

Closed Space Curves of Constant Curvature Consisting of Arcs of Circular Helices

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Abstract. A *closed* κ_0 -*curve* is a closed regular curve of class C^r ($r \geq 2$) in the Euclidean 3-space having constant curvature $\kappa_0 > 0$. We present various examples of nonplanar closed κ_0 -curves of class C^2 , which are composed of n arcs of circular helices. The construction of c starts from the spherical image (= tangent indicatrix) c^* of c , which then has to be a closed regular curve of class C^1 on the unit sphere S^2 consisting of n circular arcs and having the center O^* of S^2 as its center of gravity. The case $c^* \subseteq S^2 \cap \Pi$ is studied in detail, assuming that Π is a cube, or, more generally, a regular polyhedron the edges of which are tangent to S^2 . In order to describe and to visualize the curves c^* and c , and to derive c from c^* , projection methods of Descriptive Geometry are used.

Keywords: closed (composite) space curve, constant curvature, circular helix, spherical image, tangent indicatrix, center of gravity, regular polyhedron.

MSC 1994: 53A04, 51M20, 51N05

1. Introduction

In the real 3-dimensional Euclidean space \mathbb{E}^3 , curves c of class C^r ($r \geq 2$) the first curvature κ of which is prescribed by a function $\kappa = \kappa(s)$ of class C^{r-2} depending on the arc length parameter s of c have been studied in different regards. There is e.g. a theorem of existence and uniqueness up to translations if additionally the spherical image c^* of c is given (see [4], 183–185; [9], 162–163), including considerations under which assumptions on c^* and $\kappa(s)$ the curve c is closed ([1], 78–79; [4], 183–185).

In [2], p. 182, E. CESÀRO has considered the special case of space curves with *constant curvature* $\kappa(s) = \kappa_0 > 0$. These curves usually are called *twisted circles* of curvature κ_0 (in German: *windschiefe Kreise*), although they need not be closed, or shortly κ_0 -*curves*. Special

twisted circles having *constant torsion* $\tau(s) = \tau_0$ are the closed but planar *circles* ($\tau_0 = 0$) and the nonplanar and not closed *circular helices* ($\tau_0 \neq 0$).

In the differential-geometric literature it has been mentioned (see [1], 78–79) and proved (see [4], 183–185; compare [9], 162–163) that there exist nontrivial, i.e. *nonplanar*, closed twisted circles of curvature κ_0 , but explicit examples of such nontrivial *closed* κ_0 -*curves* seem to be missing.

In this note we present *examples of closed* κ_0 -*curves* c of class C^2 which can be generated by *connecting arcs of circular helices of curvature* κ_0 (see Sections 5 and 6). Our construction, as developed in Sections 3.1 and 4, starts from the *tangent indicatrix* c^* of c which then must consist of *circular arcs on the unit sphere* S^2 . In this context, we first need some differential geometric tools concerning closed κ_0 -curves in general (see Section 2).

Note that, in the following sections, it is substantial, in particular with respect to the spherical image c^* , to distinguish between a “*curve*” (a *regular curve*) as a bare point set and its parametrization — in the sense of an *oriented parametric curve* — which will be called a “*path*” (a *regular path*), respectively. Only by using the notion *path* it is e.g. possible to express that a circle or a circular arc is multiply traced by any moving point.

2. Differential geometrical tools

Proposition. *Construction of a closed* κ_0 -*curve* c of class C^2 from its *tangent indicatrix* c^* of class C^1 : In the Euclidean 3-space \mathbb{E}^3 let be given a regular closed curve $c^* : \mathfrak{r}^*(s^*)$, $s^* \in I^* := [0, L^*]$ of class C^{r-1} ($r \geq 2$) on the unit sphere S^2 with center $O^*(0, 0, 0)$. Let c^* , without loss of generality, be parametrized by its arc length parameter s^* ($0 \leq s^* \leq L^*$; $L^* > 0$) thus defining a path (oriented parametric curve) c^* of *path length* L^* . Under these conditions which are equivalent to

