

Quasiconvexity and Uniqueness of Stationary Points on a Space of Measure Preserving Maps

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Let $\Omega \subset \mathbb{R}^n$ be a bounded starshaped domain and consider the energy functional

$$\mathbb{F}[u; \Omega] := \int_{\Omega} \mathbf{F}(\nabla u(x)) \, dx,$$

over the space of measure preserving maps

$$\mathcal{A}_p(\Omega) = \left\{ u \in \bar{\xi}x + W_0^{1,p}(\Omega, \mathbb{R}^n) : \det \nabla u = 1 \text{ a.e. in } \Omega \right\},$$

with $p \in [1, \infty[$, $\bar{\xi} \in \mathbb{M}_{n \times n}$ and $\det \bar{\xi} = 1$. In this short note we address the question of *uniqueness* for solutions of the corresponding system of Euler-Lagrange equations. In particular we give a new proof of the celebrated result of Knops & Stuart [3] using a method based on *comparison* with homogeneous degree-one extensions as introduced by the second author in [6].

1. Introduction

Let $\Omega \subset \mathbb{R}^n$ be a bounded *starshaped* domain. In this short note we consider the energy functional

$$\mathbb{F}[u; \Omega] := \int_{\Omega} \mathbf{F}(\nabla u(x)) \, dx, \tag{1}$$

over the space of *admissible* maps

$$\mathcal{A}_p(\Omega) := \left\{ u \in W_v^{1,p}(\Omega, \mathbb{R}^n) : \det \nabla u = 1 \text{ a.e. in } \Omega \right\}, \tag{2}$$

with $p \in [1, \infty[$, where

$$W_v^{1,p}(\Omega, \mathbb{R}^n) = \left\{ u \in W^{1,p}(\Omega, \mathbb{R}^n) : u|_{\partial\Omega} = v|_{\partial\Omega} \right\},$$

while $v = \bar{\xi}x$ and $\bar{\xi} \in \mathbb{M}_{n \times n}$ with $\det \bar{\xi} = 1$. Here the integrand $\mathbf{F} : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$ is of class C^1 and for future reference we associate with it the following set of hypotheses.

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(H1) (*Growth condition*) There exists $c_1 > 0$ such that for all $\xi \in \mathbb{R}^{n \times n}$ we have that

$$|\mathbf{F}(\xi)| \leq c_1(1 + |\xi|^p).$$

(H2) (*Coercivity condition*) There exists $c_2 > 0$ such that for all $\xi \in \mathbb{R}^{n \times n}$ we have that

$$c_2|\xi|^p - c_1 \leq \mathbf{F}(\xi).$$

(H3) $_{\xi}$ (*Quasiconvexity at ξ*) For fixed $\xi \in \mathbb{M}_{n \times n}$ and all $\varphi \in C_c^\infty(\Omega, \mathbb{R}^n)$ we have that

$$\int_{\Omega} (\mathbf{F}(\xi + \nabla\varphi(x)) - \mathbf{F}(\xi)) \, dx \geq 0.$$

If, additionally, the inequality is *strict* for $\varphi \neq 0$ then \mathbf{F} is referred to as being *strictly* quasiconvex at ξ .

(H4) $_{\xi}$ (*Rank-one convexity at ξ*) For fixed $\xi \in \mathbb{M}_{n \times n}$ and all *rank-one* $\zeta \in \mathbb{M}_{n \times n}$ the function

$$\mathbb{R} \ni t \mapsto \mathbf{F}(\xi + t\zeta) \in \mathbb{R}$$

is *convex* at $t = 0$.¹

Here we are primarily concerned with the question of *uniqueness* for solutions to the system of Euler-Lagrange equations associated with the energy functional (1) over the space (2) as well as that for its *strong* local minimizers.² Indeed, the *former*, under the stated C^1 regularity assumption on \mathbf{F} are known to take the form

$$\begin{cases} \operatorname{div} \mathfrak{S}[x, \nabla u(x)] = 0 & x \in \Omega, \\ \det \nabla u(x) = 1 & x \in \Omega, \\ u(x) = v(x) & x \in \partial\Omega, \end{cases}$$

where, we have set

$$\begin{aligned} \mathfrak{S}[x, \xi] &= \mathbf{F}_{\xi}(\xi) - \mathfrak{p}(x)\xi^{-t} \\ &=: \mathfrak{T}[x, \xi]\xi^{-t}, \end{aligned} \tag{3}$$

for $x \in \Omega$, $\xi \in \mathbb{R}^{n \times n}$ satisfying $\det \xi = 1$ and \mathfrak{p} a suitable Lagrange multiplier while

$$\mathfrak{T}[x, \xi] = \mathbf{F}_{\xi}(\xi)\xi^t - \mathfrak{p}(x)\mathbf{I}_n. \tag{4}$$

A motivating source for this type of problem is nonlinear elasticity where (1) and (2) represent a simple *model* of a homogeneous *incompressible* hyperelastic material and solutions to the above system of equations serve as the corresponding *equilibrium* states (cf., e.g., Ball [1]).³

¹For a comprehensive treatment of the *convexity* notions (H3), (H4) and their significance in the *calculus of variations* we refer the interested reader to [2].

