpha_3$ ,  $\alpha'_3$ ,  $\alpha''_3$ ,  $\alpha'''_3$  are defined in Figure 2.1 and their role is vital for the concluding results (see Figure 2.1).

Y. S. Kupitz and H. Martini gave an elegant proof of existence and uniqueness of the generalized Fermat-Torricelli point in  $\mathbb{R}^d$  for  $d = 2, \dots, n$  and also derived conditions for the floating case and absorbed case that exist at the interior of the polygon or at a vertex. We start by stating the problem:

**Problem 2.1.** *Find the weighted Fermat-Torricelli point of a given weighted convex quadrilateral  $A_1A_2A_3A_4$  with non-negative weights  $B_i$  that correspond to the vertex  $A_i$ , and the floating case occurs regarding the weights  $B_i$*

$$\left\| \sum_{j=1}^4 B_j \vec{u}(A_i, A_j) \right\| > B_i, i \neq j$$

for  $i, j = 1, 2, 3, 4$ .

**Solution 2.2.** The minimum function that corresponds to the weighted Fermat-Torricelli point  $A_0$  is:

$$B_1a_1 + B_2a_2 + B_3a_3 + B_4a_4 = \text{minimum.} \quad (1)$$

The weighted Fermat-Torricelli point will be found by calculating the angles  $a_{012}$ ,  $a_{023}$ ,  $a_{034}$ ,  $a_{041}$ . Let  $a_2$ ,  $a_3$ ,  $a_4$  the functions that depend on the variables  $a_1$  and  $\alpha_3$ : we assume that the floating case of the weighted Fermat-Torricelli point  $A_0$  occurs, in order to locate it in the interior of the convex quadrilateral  $A_1A_2A_3A_4$  (see [4]) with non-negative weights  $B_i$ ,  $i = 1, 2, 3, 4$ . The idea is to calculate the angles  $\alpha_{012}$ ,  $\alpha_{023}$ ,  $\alpha_{034}$ ,  $\alpha_{041}$  of  $A_0$ . The intersection of at least two segments of the cycles with lengths for instance  $\alpha_{012}$ ,  $\alpha_{023}$  that corresponds to the sides  $a_{12}$ ,  $a_{23}$  is the weighted Fermat-Torricelli point  $A_0$ . Let  $a_2$ ,  $a_3$ ,  $a_4$  the functions that depend on the variables  $a_1$  and  $\alpha_3$ :

$$a_2 = a_2(a_1, \alpha_3), \quad a_3 = a_3(a_1, \alpha_3), \quad a_4 = a_4(a_1, \alpha_3). \quad (2)$$

By differentiating the minimum function with respect to the variables  $\alpha_3$ ,  $a_1$ , two conditions are deduced:

$$B_2 \frac{\partial a_2}{\partial \alpha_3} + B_3 \frac{\partial a_3}{\partial \alpha_3} + B_4 \frac{\partial a_4}{\partial \alpha_3} = 0$$

$$B_1 + B_2 \frac{\partial a_2}{\partial a_1} + B_3 \frac{\partial a_3}{\partial a_1} + B_4 \frac{\partial a_4}{\partial a_1} = 0.$$

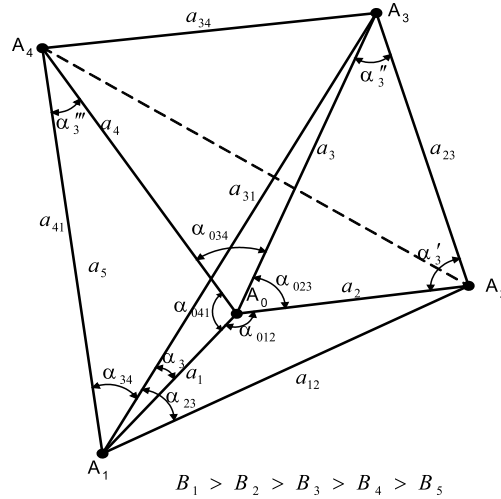


Figure 2.1

By calculating  $\frac{\partial a_2}{\partial \alpha_3}, \frac{\partial a_3}{\partial \alpha_3}, \frac{\partial a_4}{\partial \alpha_3}$  and by applying the “cosine law” and “sine law” to the corresponding triangles  $\nabla A_2 A_1 A_0, \nabla A_3 A_1 A_0, \nabla A_4 A_1 A_0$ , we derive the equation:

$$-B_2 \sin(\alpha_{012}) + B_3 \sin(\alpha_{034} + \alpha_{041}) + B_4 \sin(\alpha_{041}) = 0. \quad (3)$$

Similarly, from the differentiation with respect to the variable  $a_1$ , the second condition takes the form:

$$B_1 + B_2 \cos(\alpha_{012}) + B_3 \cos(\alpha_{034} + \alpha_{041}) + B_4 \cos(\alpha_{041}) = 0. \quad (4)$$

From (3), (4) two equations are derived:

$$\cot(\alpha_{034} + \alpha_{041}) = \frac{B_1 + B_2 \cos(\alpha_{012}) + B_4 \cos(\alpha_{041})}{B_4 \sin(\alpha_{041}) - B_2 \sin(\alpha_{012})} \quad (5)$$

$$B_3^2 = B_1^2 + B_2^2 + B_4^2 + 2B_2 B_4 \cos(\alpha_{041} + \alpha_{012}) + 2B_1 B_2 \cos(\alpha_{012}) + 2B_1 B_4 \cos(\alpha_{041}). \quad (6)$$

Two geometrical equations are used that depend on the angles  $\alpha_{012}, \alpha_{041}$  and they appear by applying the “sine law” to the triangles  $\nabla A_1 A_0 A_3, \nabla A_1 A_0 A_2, \nabla A_1 A_0 A_4$ :

$$\cot(\alpha_3) = \frac{\sin(\alpha_{23}) - \cos(\alpha_{23}) \cot(\alpha_{012}) - \frac{a_{31}}{a_{12}} \cot(\alpha_{034} + \alpha_{041})}{-\cos(\alpha_{23}) - \sin(\alpha_{23}) \cot(\alpha_{012}) + \frac{a_{31}}{a_{12}}} \quad (7)$$

$$\cot(\alpha_3) = \frac{\sin(\alpha_{34}) - \cos(\alpha_{34}) \cot(\alpha_{041}) + \frac{a_{31}}{a_{41}} \cot(\alpha_{034} + \alpha_{041})}{\cos(\alpha_{34}) + \sin(\alpha_{34}) \cot(\alpha_{041}) - \frac{a_{31}}{a_{41}}} \quad (8)$$