$$\begin{aligned} \|\mathfrak{r}^*(s^*)\| &= \left\| \frac{d\mathfrak{r}^*}{ds^*}(s^*) \right\| = 1 \quad \forall s^* \in I^*, \\ \mathfrak{r}^*(0) &= \mathfrak{r}^*(L^*), \quad \frac{d^k \mathfrak{r}^*}{ds^{*k}}(0) = \frac{d^k \mathfrak{r}^*}{ds^{*k}}(L^*) \quad (k = 1, \dots, r-1) \end{aligned} \tag{1}$$

the following propositions (a), (b), (c) hold¹:

(a) For any $\kappa_0 > 0$, the curve $c \subset \mathbb{E}^3$ which is defined — according to (1) — by

$$c : \quad \mathfrak{r}(s) = \frac{1}{\kappa_0} \int_0^{\kappa_0 s} \mathfrak{r}^*(s^*) ds^*, \quad s \in I := [0, L], \quad L := \frac{L^*}{\kappa_0} \tag{2}$$

is a regular space curve of class C^r with the arc length parameter s , the path length $L = L^*/\kappa_0$ and the constant first curvature $\kappa(s) := \|\mathfrak{r}''(s)\| = \kappa_0$, i.e. c is a κ_0 -*curve of class* C^r (compare [9], 162–163); corresponding arcs of c^* and c have proportional lengths $s^* \in [0, L^*]$ and $s = s^*/\kappa_0 \in [0, L]$, respectively.

Note that, according to (2), any two closed κ_0 -curves c_1 and c_2 of constant positive curvature κ_1 , κ_2 , respectively, corresponding to the *same spherical image* (tangent indicatrix) c^* are *similar* to each other: c_2 arises from c_1 via a *homothety of ratio* $\kappa_1/\kappa_2 > 0$.

¹for the conditions of closure used here in (1)₂, compare [8], p. 21

- (b) A κ_0 -curve c of class C^r ($r \geq 2$) defined by (2), (1) is *closed*, i.e., a closed κ_0 -curve, if and only if the geometric center of gravity G^* of its tangent indicatrix c^* considered as a path coincides with the center O^* of S^2 , that is if and only if (compare [4])

$$L^* \cdot \overrightarrow{O^*G^*} := \int_0^{L^*} \mathbf{r}^*(s^*) ds^* = \mathbf{o}. \quad (3)$$

- (c) A closed κ_0 -curve c of class C^r ($r \geq 2$) defined by (2), (1), (3) is *nonplanar* if and only if its closed tangent indicatrix $c^* \subset S^2$ as a point set is *not* a great circle of S^2 .

Proof:

- (a) From (2) we get

$$\frac{d\mathbf{x}}{ds}(s) = \mathbf{r}^*(\kappa_0 s) \xrightarrow{(1)} \left(\frac{d\mathbf{x}}{ds} \right)^2 \equiv 1 \quad \forall s \in I, \quad \mathbf{x}''(s) := \frac{d^2\mathbf{x}}{ds^2}(s) = \kappa_0 \frac{d\mathbf{x}^*}{ds^*}(\kappa_0 s).$$

Because of (1) this means that c is *regular* having s as its *arc length parameter* and the *constant curvature* $\kappa(s) = \|\mathbf{x}''(s)\| = \kappa_0$.

- (b) In consequence of (2), (1) we get:

$$\text{A } \kappa_0\text{-curve } c : \mathbf{x}(s), s \in I \text{ is } \textit{closed} \iff \mathbf{o} = \mathbf{x}(L) - \mathbf{x}(0) = \frac{1}{\kappa_0} \int_0^{L^*} \mathbf{r}^*(s^*) ds^* \iff (3).$$

- (c) Any regular curve $c \subset \mathbb{E}^3 : \mathbf{x}(s), s \in I$ of class C^1 , having without loss of generality s as its arc length parameter, is *planar* if and only if there exists a vector $\mathbf{a} \in \mathbb{R}^3 \setminus \{\mathbf{o}\}$ such that $\mathbf{a} \cdot \mathbf{x}(s) = \mathbf{a} \cdot \mathbf{x}(s_0), \forall s \in I (s_0 \in I) \iff \mathbf{a} \cdot \mathbf{x}'(s) = 0 \quad \forall s \in I$ (*).