²A map $u \in \mathcal{A}_p(\Omega)$ is a *strong* local minimizer of \mathbb{F} if and only if there exists $\rho = \rho(u) > 0$ such that $\mathbb{F}[u; \Omega] \leq \mathbb{F}[w; \Omega]$ for all $w \in \mathcal{A}_p(\Omega)$ satisfying $\|u - w\|_{W^{1,p}} \leq \rho$.

³In the language of elasticity, the *tensor* fields (3) and (4) are referred to as the *Piola-Kirchhoff* and the *Cauchy* stress tensors respectively and the *Lagrange* multiplier \mathfrak{p} is better known as the *hydrostatic* pressure.

The question of uniqueness of solutions to the above system of Euler-Lagrange equations [subject to *linear* boundary conditions] was established in a seminal paper of Knops & Stuart (see [3]). There it is shown that subject to \mathbf{F} being of class C^2 , *rank-one* convex everywhere and *strictly* quasiconvex at $\bar{\xi}$ any smooth solution u in a *starshaped* domain satisfying $\det \nabla u = 1$ in Ω and $u = \bar{\xi}x$ on $\partial\Omega$ satisfies $u = \bar{\xi}x$ on $\bar{\Omega}$.

Without *further* restriction on the domain Ω uniqueness in general may *fail*. Indeed one can construct domains Ω for which *any* energy functional \mathbb{F} whose integrand \mathbf{F} satisfies (H1)–(H3) admits multiple [*infinitely* many for $n = 2$] *strong* local minimizers as well as multiple [*infinitely* many for n *even*] smooth solutions to the corresponding system of Euler-Lagrange equations. (See [7], [8] and [4], [5].)⁴

In this short note we give a *new* proof of the *mentioned* uniqueness result of Knops & Stuart [3]. This is based on *firstly* removing the measure preserving condition $\det \nabla u = 1$ and considering instead a suitable *unconstrained* functional [with the aid of the Lagrange multiplier \mathbf{p}] and *secondly* utilising the so-called *stationarity* condition followed by comparison with *homogeneous* degree-one extensions as introduced in [6]. This approach has the advantage of *extending* the uniqueness result to all *weak* solutions u of class C^1 satisfying the *weak* form of the stationarity condition (see (8) below).

Finally we prove a new uniqueness result for *strong* local minimizers of \mathbb{F} over $\mathcal{A}_p(\Omega)$ to the effect that subject to (H1), (H3) $_{\bar{\xi}}$ alone *any* such $u \in \mathcal{A}_p(\Omega)$ satisfies $\mathbb{F}[u; \Omega] = \mathbb{F}[\bar{\xi}x; \Omega]$ and therefore subject to the additional *strictly* quasiconvexity of \mathbf{F} at $\bar{\xi}$ it must be that $u = \bar{\xi}x$ on $\bar{\Omega}$!

2. The main result

Let $\Omega \subset \mathbb{R}^n$ be a C^1 bounded *starshaped* domain (with respect to the origin). Without loss of generality we assume in the sequel that there exists a *strictly* positive function $d : \mathbb{S}^{n-1} \rightarrow \mathbb{R}$ such that

$$\partial\Omega = \left\{ \omega \neq 0 : |\omega| = d \left(\frac{\omega}{|\omega|} \right) \right\}.$$

It is then clear that $\Omega = \{0\} \cup \{x \neq 0 : |x| < d(x/|x|)\}$. Moreover the *unit* outward normal to the boundary at a point $\omega \in \partial\Omega$ is given by

$$\nu = \frac{1}{\alpha(\theta)} \left[\theta - (\mathbf{I}_n - \theta \otimes \theta) \frac{\nabla d(\theta)}{d(\theta)} \right]$$

where $\alpha(\theta) = d^{-1}(\theta) \sqrt{d^2(\theta) + |\nabla d(\theta)|^2 - \langle \theta, \nabla d(\theta) \rangle^2}$ and $\theta = \omega/|\omega|$.

Definition 2.1 (Classical solution). A pair (u, \mathbf{p}) is said to be a *classical* solution to the Euler-Lagrange equations associated with \mathbb{F} over $\mathcal{A}_p(\Omega)$ if and only if the following hold.

(1) $u \in C^2(\Omega, \mathbb{R}^n) \cap C^1(\bar{\Omega}, \mathbb{R}^n),$

⁴For technical reasons one needs to restrict to $p \in [n, \infty[$ for the multiplicity result relating to *strong* local minimizers and to $p \in]1, \infty[$ for the one relating to smooth solutions.