From (7), (8) and taking into account (5), we get the equation:

$$f_2(\alpha_{012}, \alpha_{041}) = 0. \quad (9)$$

The system of the two implicit equations (9), (6) give the angles  $\alpha_{012}, \alpha_{041}$ . If these values are replaced to equation (5), then  $\alpha_{034}$  is obtained. Finally,

$$\alpha_{023} = 2\pi - \alpha_{012} - \alpha_{034} - \alpha_{41}.$$

**Remark 2.3.** The Newton method may be selected and the initial conditions for the values of the two angles are taken from the inequalities between  $B_i$ ,  $i = 1, 2, 3, 4$ . The angle  $\alpha_3$  plays a vital role in the implementation of the computational approach of the generalized weighted “Fermat-Torricelli” point. By selecting different weights from Figure 2.1 modifications of signs will occur in equations (7), (8), by using the same method to calculate the  $\cot(\alpha_3)$ .

**Example 2.4.** For the case of tetragon the derived equations depend only on the values of the non-negative weights  $B_i$ ,  $i = 1, 2, 3, 4$ .

$$-\cot(\alpha_{041} - \alpha_{012}) + \cot(\alpha_{034} + \alpha_{041}) = \frac{\cot(\alpha_{012}) + \cot(\alpha_{041})}{\cot(\alpha_{041}) - \cot(\alpha_{012})}$$

and

$$\cot(\alpha_{034} + \alpha_{041}) = \frac{B_1 + B_2 \cos(\alpha_{012}) + B_4 \cos(\alpha_{041})}{B_4 \sin(\alpha_{041}) - B_2 \sin(\alpha_{012})}.$$

The second equation of the variables  $\alpha_{012}$ ,  $\alpha_{041}$  is the equation 6. The first equation depends on the orientation of the angle  $\alpha_3$  and it was taken as it appears in Figure 2.1. This means that by selecting different weights  $B_1, B_2, B_3, B_4$ , the signs of the first equation could change.

### 3. The invariance property of the weighted Fermat-Torricelli point.

**Proposition 3.1.** *Suppose that there is an  $n$ -convex polygon  $A_1 A_2 \dots A_n$  in  $\mathbb{R}^2$  and each vertex  $A_i$  has a non-negative weight  $B_i$  for  $i = 1, 2, \dots, n$ . Assume that the floating case of the generalized weighted Fermat-Torricelli point  $A_0$  point is valid: for each  $A_i \in A_1, \dots, A_n$*

$$\left\| \sum_{j=1}^n B_j \vec{u}(A_i, A_j) \right\| > B_i, i \neq j.$$

*If  $A_0$  is connected with every vertex  $A_i$  for  $i = 1, 2, \dots, n$  and a point  $A'_i$  is selected randomly with non-negative weight  $B_i$  of the line that is defined by the line segment  $A_0 A_i$  and the  $n$  convex polygon  $A'_1 A'_2 \dots A'_n$  is constructed such that:*

$$\left\| \sum_{j=1}^n B_j \vec{u}(A'_i, A'_j) \right\| > B_i, i \neq j.$$

*Then the generalized weighted Fermat-Torricelli point  $A'_0$  is identical with  $A_0$  (see Figure 3.1). This is the invariance property of the weighted Fermat-Torricelli point.*

**Proof.** The existence and uniqueness of the generalized weighted Fermat-Torricelli point given  $n$  non-collinear points  $A_1, \dots, A_n \in \mathbb{R}^d$  was studied in [4]. Furthermore, if for each point  $A_i \in A_1, \dots, A_n$

$$\left\| \sum_{j=1}^n B_j \vec{u}(A_i, A_j) \right\| > B_i, i \neq j$$

holds, then

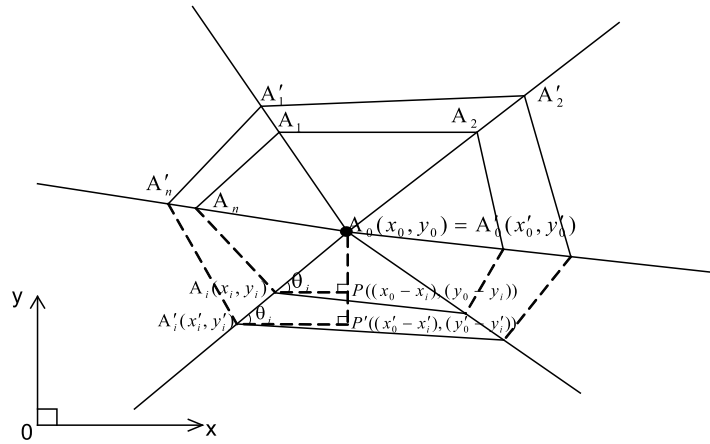


Figure 3.1

(a) the weighted minimum point  $A_0$  does not belong to  $A_i \in A_1, \dots, A_n$

(b) 
$$\sum_{i=1}^n B_i \vec{u}(A_0, A_i) = 0, i \neq j$$

(weighted floating case).

We consider the particular case for  $d=2$ , regarding the  $n$ -convex polygon  $A_1(x_1, y_1), \dots, A_n(x_n, y_n)$ . Let  $A_0(x_0, y_0)$  be the coordinates of the weighted Fermat Torricelli point (critical).

The minimum conditions are:

$$\frac{\partial f}{\partial x} = \sum_{i=1}^n B_i \frac{(x - x_i)}{\sqrt{(x - x_i)^2 + (y - y_i)^2}} = 0$$

$$\frac{\partial f}{\partial y} = \sum_{i=1}^n B_i \frac{(y - y_i)}{\sqrt{(x - x_i)^2 + (y - y_i)^2}} = 0.$$

If  $\theta_i$  is the angle between the line segment  $(x_i - x_0)$  with the distance  $A_0A_i$ , then the conditions that minimizes  $f(x,y)$  are:

$$\frac{\partial f}{\partial x} = \sum_{i=1}^n B_i \cos(\theta_i) = 0$$

$$\frac{\partial f}{\partial y} = \sum_{i=1}^n B_i \sin(\theta_i) = 0.$$

□

The invariance property of the generalized weighted Fermat-Torricelli point in  $\mathbb{R}^2$  was well known by V. Viviani ([2]).