- (2) $\mathbf{p} \in C^1(\Omega) \cap C^0(\bar{\Omega})$,
(3) (u, \mathbf{p}) satisfy the *system* of equations⁵

$$\begin{cases} \operatorname{div} \{ \mathbf{F}_\xi(\nabla u) - \mathbf{p}[\operatorname{cof} \nabla u] \} = 0 & \text{in } \Omega, \\ \det \nabla u = 1 & \text{in } \Omega, \\ u = v & \text{on } \partial\Omega. \end{cases}$$

Now suppose that (u, \mathbf{p}) is a classical solution as described in Definition 2.1. We set

$$\mathbf{G}(x, z, \xi) = \mathbf{G}(x, z, \xi; \mathbf{p}) := \mathbf{F}(\xi) - \mathbf{p}(x)(\det \xi - 1), \quad (5)$$

for all $x \in \Omega$, $z \in \mathbb{R}^n$ and $\xi \in \mathbb{M}_{n \times n}$. Next with the aid of \mathbf{G} we introduce the *Hamilton* [or the *energy-momentum*] tensor

$$\mathbf{T}_\alpha^\beta(x, z, \xi) := \xi_\alpha^i \mathbf{G}_{\xi_\beta^i}(x, z, \xi) - \delta_\alpha^\beta \mathbf{G}(x, z, \xi). \quad (6)$$

Theorem 2.2. *Let (u, \mathbf{p}) be a classical solution to the Euler-Lagrange equations associated with \mathbb{F} over $\mathcal{A}_p(\Omega)$. Let \mathbf{F} be of class C^2 . Then with \mathbf{G} and \mathbf{T} as in (5) and (6) we have that*

$$\operatorname{div} \{ \mathbf{T}(x, u, \nabla u) \} + \mathbf{G}_x(x, u, \nabla u) = 0 \quad (7)$$

in Ω .⁶

Proof. (By direct *verification*) Indeed expanding the above identity *componentwise* we have that

$$\begin{aligned} \mathbf{L}_\alpha &:= [\operatorname{div} \{ \mathbf{T}(x, u, \nabla u) \} + \mathbf{G}_x(x, u, \nabla u)]_\alpha \\ &= \frac{\partial \mathbf{T}_\alpha^\beta}{\partial x_\beta}(x, u, \nabla u) + \mathbf{G}_{x_\alpha}(x, u, \nabla u) \\ &= \frac{\partial}{\partial x_\beta} \left\{ u_{,\alpha}^i \left(\mathbf{F}_{\xi_\beta^i} - \mathbf{p}(x)[\operatorname{cof} \nabla u]_{i\beta} \right) \right\} \\ &\quad - \frac{\partial}{\partial x_\alpha} \{ \mathbf{F} - \mathbf{p}(x)[\det \nabla u - 1] \} - \frac{\partial \mathbf{p}}{\partial x_\alpha}(x)[\det \nabla u - 1]. \end{aligned}$$

Therefore taking advantage of $\det \nabla u = 1$ and by direct *differentiation* we can write

$$\begin{aligned} \mathbf{L}_\alpha &= u_{,\alpha\beta}^i \left(\mathbf{F}_{\xi_\beta^i} - \mathbf{p}(x)[\operatorname{cof} \nabla u]_{i\beta} \right) \\ &\quad + u_{,\alpha}^i \frac{\partial}{\partial x_\beta} \left(\mathbf{F}_{\xi_\beta^i} - \mathbf{p}(x)[\operatorname{cof} \nabla u]_{i\beta} \right) - \mathbf{F}_{\xi_\beta^i} u_{,\alpha\beta}^i \\ &= -\mathbf{p}(x) \frac{\partial}{\partial x_\alpha} \det \nabla u + u_{,\alpha}^i \frac{\partial}{\partial x_\beta} \left(\mathbf{F}_{\xi_\beta^i} - \mathbf{p}(x)[\operatorname{cof} \nabla u]_{i\beta} \right) \\ &= u_{,\alpha}^i \frac{\partial}{\partial x_\beta} \left(\mathbf{F}_{\xi_\beta^i} - \mathbf{p}(x)[\operatorname{cof} \nabla u]_{i\beta} \right) = 0, \end{aligned}$$

which is the required conclusion. \square

⁵Although we are primarily concerned with the case $v = \bar{\xi}x$, for reasons that will become clear later, we allow $v \in C^1(\bar{\Omega}, \mathbb{R}^n)$ to be arbitrary.

⁶This is the so-called *stationarity* condition in its *strong* form as opposed to its *weak* form given by (8) below.

For the sake of future reference we next introduce the *unconstrained* energy functional

$$\begin{aligned} \mathbb{G}[u, \mathbf{p}; \Omega] &:= \int_{\Omega} \mathbf{G}(x, u, \nabla u) \, dx \\ &= \int_{\Omega} (\mathbf{F}(\nabla u) - \mathbf{p}(x)[\det \nabla u - 1]) \, dx. \end{aligned}$$