#### 4. The inverse weighted Fermat-Torricelli problem

**Definition 4.1.** Given the generalized weighted Fermat-Torricelli point  $A_0$  of the weighted  $n$ -convex polygon  $A_1A_2 \dots A_n$  find the ratios between the non negative weights  $\frac{B_i}{B_j}$ ,  $i, j = 1, \dots, n$  such that:

$$\sum_{i=1}^n B_i = \text{constant.}$$

This is the inverse generalized weighted Fermat-Torricelli problem.

We proceed with the case for  $n = 4$  of the convex quadrilateral  $A_1A_2A_3A_4$  with non-negative weights  $B_i$ ,  $i = 1, 2, 3, 4$ . Let  $a_1, a_3, a_4$  be functions that depend on  $a_2$  and  $\alpha'_3$ .

$$a_1 = a_1(a_2, \alpha'_3), \quad a_3 = a_3(a_2, \alpha'_3), \quad a_4 = a_4(a_2, \alpha'_3). \quad (10)$$

By differentiating (1) with respect to the variables  $\alpha'_3$  and  $a_2$ , two equations are derived:

$$B_1 \frac{\partial a_1}{\partial \alpha'_3} + B_3 \frac{\partial a_3}{\partial \alpha'_3} + B_4 \frac{\partial a_4}{\partial \alpha'_3} = 0$$

$$B_1 \frac{\partial a_1}{\partial a_2} + B_2 + B_3 \frac{\partial a_3}{\partial a_2} + B_4 \frac{\partial a_4}{\partial a_2} = 0.$$

By calculating  $\frac{\partial a_1}{\partial \alpha'_3}$ ,  $\frac{\partial a_3}{\partial \alpha'_3}$ ,  $\frac{\partial a_4}{\partial \alpha'_3}$  and by applying the ‘‘cosine law’’ and the ‘‘sine law’’ to the corresponding triangles  $\nabla A_1A_2A_0$ ,  $\nabla A_3A_2A_0$ ,  $\nabla A_4A_2A_0$ , we have the equation:

$$-B_1 \sin(\alpha_{012}) + B_3 \sin(\alpha_{023}) + B_4 \sin(\alpha_{034} + \alpha_{023}) = 0. \quad (11)$$

Additionally, by differentiating with respect to the variable  $a_2$ , the equation takes the form:

$$B_1 \cos(\alpha_{012}) + B_2 + B_3 \cos(\alpha_{023}) + B_4 \cos(\alpha_{034} + \alpha_{023}) = 0. \quad (12)$$

Similarly, we differentiate the minimum function (1) with respect to the variables  $(\alpha''_3)$ ,  $(\alpha_3)$  (see Figure 2.1), in order to get correspondingly the equations:

$$-B_1 \sin(\alpha_{034} + \alpha_{041}) + B_2 \sin(\alpha_{023}) - B_4 \sin(\alpha_{034}) = 0 \quad (13)$$

$$-B_2 \sin(\alpha_{012}) + B_3 \sin(\alpha_{041} + \alpha_{034}) + B_4 \sin(\alpha_{041}) = 0 \quad (14)$$

and

$$\alpha_{012} + \alpha_{023} + \alpha_{034} + \alpha_{041} = 2\pi. \quad (15)$$

**Corollary 4.2.** Concerning the inverse 4-weighted Fermat-Torricelli problem if  $\alpha_{012} = \alpha_{034}$ ,  $\alpha_{023} = \alpha_{041}$  then  $B_1 = B_3, B_2 = B_4$ .

It follows from the fact that  $\sin(\alpha_{041} + \alpha_{034}) = 0$ ,  $\sin(\alpha_{034} + \alpha_{041}) = 0$  and  $\sin(\alpha_{012}) = \sin(\alpha_{034}) = \sin(\alpha_{023}) = \sin(\alpha_{041})$ . Equations (11), (14) imply that:

$$B_1 = B_3, \quad B_2 = B_4.$$

**Corollary 4.3.** Referring to the inverse weighted Fermat-Torricelli problem for the triangle  $n = 3$  ( $B_4 = 0$ ). From the equations (14), (11) and given the angles  $\alpha_{012}$ ,  $\alpha_{023}$ ,  $\alpha_{031}$  and the weight  $B_4 = 0$  the ratio of the three weights is:

$$B_1 : B_2 : B_3 = \sin(\alpha_{023}) : \sin(\alpha_{031}) : \sin(\alpha_{012}).$$

This result was also proved in [3] and [7].

We conclude with a fundamental result that deals with the *plasticity* of the inverse 4-weighted Fermat-Torricelli problem.

**Proposition 4.4.** Consider the inverse 4-weighted Fermat-Torricelli problem such that the angles  $\alpha_{0ij}$  are given  $i, j = 1, \dots, 4$ ,  $i \neq j$ . The following equations point out the plasticity of the system:

$$\left(\frac{B_2}{B_1}\right)_{1234} = \left(\frac{B_2}{B_1}\right)_{123} \left[1 - \left(\frac{B_4}{B_1}\right)_{1234} \left(\frac{B_1}{B_4}\right)_{134}\right] \tag{16}$$

$$\left(\frac{B_3}{B_1}\right)_{1234} = \left(\frac{B_3}{B_1}\right)_{123} \left[1 - \left(\frac{B_4}{B_1}\right)_{1234} \left(\frac{B_1}{B_4}\right)_{124}\right]. \tag{17}$$

The weight  $(B_i)_{1234}$  corresponds to the vertex  $A_i$  that lie in the line  $A_0A_i$ ,  $i = 1, 2, 3, 4$  and the weight  $(B_j)_{jkl}$  corresponds to the vertex  $A_j$  that lie in the  $A_0A_j$  regarding the triangle  $\nabla A_jA_kA_l$ ,  $j, k, l = 1, 2, 3, 4$ .