Then setting $u_{\varepsilon}(x) := u(x + \varepsilon\varphi)$ with $\varphi \in C_c^{\infty}(\Omega, \mathbb{R}^n)$ an application of Theorem 2.2 and the *divergence* theorem along with a straight-forward calculation gives

$$\begin{aligned} \left. \frac{d}{d\varepsilon} \mathbb{G}[u_{\varepsilon}, \mathbf{p}; \Omega] \right|_{\varepsilon=0} &= \int_{\Omega} (\mathbf{T}_{\alpha}^{\beta} \varphi_{,\beta}^{\alpha} - \mathbf{G}_{x_{\alpha}} \varphi^{\alpha}) \, dx \\ &= \int_{\Omega} (u_{,\alpha}^i \mathbf{G}_{\xi_{\beta}^i} \varphi_{,\beta}^{\alpha} - \delta_{\alpha}^{\beta} \mathbf{G} \varphi_{,\beta}^{\alpha} - \mathbf{G}_{x_{\alpha}} \varphi^{\alpha}) \, dx = 0. \end{aligned} \tag{8}$$

Theorem 2.3. *Let (u, \mathbf{p}) be a classical solution to the Euler-Lagrange equations associated with \mathbb{F} over $\mathcal{A}_{\mathbf{p}}(\Omega)$. Assume that*

- (1) \mathbf{F} is of class C^2 ,
- (2) \mathbf{F} satisfies $(H4)_{\xi}$ for all $\xi \in \{\nabla u(\omega) : \omega \in \partial\Omega\}$.

Then with \mathbf{G} and \mathbf{T} as in (5) and (6) we have that

$$\mathbb{G}[u, \mathbf{p}; \Omega] \leq \mathbb{G}[\bar{u}, \bar{\mathbf{p}}; \Omega] \tag{9}$$

where $\bar{u}, \bar{\mathbf{p}}$ denote the homogeneous degree-one and degree-zero extensions of u, \mathbf{p} to Ω respectively, that is,

$$\bar{u}(x) := \frac{r}{d(\theta)} u(\theta d(\theta))$$

and

$$\bar{\mathbf{p}}(x) := \mathbf{p}(\theta d(\theta))$$

for $x \in \bar{\Omega}$ where $r = |x|$ and $\theta = x/|x|$.⁷

Proof. For the sake of clarity and convenience we present this in the following *two* steps.

Step 1. ($\mathbb{G}[u, \mathbf{p}; \Omega]$ as a *boundary* integral) For $t \in [0, 1]$ and $\varepsilon > 0$ put

$$\mathbf{s}_{\varepsilon}(t) = \begin{cases} 1 & \text{for } 0 \leq t \leq 1 - \varepsilon \\ 1 - \frac{t - (1 - \varepsilon)}{\varepsilon} & \text{for } 1 - \varepsilon \leq t \leq 1, \end{cases}$$

⁷In the course of the proof of this theorem we make repeated use of the following integration formula. For every $f \in L^1(\Omega)$ we have that

$$\int_{\Omega} f(x) \, dx = \int_0^1 \int_{\partial\Omega} \rho^{n-1} \frac{d(\theta)}{\alpha(\theta)} f(\rho\omega) \, d\mathcal{H}^{n-1}(\omega) \, d\rho.$$

(See [6] for a proof.)

and set

$$\varphi(x) = \mathbf{s}_\varepsilon \left(\frac{|x|}{d(\theta)} \right) x. \quad (10)$$

Then one can easily verify that

$$\begin{aligned} \nabla \varphi(x) &= \mathbf{s}_\varepsilon \left(\frac{|x|}{d(\theta)} \right) \mathbf{I}_n + |x| \frac{1}{d(\theta)} \mathbf{s}'_\varepsilon \left(\frac{|x|}{d(\theta)} \right) \theta \otimes \left(\theta - (\mathbf{I}_n - \theta \otimes \theta) \frac{\nabla d(\theta)}{d(\theta)} \right) \\ &= \mathbf{s}_\varepsilon \left(\frac{|x|}{d(\theta)} \right) \mathbf{I}_n + |x| \frac{\alpha(\theta)}{d(\theta)} \mathbf{s}'_\varepsilon \left(\frac{|x|}{d(\theta)} \right) \theta \otimes \nu, \end{aligned}$$

where $\theta = x/|x|$ and $\nu = \nu(\theta d(\theta))$ is the unit *outward* normal to $\partial\Omega$. Moreover it is evident that

$$\mathbf{1}_\Omega = \lim_{\varepsilon \downarrow 0} \mathbf{s}_\varepsilon \left(\frac{|x|}{d(\theta)} \right) \quad (11)$$

where the *limit* is being understood both as \mathcal{L}^n -a.e. in Ω and strongly in $L^1(\Omega)$. Now upon substituting φ as given by (10) into (8) and re-arranging terms it follows after taking into account (11) that

$$\begin{aligned} n\mathbb{G}[u, \mathbf{p}; \Omega] &= \lim_{\varepsilon \downarrow 0} \int_\Omega n \mathbf{s}_\varepsilon \left(\frac{|x|}{d(\theta)} \right) \mathbf{G}(x, u, \nabla u) dx \\ &= \lim_{\varepsilon \downarrow 0} \int_\Omega \left\{ -\frac{\alpha(\theta)}{d(\theta)} |x| (\theta \cdot \nu) \mathbf{s}'_\varepsilon \left(\frac{|x|}{d(\theta)} \right) \mathbf{G}(x, u, \nabla u) \right. \\ &\quad \left. + \mathbf{s}_\varepsilon \left(\frac{|x|}{d(\theta)} \right) \langle \mathbf{G}_\xi(x, u, \nabla u), \nabla u \rangle \right. \\ &\quad \left. + \frac{\alpha(\theta)}{d(\theta)} |x| \mathbf{s}'_\varepsilon \left(\frac{|x|}{d(\theta)} \right) \langle \mathbf{G}_\xi(x, u, \nabla u), \nabla u \theta \otimes \nu \rangle \right\} dx \\ &= \lim_{\varepsilon \downarrow 0} \{\mathbf{I} + \mathbf{II} + \mathbf{III}\}. \quad (12) \end{aligned}$$

We now proceed by considering each term separately. Indeed, with regards to the *first* term we have that

$$\begin{aligned} \mathbf{I} = \mathbf{I}(\varepsilon) &= \int_\Omega -\frac{\alpha(\theta)}{d(\theta)} |x| (\theta \cdot \nu) \mathbf{s}'_\varepsilon \left(\frac{|x|}{d(\theta)} \right) \mathbf{G}(x, u, \nabla u) dx \\ &= \int_\Omega -\frac{1}{d(\theta)} |x| \mathbf{s}'_\varepsilon \left(\frac{|x|}{d(\theta)} \right) \mathbf{F}(\nabla u(x)) dx \\ &= \int_{1-\varepsilon}^1 \int_{\partial\Omega} \frac{1}{\varepsilon} \rho^n \frac{d(\theta)}{\alpha(\theta)} \mathbf{F}(\nabla u(\rho\omega)) d\mathcal{H}^{n-1}(\omega) d\rho. \end{aligned}$$

Thus by passing to the limit $\varepsilon \downarrow 0$ we have that

$$\begin{aligned} \lim_{\varepsilon \downarrow 0} \mathbf{I} &= \lim_{\varepsilon \downarrow 0} \int_{1-\varepsilon}^1 \int_{\partial\Omega} \frac{1}{\varepsilon} \rho^n \frac{d(\theta)}{\alpha(\theta)} \mathbf{F}(\nabla u(\rho\omega)) d\mathcal{H}^{n-1}(\omega) d\rho \\ &= \int_{\partial\Omega} \frac{d(\theta)}{\alpha(\theta)} \mathbf{F}(\nabla u(\omega)) d\mathcal{H}^{n-1}(\omega). \end{aligned}$$

In a similar way with regards to the *second* term we have that

$$\begin{aligned} \mathbf{II} &= \mathbf{II}(\varepsilon) = \int_{\Omega} \mathbf{s}_{\varepsilon} \left(\frac{|x|}{d(\theta)} \right) \langle \mathbf{G}_{\xi}(x, u, \nabla u), \nabla u \rangle dx \\ &= \int_{\Omega} \mathbf{s}_{\varepsilon} \left(\frac{|x|}{d(\theta)} \right) \langle \mathbf{F}_{\xi}(\nabla u) - \mathbf{p}(x)[\text{cof } \nabla u], \nabla u \rangle dx. \end{aligned}$$

Utilising (11) and Lebesgue's theorem on dominated converge, passing to the limit $\varepsilon \downarrow 0$ yields

$$\begin{aligned} \lim_{\varepsilon \downarrow 0} \mathbf{II} &= \lim_{\varepsilon \downarrow 0} \int_{\Omega} \mathbf{s}_{\varepsilon} \left(\frac{|x|}{d(\theta)} \right) \langle \mathbf{F}_{\xi}(\nabla u) - \mathbf{p}(x)[\text{cof } \nabla u], \nabla u \rangle dx \\ &= \int_{\Omega} \langle \mathbf{F}_{\xi}(\nabla u) - \mathbf{p}(x)[\text{cof } \nabla u], \nabla u \rangle dx \\ &= \int_{\partial\Omega} \langle \mathbf{F}_{\xi}(\nabla u(\omega)) - \mathbf{p}(\omega)[\text{cof } \nabla u(\omega)], u(\omega) \otimes \nu \rangle d\mathcal{H}^{n-1}(\omega), \end{aligned}$$

where in the *second* identity we have appealed to the *divergence* theorem along with the fact that (u, \mathbf{p}) is a solution to the Euler-Lagrange equations associated with \mathbb{F} over \mathcal{A}_p .