**Proof.** The equation (13) implies that:

$$\left(\frac{B_2}{B_1}\right)_{1234} = \frac{\sin(\alpha_{034} + \alpha_{041})}{\sin(\alpha_{023})} \left[ \left(\frac{B_4}{B_1}\right)_{1234} \frac{\sin(\alpha_{034})}{\sin(\alpha_{034} + \alpha_{041})} + 1 \right].$$

Referring to Corollary 4.3, from the triangle  $\nabla A_1A_2A_3$ :

$$\frac{\sin(\alpha_{034} + \alpha_{041})}{\sin(\alpha_{023})} = \frac{\sin(\alpha_{031})}{\sin(\alpha_{023})} = \left(\frac{B_2}{B_1}\right)_{123}.$$

Similarly, from the vague triangle  $\nabla A_1A_3A_4^*$  ( $A_4^*$  is the projection of  $A_4$  corresponding to the Fermat-Torricelli point  $A_0$ ):

$$-\left(\frac{B_1}{B_4}\right)_{134} = \frac{\sin(\alpha_{034})}{\sin(\alpha_{034} + \alpha_{041})}$$

and equation (16) is proved. To deduce the equation (17), (11) is used and the following ratio is calculated:

$$\left(\frac{B_3}{B_1}\right)_{1234} = \frac{\sin(\alpha_{012})}{\sin(\alpha_{023})} \left(1 - \frac{B_4 \sin(\alpha_{034} + \alpha_{023})}{B_1 \sin(\alpha_{012})}\right).$$

From the triangles  $\nabla A_1A_2A_3$ ,  $\nabla A_1A_2A_4$  and Corollary 4.3, two ratios are used:

$$\left(\frac{B_3}{B_1}\right)_{123} = \frac{\sin(\alpha_{012})}{\sin(\alpha_{023})}, \quad \left(\frac{B_1}{B_4}\right)_{124} = \frac{\sin(\alpha_{034} + \alpha_{023})}{\sin(\alpha_{012})}.$$

□

**Corollary 4.5.** Set  $\sum_{1234} B := (B_1)_{1234}(1 + \frac{B_2}{B_1} + \frac{B_3}{B_1} + \frac{B_4}{B_1})_{1234}$ . If  $\sum_{1234} B = \sum_{123} B = \sum_{124} B = \sum_{134} B$ , then

$$\begin{aligned} (B_i)_{1234} &= x_i(B_4)_{1234} + y_i, \quad i = 1, 2, 3 : \\ (x_1, y_1) &= \left( \frac{(\frac{B_1}{B_4})_{134}(\frac{B_2}{B_1})_{123} + (\frac{B_1}{B_4})_{124}(\frac{B_3}{B_1})_{123} - 1}{1 + (\frac{B_2}{B_1})_{123} + (\frac{B_3}{B_1})_{123}}, (B_1)_{123} \right) \\ (x_2, y_2) &= \left( x_1(\frac{B_2}{B_1})_{123} - (\frac{B_1}{B_4})_{134}(\frac{B_2}{B_1})_{123}, (B_2)_{123} \right) \\ (x_3, y_3) &= \left( x_1(\frac{B_3}{B_1})_{123} - (\frac{B_1}{B_4})_{124}(\frac{B_3}{B_1})_{123}, (B_3)_{123} \right). \end{aligned}$$

**Proposition 4.6.** Corollaries 4.2, 4.3, 4.5 and Proposition 4.4 applies also for the case of weighted convex quadrilaterals and triangles in the two-dimensional sphere and two-dimensional hyperboloid (Spherical and Hyperbolic Plasticity).

**Proof.** We agree on the same notations that are indicated in Figure 2.1. The equations (11), (12), (13), (15) remain the same by applying the “cosine law” and “sine law” of spherical (hyperbolic) triangles to the derived equations from (1) by differentiating with respect to the spherical (hyperbolic) angles  $\alpha_3, \alpha_{3'}, \alpha_{3''}$  and the geodesic segment  $a_2$ .  $\square$

**Example 4.7.** Given the angles  $\alpha_{012} = 120^\circ, \alpha_{023} = 90^\circ, \alpha_{034} = 50^\circ, \alpha_{041} = 100^\circ$ , the weight  $(B_1)_{123} = 1$  and the assumption that  $\sum_{1234} B = \sum_{123} B = \sum_{124} B = \sum_{134} B$  from the Proposition 4.4 and Corollary 4.5 the following results are derived:

$$\begin{aligned} \nabla_{123}(A_1 A_2 A_3) : (B_1)_{123} &= 1, (B_2)_{123} = 0.50, (B_3)_{123} = 0.866 \\ \sum_{123} B &= 2.366 \\ \nabla_{124}(A_1 A_2 A_4) : (B_1)_{124} &= 0.606, (B_2)_{124} = 0.942, (B_4)_{124} = 0.818 \\ \sum_{124} B &= 2.366 \\ \nabla_{134}(A_1 A_3 A_4) : (B_1)_{134} &= 1.432, (B_3)_{134} = 1.869, (B_4)_{134} = -0.935 \\ \sum_{134} B &= 2.366 \\ (B_1)_{1234} - (B_1)_{123} &= -0.475(B_4)_{1234} & (18) \\ (B_2)_{1234} - (B_2)_{123} &= 0.53(B_4)_{1234} & (19) \\ (B_3)_{1234} - (B_3)_{123} &= -1.054(B_4)_{1234} & (20) \end{aligned}$$

and  $\sum_{1234} B = 2.366$ . The range of  $(B_4)_{1234}, (B_1)_{1234}, (B_2)_{1234}, (B_3)_{1234}$  is:

$$\begin{aligned} 0 &\leq (B_4)_{1234} \leq 0.821 \\ 1 &\geq (B_1)_{1234} \geq 0.61 \\ 0.5 &\leq (B_2)_{1234} \leq 0.935 \\ 0.866 &\geq (B_3)_{1234} \geq 0. \end{aligned}$$



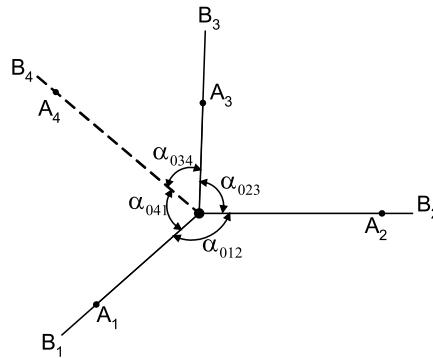


Figure 4.1

**Remark 4.8.** By taking into consideration in Figure 4.1 the branch with weight  $B_4$  that lies inside the angle  $\alpha_{031}$  and referring to the Example 4.7, the weights of the two branches with weights  $B_1, B_3$  decrease and the weight of the opposite branch  $B_2$  increases (see equations (18), (19), (20)).

**Remark 4.9.** For values of  $B_1, B_2, B_3$  which depend on  $B_4$  according to Corollary 4.5 and for any value of the vertex  $A_i$  which lies in the line  $A_0A_i$  such that the inequalities of the weighted floating case are satisfied (see [4]), the weighted Fermat-Torricelli point  $A_0$  remains invariant.

**Example 4.10.** Let  $A_1A_2A_3A_4$  be the given convex quadrilateral with  $a_1 = 5, a_2 = 7.5, a_3 = 5, a_4 = 10, \alpha_{012} = 120^\circ, \alpha_{023} = 90^\circ, \alpha_{034} = 50^\circ, \alpha_{041} = 100^\circ$  and weights  $B_1 = 0.762, B_2 = 0.765, B_3 = 0.339, B_4 = 0.5$  taken from Example 4.7. The point  $A_0$  is the weighted Fermat-Torricelli point (see Figure 4.2). The convex quadrilateral  $A_1A_2A_3A_4$  of Figure 4.3 has the same angles  $a_{0ij}$  and lengths  $a_i, i, j = 1, 2, 3, 4, i \neq j$  like in Figure 4.3 with weights  $B_1 = 0.81, B_2 = 0.712, B_3 = 0.444, B_4 = 0.4$  taken from Example 4.7. From Figure 4.2 and Figure 4.3 the weighted Fermat-Torricelli point  $A_0$  remains invariant. Let  $A_1A_2A'_3A_4$  be the convex quadrilateral in Figure 4.4 and  $A'_3$  is the vertex that exists at the line that connects the point  $A_0$  of  $A_1A_2A'_3A_4$  with  $A_3$  like in Figure 4.3 such that  $a'_3 = 7$  with the angles  $a_{0ij}$  with the other lengths and the weights  $B_i, i = 1, 2, 3, 4$ , to be the same as in Figure 4.3. The weighted Fermat-Torricelli point  $A_0$  of Figure 4.3 and Figure 4.4 remains also invariant.

**Remark 4.11.** Taking into consideration equations from physics, we can bound the solutions regarding the dimensions of the quadrilateral.

From statics, concerning  $n$  bars  $A_0A_1, A_0A_2, \dots, A_0A_n$ , with constant density and lengths  $a_1, a_2, \dots, a_n$  respectively that connect at the Fermat-Torricelli point  $A_0$ , the sum of the projection of the moments on the x-axis and the sum of the projection on the y-axis are:

$$\sum_{i=1}^n (M_i)_x = 0, \quad \sum_{i=1}^n (M_i)_y = 0. \tag{21}$$

**Definition 4.12.** The moment due to the gravity of the bar  $A_0A_i$  with length  $a_i$  referring to the point  $A_0$  is:

$$\vec{M}_i = ca_i^q \vec{u}_i, \quad q \in \mathbf{Q} : q \geq 2.$$

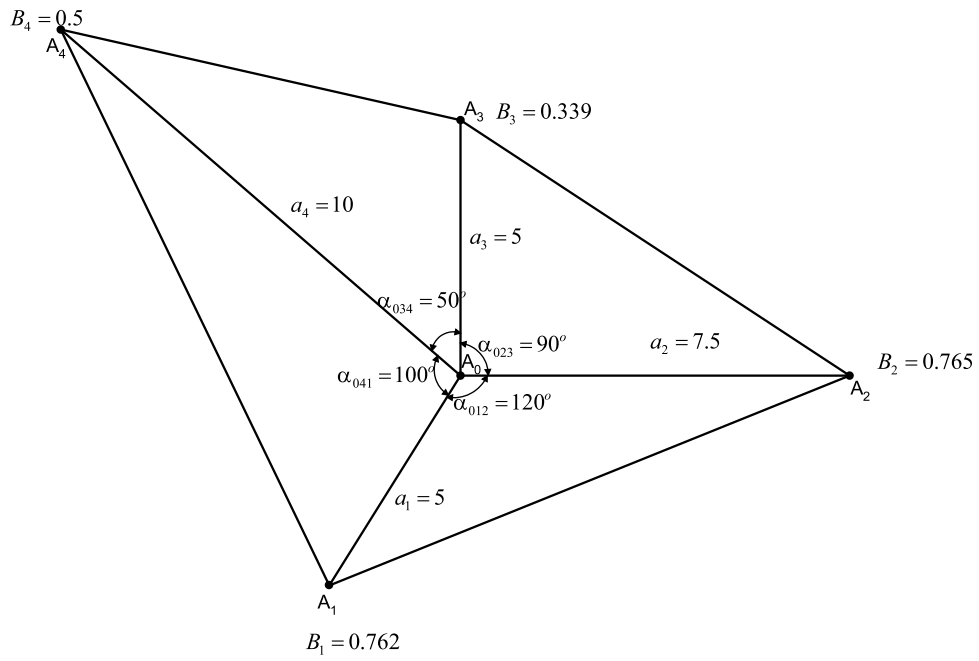


Figure 4.2

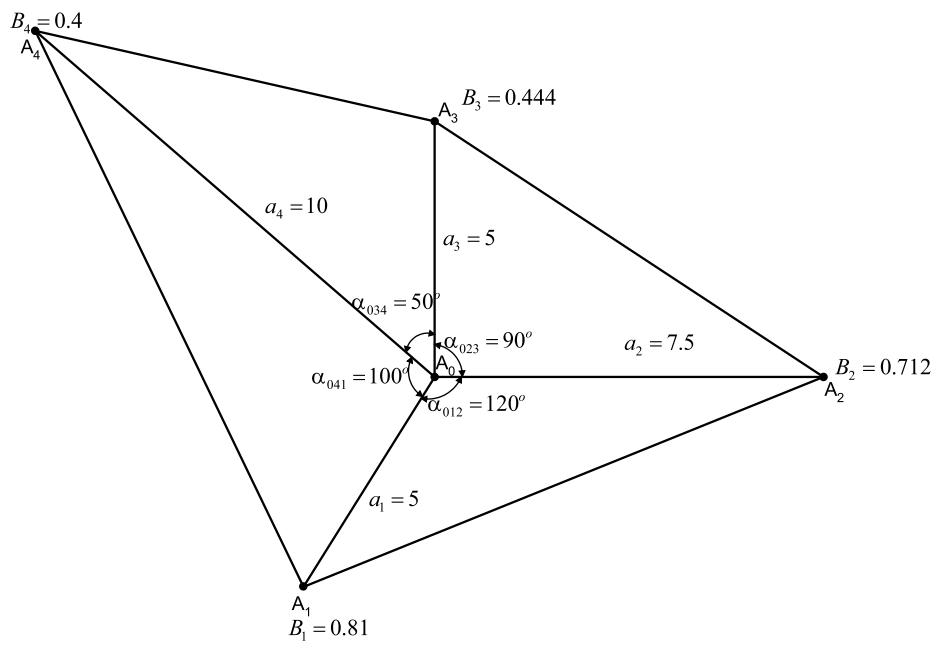


Figure 4.3

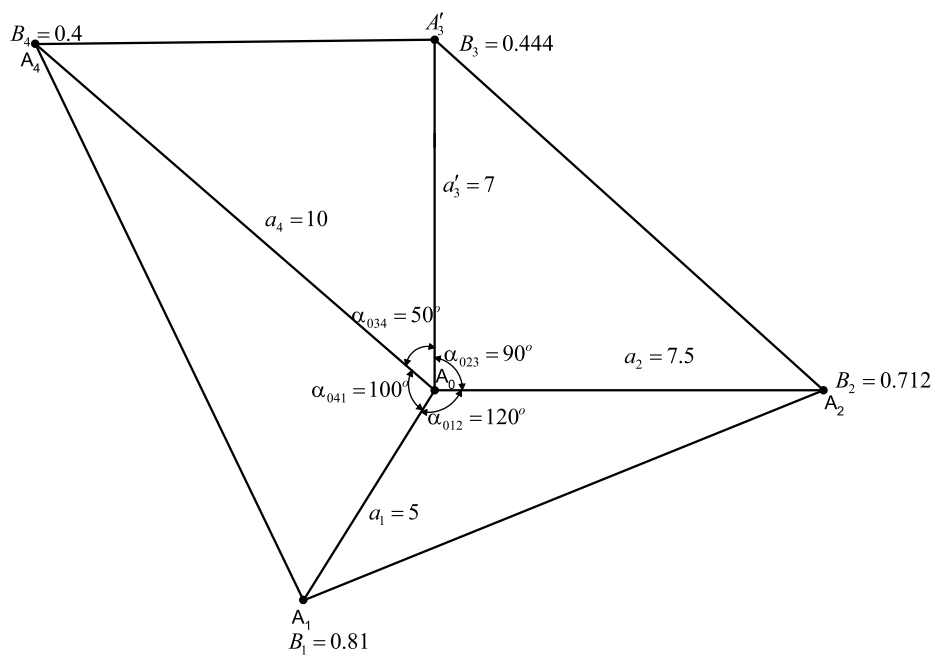


Figure 4.4

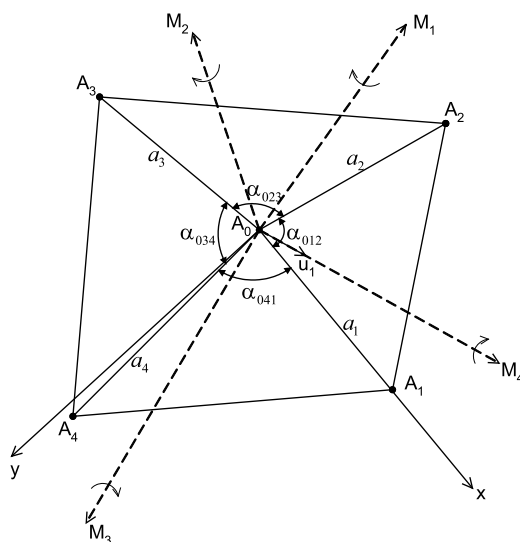


Figure 4.5

such that  $c$  is a constant and  $u_i$  is the unit vector of  $\vec{M}_i$ ,  $q$  depends on the cross-section of the bar.

For simplicity we deal with  $q = 2$  or  $q = 3$ . Suppose that for the case  $n = 4$ , we consider the projection on the x-axis ( $A_0A_2$ ) of the moments and on the y-axis which is orthogonal to the x-axis (see Figure 4.5). From the conditions (21), two equations are deduced:

$$\begin{aligned} -a_1^2 \sin(\alpha_{012}) + a_2^2 \sin(\alpha_{023}) + a_4^2 \sin(\alpha_{034} + \alpha_{023}) &= 0 \\ a_1^2 \cos(\alpha_{012}) + a_2^2 + a_3^2 \cos(\alpha_{023}) + a_4^2 \cos(\alpha_{034} + \alpha_{023}) &= 0. \end{aligned}$$

Similarly, by taking as x-axis  $A_0A_3$ ,  $A_0A_1$  the following equations are derived:

$$\begin{aligned} -a_1^2 \sin(\alpha_{034} + \alpha_{041}) + a_2^2 \sin(\alpha_{023}) - a_4^2 \sin(\alpha_{034}) &= 0 \\ -a_2^2 \sin(\alpha_{012}) + a_3^2 \sin(\alpha_{041} + \alpha_{034}) + a_4^2 \sin(\alpha_{041}) &= 0. \end{aligned}$$

The form of the derived equations from the projection of moments are similar to the equations (11), (12), (13), (14) by expressing the weights  $B_i \sim a_i^2$ ,  $i = 1, 2, 3, 4$ . The maximum area of the convex quadrilateral  $A_1A_2A_3A_4$  can be calculated:

$$\text{Area}_1 = \frac{\alpha_1 \alpha_2 \sin(\alpha_{012}) + \alpha_2 \alpha_3 \sin(\alpha_{023}) + \alpha_3 \alpha_4 \sin(\alpha_{034}) + \alpha_4 \alpha_1 \sin(\alpha_{041})}{2}. \quad (22)$$

The area of the quadrilateral ( $A_1A_2A_3A_4$ ) is a composition of rational functions of the variable  $a_4$ , because the following equations are valid:

$$a_i^2 = x_i a_4^2 + y_i, \quad i = 1, 2, 3 \quad (23)$$

such that:

$$x_1 + x_2 + x_3 = 0.$$

The area of the convex quadrilateral  $A_1A_2A_3A_4$  as a composition of rational functions of  $a_4$  is a continuous function and has a maximum value for the interval  $0 \leq a_4 \leq \sqrt{\frac{(B_1)_{123}}{x_1}}$  or  $0 \leq a_4 \leq \sqrt{\frac{(B_3)_{123}}{x_3}}$ .