Finally with regards to the *third* term we can write

$$\begin{aligned} \mathbf{III} &= \mathbf{III}(\varepsilon) \\ &= \int_{\Omega} \frac{\alpha(\theta)}{d(\theta)} |x| \mathbf{s}'_{\varepsilon} \left(\frac{|x|}{d(\theta)} \right) \langle \mathbf{G}_{\xi}(x, u, \nabla u), \nabla u \theta \otimes \nu \rangle dx \\ &= \int_{\Omega} \frac{\alpha(\theta)}{d(\theta)} |x| \mathbf{s}'_{\varepsilon} \left(\frac{|x|}{d(\theta)} \right) \langle \mathbf{F}_{\xi}(\nabla u) - \mathbf{p}(x)[\text{cof } \nabla u], \nabla u \theta \otimes \nu \rangle dx \\ &= \int_{1-\varepsilon}^1 \int_{\partial\Omega} -\frac{1}{\varepsilon} \rho^n d(\theta) \\ &\quad \times \{ \langle \mathbf{F}_{\xi}(\nabla u(\rho\omega)) - \mathbf{p}(\rho\omega)[\text{cof } \nabla u(\rho\omega)], \nabla u(\rho\omega) \theta \otimes \nu \rangle \} d\mathcal{H}^{n-1}(\omega) d\rho. \end{aligned}$$

Thus by passing to the limit $\varepsilon \downarrow 0$ we have that

$$\begin{aligned} \lim_{\varepsilon \downarrow 0} \mathbf{III} &= \lim_{\varepsilon \downarrow 0} \int_{1-\varepsilon}^1 \int_{\partial\Omega} -\frac{1}{\varepsilon} \rho^n d(\theta) \\ &\quad \times \{ \langle \mathbf{F}_{\xi}(\nabla u(\rho\omega)) - \mathbf{p}(\rho\omega)[\text{cof } \nabla u(\rho\omega)], \nabla u(\rho\omega) \theta \otimes \nu \rangle \} d\mathcal{H}^{n-1}(\omega) d\rho \\ &= \int_{\partial\Omega} -d(\theta) \langle \mathbf{F}_{\xi}(\nabla u(\omega)) - \mathbf{p}(\omega)[\text{cof } \nabla u(\omega)], \nabla u(\omega) \theta \otimes \nu \rangle d\mathcal{H}^{n-1}(\omega). \end{aligned}$$

Hence referring to (12) and *summarising* the above conclusions we have that

$$\begin{aligned}
& n\mathbb{G}[u, \mathbf{p}; \Omega] \\
&= \int_{\Omega} n\mathbf{G}(x, u, \nabla u) dx \\
&= \int_{\partial\Omega} \frac{d(\theta)}{\alpha(\theta)} \mathbf{F}(\nabla u(\omega)) d\mathcal{H}^{n-1}(\omega) \\
&\quad + \int_{\partial\Omega} \langle \mathbf{F}_{\xi}(\nabla u(\omega)) - \mathbf{p}(\omega)[\text{cof } \nabla u(\omega)], u(\omega) \otimes \nu \rangle d\mathcal{H}^{n-1}(\omega) \\
&\quad - \int_{\partial\Omega} d(\theta) \langle \mathbf{F}_{\xi}(\nabla u(\omega)) - \mathbf{p}(\omega)[\text{cof } \nabla u(\omega)], \nabla u(\omega)\theta \otimes \nu \rangle d\mathcal{H}^{n-1}(\omega). \quad (13)
\end{aligned}$$

Step 2. (A lower bound on $\mathbb{G}[\bar{u}, \bar{\mathbf{p}}; \Omega]$) Recall that the *homogeneous* degree-one extension of u to Ω is given by

$$\bar{u}(x) = \frac{|x|}{d(\theta)} u(\theta d(\theta))$$

for $x \in \bar{\Omega}$ with $\theta = x/|x|$. It can therefore be easily checked that

$$\begin{aligned}
\nabla \bar{u}(x) &= \nabla u(\theta d(\theta)) + \left\{ \left(\frac{u(\theta d(\theta))}{d(\theta)} - \nabla u(\theta d(\theta))\theta \right) \otimes \left(\theta - (\mathbf{I}_n - \theta \otimes \theta) \frac{\nabla d(\theta)}{d(\theta)} \right) \right\} \\
&= \nabla u(\omega) + \frac{\alpha(\theta)}{d(\theta)} \{ [u(\omega) - d(\theta)\nabla u(\omega)\theta] \otimes \nu \} \quad (14)
\end{aligned}$$

for $x \in \bar{\Omega}$ where $\omega = \theta d(\theta) \in \partial\Omega$. In particular we have that

$$\begin{aligned}
\det \nabla \bar{u}(x) &= \det \nabla u(\omega) + \frac{\alpha(\theta)}{d(\theta)} \langle [\nabla u(\omega)]^{-1} [u(\omega) - d(\theta)\nabla u(\omega)\theta], \nu \rangle \\
&= 1 + \frac{\alpha(\theta)}{d(\theta)} \langle [\text{cof } \nabla u(\omega)]^t [u(\omega) - d(\theta)\nabla u(\omega)\theta], \nu \rangle. \quad (15)
\end{aligned}$$