**Remark 4.13.** Given the  $A_0$  weighted Fermat-Torricelli point, the angles  $\alpha_{012}$ ,  $\alpha_{023}$ ,  $\alpha_{034}$ ,  $\alpha_{041}$  of  $A_0$  and the weights  $B_i \sim a_i^q$ , three different constraints are used in the following Examples 4.14, 4.15, 4.16 to calculate the distances  $a_1, a_2, a_3, a_4$  of the  $A_0$  weighted Fermat-Torricelli point, in order to maximize the area of the quadrilateral  $A_1A_2A_3A_4$ :

- (i)  $\sum_{i=1}^4 a_i^q = c_1$  (Example 4.14,  $q = 2$ ,  $c_1 = 2.366$ )
- (ii)  $a_1 = c_2$  (Example 4.15,  $q = 3$ ,  $c_2 = 1$ )
- (iii) The perimeter of  $A_1A_2A_3A_4$  is constant:  
Perimeter =  $a_{12} + a_{23} + a_{34} + a_{41} = c_s$  (Example 4.16,  $q = 3$ ,  $c_s = 3$ ).

**Example 4.14.** Let  $A_1A_2A_3A_4$  be the convex quadrilateral with weights  $B_i \sim a_i^2$  for  $i = 1, 2, 3, 4$ . Given  $\alpha_{012} = 120^\circ$ ,  $\alpha_{023} = 90^\circ$ ,  $\alpha_{034} = 50^\circ$ ,  $\alpha_{041} = 100^\circ$ ,  $A_0$  is the weighted Fermat-Torricelli point and the constraint:

$$\sum_{i=1}^4 a_i^2 = 2.366.$$

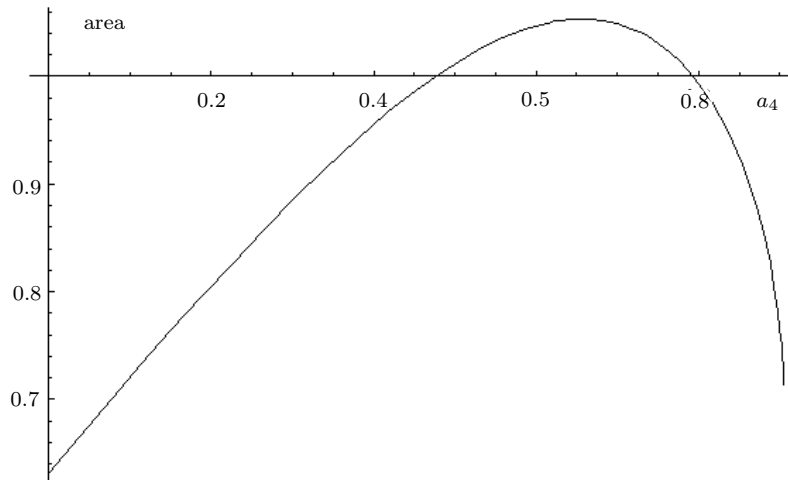


Figure 4.6

To achieve the maximum area of  $A_1A_2A_3A_4$  the variables  $a_1, a_2, a_3$  are expressed as functions of  $a_4$ : taking into account the equations (21) of the moments from the remark 4.11 and the Example 4.7, equations (23) take the form:

$$\begin{aligned} a_1^2 &= 1 - 0.475a_4^2 \\ a_2^2 &= 0.50 + 0.53a_4^2 \\ a_3^2 &= 0.866 - 1.054a_4^2. \end{aligned}$$

The maximum area of the quadrilateral is obtained when  $a_4 = 0.6563, a_1 = 0.8918, a_2 = 0.8534, a_3 = 0.6417$  (see Figure 4.6).

**Example 4.15.** Consider the quadrilateral  $A_1A_2A_3A_4$  with the same given angles  $\alpha_{012}, \alpha_{023}, \alpha_{034}, \alpha_{041}$  as in Example 4.14 with weights  $B_i \sim a_i^3$  that correspond to each vertex  $A_i, i = 1, 2, 3, 4, A_0$  is the weighted Fermat-Torricelli point and the constraint  $a_1 = 1$ . We use the two equations with a “sine form” (projection on the x-axis) of the moments for  $a_2, a_3$  and  $q = 3$ :

$$a_2 = ((1/\sin(\alpha_{023}))(a_1^3 \sin(\alpha_{034} + \alpha_{041}) + (a_4^3) \sin(\alpha_{034})))^{1/3} \tag{24}$$

$$a_3 = ((1/\sin(\alpha_{023}))(a_1^3 \sin(\alpha_{012}) - (a_4^3) \sin(\alpha_{034} + \alpha_{023})))^{1/3}. \tag{25}$$

The maximum area of the quadrilateral is achieved as a function of  $a_4$  by replacing the variables  $a_2, a_3$  from (24), (25) to the equation (22). The area of the quadrilateral is maximized for the values:  $a_4 = 0.982273, a_1 = 1, a_2 = 1.07029, a_3 = 0.635637$  (see Figure 4.7)

**Example 4.16.** Consider the same quadrilateral  $A_1A_2A_3A_4$  as in Example 4.15, the angles  $\alpha_{012}, \alpha_{023}, \alpha_{034}, \alpha_{041}$ , the weights  $B_i \sim a_i^3$ , the weighted Fermat-Torricelli point  $A_0$  and the following constraint for the perimeter of  $A_1A_2A_3A_4$ :

$$\text{Perimeter} = a_{12} + a_{23} + a_{34} + a_{41} = \text{constant}.$$

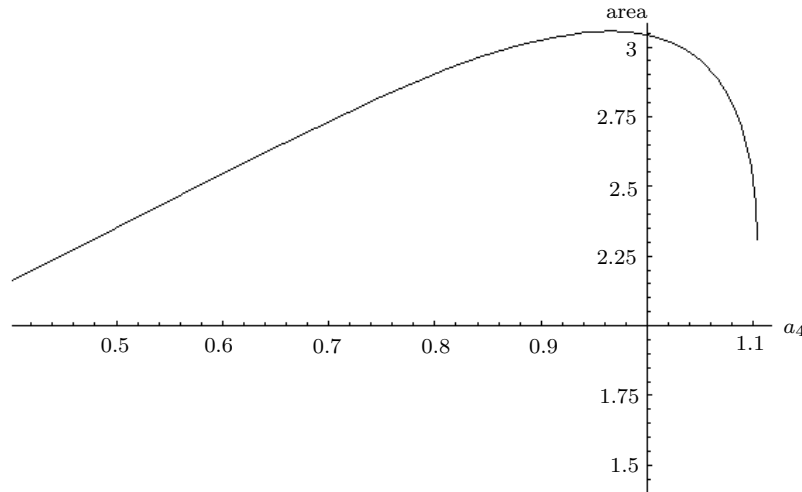


Figure 4.7

This means that the quadrilateral  $A_1A_2A_3A_4$  is inscribed to a circle. We will calculate the values  $a_1, a_2, a_3, a_4$  that maximize the area of  $A_1A_2A_3A_4$ . The constraint can be written as a function of  $a_1, a_2, a_3, a_4$ .