Thus we can write

$$\begin{aligned}
& n\mathbb{G}[\bar{u}, \bar{\mathbf{p}}; \Omega] \\
&= n \int_{\Omega} \mathbf{G}(x, \bar{u}, \nabla \bar{u}; \bar{\mathbf{p}}) dx \\
&= n \int_{\Omega} \mathbf{F}(\nabla \bar{u}) - \bar{\mathbf{p}}(x)[\det \nabla \bar{u} - 1] dx \\
&= n \int_0^1 \int_{\partial\Omega} \rho^{n-1} \frac{d(\theta)}{\alpha(\theta)} \times \{ \mathbf{F}(\nabla \bar{u}(\rho\omega)) - \bar{\mathbf{p}}(\rho\omega)[\det \nabla \bar{u}(\rho\omega) - 1] \} d\mathcal{H}^{n-1}(\omega) d\rho \\
&= \int_{\partial\Omega} \frac{d(\theta)}{\alpha(\theta)} \{ \mathbf{F}(\nabla \bar{u}(\omega)) - \bar{\mathbf{p}}(\omega)[\det \nabla \bar{u}(\omega) - 1] \} d\mathcal{H}^{n-1}(\omega) \quad (16)
\end{aligned}$$

where in concluding the *last* line we have used the identities $\nabla \bar{u}(\rho\omega) = \nabla \bar{u}(\omega)$ and $\bar{\mathbf{p}}(\rho\omega) = \bar{\mathbf{p}}(\omega)$ for $\rho \in [0, 1]$ and $\omega \in \partial\Omega$ as a consequence of *homogeneity*.

Now anticipating on the integral on the *right* in (16) we *first* note that in view of the *rank-one* convexity of \mathbf{F} at the points $\nabla u(\omega)$ using (14) [with $x = \omega$] we have that

$$\begin{aligned} \mathbf{F}(\nabla \bar{u}(\omega)) &= \mathbf{F}(\nabla u(\omega) + \frac{\alpha(\theta)}{d(\theta)}[u(\omega) - d(\theta)\nabla u(\omega)\theta] \otimes \nu) \\ &\geq \mathbf{F}(\nabla u(\omega)) + \frac{\alpha(\theta)}{d(\theta)} \langle \mathbf{F}_\xi(\nabla u(\omega)), [u(\omega) - d(\theta)\nabla u(\omega)\theta] \otimes \nu \rangle. \end{aligned} \quad (17)$$

Hence substituting from (15) and (17) into (16) and making note of the inequality $d/\alpha > 0$ we can write

$$\begin{aligned} n\mathbb{G}[\bar{u}, \bar{\mathbf{p}}; \Omega] &= \int_{\partial\Omega} \frac{d(\theta)}{\alpha(\theta)} \{ \mathbf{F}(\nabla \bar{u}(\omega)) - \bar{\mathbf{p}}(\omega)[\det \nabla \bar{u}(\omega) - 1] \} d\mathcal{H}^{n-1}(\omega) \\ &\geq \int_{\partial\Omega} \frac{d(\theta)}{\alpha(\theta)} \mathbf{F}(\nabla u(\omega)) d\mathcal{H}^{n-1}(\omega) \\ &\quad + \int_{\partial\Omega} \langle \mathbf{F}_\xi(\nabla u(\omega)), [u(\omega) - d(\theta)\nabla u(\omega)\theta] \otimes \nu \rangle d\mathcal{H}^{n-1}(\omega) \\ &\quad - \int_{\partial\Omega} \mathbf{p}(\omega) \langle [\text{cof } \nabla u(\omega)]^t [u(\omega) - d(\theta)\nabla u(\omega)\theta], \nu \rangle d\mathcal{H}^{n-1}(\omega). \end{aligned}$$

Finally, re-arranging terms and comparing the expression on the *right* in the above with (13) immediately yields

$$\begin{aligned} &n\mathbb{G}[\bar{u}, \bar{\mathbf{p}}; \Omega] \\ &\geq \int_{\partial\Omega} \frac{d(\theta)}{\alpha(\theta)} \mathbf{F}(\nabla u(\omega)) d\mathcal{H}^{n-1}(\omega) \\ &\quad + \int_{\partial\Omega} \langle \mathbf{F}_\xi(\nabla u(\omega)) - \mathbf{p}(\omega)[\text{cof } \nabla u(\omega)], u(\omega) \otimes \nu \rangle d\mathcal{H}^{n-1}(\omega) \\ &\quad - \int_{\partial\Omega} d(\theta) \langle \mathbf{F}_\xi(\nabla u(\omega)) - \mathbf{p}(\omega)[\text{cof } \nabla u(\omega)], \nabla u(\omega)\theta \otimes \nu \rangle d\mathcal{H}^{n-1}(\omega) \\ &\geq n\mathbb{G}[u, \mathbf{p}; \Omega] \end{aligned}$$

which is the required conclusion. □

In the remainder of this section we confine ourselves to the case of *linear* boundary conditions, that is, $v = \bar{\xi}x$ where $\bar{\xi} \in \mathbb{M}_{n \times n}$ and $\det \bar{\xi} = 1$.

Theorem 2.4 (Uniqueness I). *Let $\Omega \subset \mathbb{R}^n$ be a C^1 bounded starshaped domain and consider the energy functional \mathbb{F} over $\mathcal{A}_p(\Omega)$. Assume that*

- (1) \mathbf{F} is of class C^2 ,
- (2) \mathbf{F} satisfies (H1) and (H3) $_{\bar{\xi}}$,
- (3) (u, \mathbf{p}) a classical solution (see Definition 2.1),
- (4) \mathbf{F} satisfies (H4) $_{\xi}$ for all $\xi \in \{\nabla u(\omega) : \omega \in \partial\Omega\}$.

Then,

$$\mathbb{F}[u; \Omega] = \mathbb{F}[\bar{\xi}x; \Omega] = \inf_{\mathcal{A}_p(\Omega)} \mathbb{F}[\cdot; \Omega].$$

If, additionally, \mathbf{F} is strictly quasiconvex at $\bar{\xi}$ then $u = \bar{\xi}x$ on $\bar{\Omega}$.

Proof. Evidently $\bar{u} = \bar{\xi}x$ and therefore $\det \nabla \bar{u} = 1$ in Ω .⁸ Hence referring to the estimate (9) in Theorem 2.3 and the *quasiconvexity* of \mathbf{F} at $\bar{\xi}$ we can write

$$\mathbb{F}[\bar{u}; \Omega] \leq \mathbb{F}[u; \Omega] = \mathbb{G}[u, \mathbf{p}; \Omega] \leq \mathbb{G}[\bar{u}, \bar{\mathbf{p}}; \Omega] = \mathbb{F}[\bar{u}; \Omega].$$

The remaining assertion is now a *trivial* consequence of the latter and the *strict* quasiconvexity of \mathbf{F} at $\bar{\xi}$. \square

Remark 2.5. The proof of Theorem 2.3 and Theorem 2.4 remain unchanged if \mathbf{F} is of class C^1 and in Definition 2.1 (1) is replaced by $u \in C^1(\bar{\Omega}, \mathbb{R}^n)$, (2) by $\mathbf{p} \in C^0(\bar{\Omega})$ and (3) by (u, \mathbf{p}) being a *weak* solution to the corresponding system of Euler-Lagrange equation provided that *additionally* (8) holds.

Theorem 2.6 (Uniqueness II). *Let $\Omega \subset \mathbb{R}^n$ be a bounded starshaped domain and consider the energy functional \mathbb{F} over $\mathcal{A}_p(\Omega)$. Assume that*

- (1) \mathbf{F} is of class C^0 ,
- (2) \mathbf{F} satisfies (H1) and (H3) $_{\bar{\xi}}$,
- (3) $u \in \mathcal{A}_p(\Omega)$ is a strong local minimizer of \mathbb{F} , i.e., that there exists $\rho = \rho(u) > 0$ such that $\mathbb{F}[u; \Omega] \leq \mathbb{F}[w; \Omega]$ for all $w \in \mathcal{A}_p(\Omega)$ with $\|u - w\|_{W^{1,p}} \leq \rho$.

Then,

$$\mathbb{F}[u; \Omega] = \mathbb{F}[\bar{\xi}x; \Omega] = \inf_{\mathcal{A}_p(\Omega)} \mathbb{F}[\cdot; \Omega]. \quad (18)$$

If, additionally, \mathbf{F} is strictly quasiconvex at $\bar{\xi}$ then $u = \bar{\xi}x$ on $\bar{\Omega}$.

Proof. The *second* identity in (18) is a result of (1), (2) and a straight-forward *approximation* and so it suffices to justify only the *first* equality. Indeed for the sake of a contradiction assume $\mathbb{F}[u; \Omega] > \mathbb{F}[\bar{\xi}x; \Omega]$ and for $\delta \in (0, 1]$ and $x \in \Omega$ set

$$u_\delta(x) := \begin{cases} \delta u(\frac{x}{\delta}) & x \in \bar{\Omega}_\delta, \\ \bar{\xi}x & x \in \Omega \setminus \bar{\Omega}_\delta, \end{cases}$$

where $\Omega_\delta = \delta\Omega$. Then $\det \nabla u_\delta = 1$ \mathcal{L}^n -a.e. in Ω and so $u_\delta \in \mathcal{A}_p(\Omega)$. Moreover a straight-forward calculation gives

$$\begin{aligned} \mathbb{F}[u_\delta; \Omega] &= \mathbb{F}[u; \Omega] + (1 - \delta^n) \{ \mathbb{F}[\bar{\xi}x; \Omega] - \mathbb{F}[u; \Omega] \} \\ &< \mathbb{F}[u; \Omega] \end{aligned}$$

whilst $u_\delta \rightarrow u$ in $W^{1,p}$ as $\delta \uparrow 1$. This contradicts (3) and so the assertion is justified. The final part is now a *trivial* consequence of the latter and the *strict* quasiconvexity of \mathbf{F} at $\bar{\xi}$. \square

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⁸Note that in general $\det \nabla \bar{u} = 1$ is *false!* [See (15)] However, interestingly, subject to $u = \bar{\xi}x$ on $\partial\Omega$ as described the latter identity holds throughout Ω .

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