$$2S = \sum_{i=1}^4 \sqrt{a_i^2 + a_{i+1}^2 - 2a_i a_{i+1} \cos \alpha_{0ii+1}} = C_s, \quad i = 1, 2, 3, 4. \tag{26}$$

For  $i = 4$  set  $i + 1 = 1$  and  $S$  is the semi perimeter of the convex quadrilateral  $A_1A_2A_3A_4$ . The area of the inscribed quadrilateral in a circle is given by the formula:

$$\text{Area}_2 = \sqrt{(S - a_{12})(S - a_{23})(S - a_{34})(S - a_{41})}. \tag{27}$$

A system of two equations can be derived as functions of  $a_1$  and  $a_4$ :

$$\text{Area}_1 = \text{Area}_2 \tag{28}$$

and the equation (26). The variables  $a_2$  and  $a_3$  are functions of  $a_1$  and  $a_4$  and they can be taken from (24), (25) respectively. The formula of  $\text{Area}_1$  is given by (22). Let the constant of (26) be  $c_s = 3$ . The system of the two equations (28), (26) can be solved numerically by Newton’s method. The values  $a_1 = 0.595346, a_4 = 0.482094, a_2 = 0.576236, a_3 = 0.480186$  maximize the area of the quadrilateral  $A_1A_2A_3A_4$  (see Figure 4.8 for  $c_s = 3, 4, 6$ ).

**Remark 4.17.** Let  $A_1A_2A_3A_4$  be the convex quadrilateral with weights  $B_i \sim a_i^q$  for  $i = 1, 2, 3, 4$  and angles  $\alpha_{012} = 120^\circ, \alpha_{023} = 120^\circ, \alpha_{034} = 60^\circ, \alpha_{041} = 60^\circ$ . There is a connection between the weighted Fermat-Torricelli point  $A_0$  for the given convex quadrilateral  $A_1A_2A_3A_4$  and the *fundamental equation of Fermat*. Similar equations with (11), (14) are deduced:

$$-a_1^q \sin(\alpha_{012}) + a_3^q \sin(\alpha_{023}) + a_4^q \sin(\alpha_{034} + \alpha_{023}) = 0 \tag{29}$$

$$-a_2^q \sin(\alpha_{012}) + a_3^q \sin(\alpha_{041} + \alpha_{034}) + a_4^q \sin(\alpha_{041}) = 0. \tag{30}$$

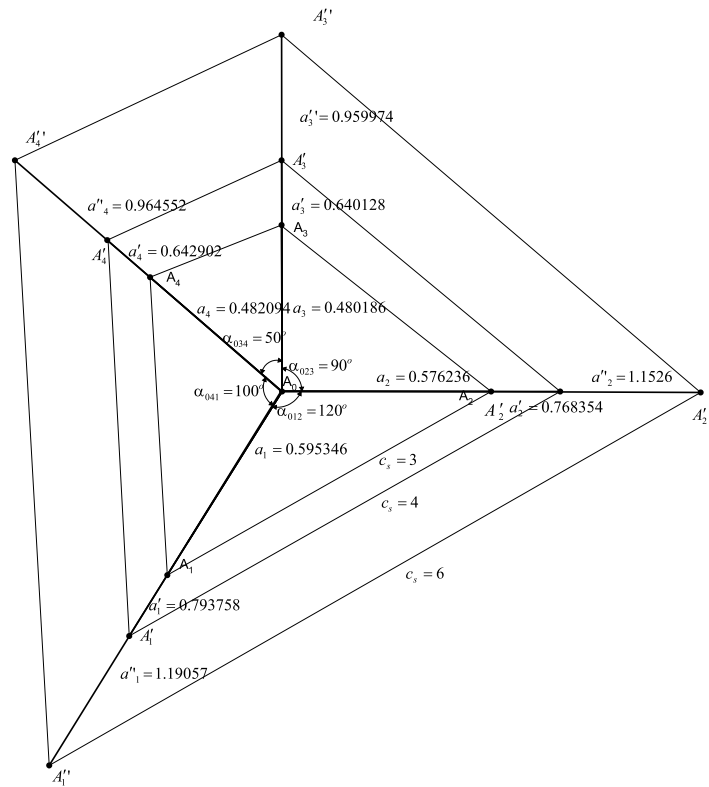


Figure 4.8

From equation (29):

$$a_1^q = a_3^q. \tag{31}$$

Equation (30) gives the equation of Fermat:

$$a_2^q = a_3^q + a_4^q \tag{32}$$

for  $q \in \mathbb{N}$ .

**Conclusion 4.18.** The starting point of the evolution of weighted convex quadrilateral at time  $t = 0$  is the weighted Fermat-Torricelli point  $A_0$ . This is the main reason that we have followed a computational approach which does not depend on the coordinates of the vertices  $A_i(x_i, y_i)$  but on the geodesic segments  $a_i$   $i = 1, 2, 3, 4$ . The result of plasticity holds in  $\mathbb{R}^2, S^2$  and  $H^2$ . An open question is to derive plasticity conditions for an n-convex polygon in  $\mathbb{R}^2, S^2$  and  $H^2$  and solve the generalized inverse weighted Fermat-Torricelli problem for  $n > 4$ . Finally, we would like to note that taking into consideration the connection of the Fermat-Torricelli point with the fundamental equation of P. de Fermat, there cannot exist a simultaneously integer evolution concerning  $a_1, a_2, a_3, a_4$  from  $A_0$ , because of the invariance of the weighted Fermat-Torricelli point.

**A. Explanation of the moments**  $M = C \int_0^{a_i} r^2 x dx = r = r_0(1 - (x/a_i)^n)$

Suppose that  $r_0 \sim C_1 a_i^q$  then:

$$M = C a_i^{2+q'} = C a_i^q,$$

$C$  and  $C_1$  are constant and  $q', q \in \mathbb{Q}$ . If  $q' = 0$  then  $q = 2$  (cylinder). If  $q' = 1$  then  $q = 3$  (cone).

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