On the other hand, the tangent indicatrix $c^* : \mathbf{x}^*(s) := \mathbf{x}'(s), s \in I$ (which is a curve of class C^0 on S^2) of such a regular curve c of class C^1 is contained in a great circle of S^2 if and only if c^* is contained in a plane having normal vector \mathbf{b} and containing $O^*(0, 0, 0) \iff$ there exists a vector $\mathbf{b} \in \mathbb{R}^3 \setminus \{\mathbf{o}\}$ such that $0 = \mathbf{b} \cdot \mathbf{x}^*(s) = \mathbf{b} \cdot \mathbf{x}'(s) \quad \forall s \in I$ (**).

Since the conditions (*), (**) coincide for $\mathbf{a} = \mathbf{b}$, one gets the local [global] result: A regular [closed regular] curve $c \subset \mathbb{E}^3$ of class C^1 is planar \iff the point set of the tangent indicatrix c^* of c is contained in [equals] a great circle of S^2 . q.e.d.

Remark: According to FENCHEL's Theorem (see [3], 238–245; [7], 139–145; [8], 31–32) and Eq. (2), the path length L^* of the tangent indicatrix c^* of a nonplanar closed κ_0 -curve c and the length L of c satisfy the inequalities $L^* > 2\pi$ and $L = L^*/\kappa_0 > 2\pi/\kappa_0$, respectively.

3. Special tangent indicatrices of closed κ_0 -curves, lying on regular polyhedra

3.1.

Let Π be any *regular polyhedron* (regular tetrahedron, hexahedron (cube), octahedron, dodecahedron or icosahedron, respectively), of edge length $e > 0$, and denote by O^* the *point of symmetry* (= center of the circumsphere) of Π . It is well-known and obvious for reasons of symmetry that there is a unique sphere $S^2(O^*, \rho)$ with center O^* and radius $\rho = \rho(e) > 0$ being tangent to all of the edges of Π touching them at their midpoints A, B, C, \dots , compare [5], 84–91 for certain tetrahedra Π and [6], 436–438 for regular polyhedra Π . Obviously, this

edge-sphere (German: *Kantenkugel*) of Π intersects each face of Π , which is a regular m -gon, $m \in \{3, 4, 5\}$, in its incircle being tangent to the edges of this face at their midpoints. Let e be chosen in such a way that $\rho(e) = 1$, i.e. that the edge-sphere of Π is the unit sphere $S^2(O^*, 1) =: S^2$ with center O^* . In the case of a cube Π , which will be studied in detail later on, this means $e = \sqrt{2}$.

For reasons of symmetry, O^* is the center of gravity of the union \mathcal{I} of the incircles of all faces of Π . Now, by Proposition (b), any closed regular path $c^* \subseteq \mathcal{I}$ of class C^1 , having O^* as its center of gravity, will be the spherical image (= the tangent indicatrix) of closed κ_0 -curves c of class C^2 , which are determined by c^* up to similarities, the ratio of similarity being $1/\kappa_0$. By this we have found a simple *geometric method* of constructing tangent indicatrices of closed κ_0 -curves of class C^2 consisting of arcs of circular helices.

3.2.

For first examples — which show that closed κ_0 -curves consisting of helical arcs do exist — we consider in Fig. 1 three different regular polyhedra Π_i ($i = 1, 2, 3$), a *cube* Π_1 , a regular *tetrahedron* Π_2 , and a regular *octahedron* Π_3 , each of them having an edge-sphere S^2 with radius 1. Each of the regular polyhedra Π_1, Π_2, Π_3 has regular m -gons as faces, with $m = 4, 3, 3$, respectively. Each of these polyhedra Π_i carries a spherical image $c_i^* \subseteq \Pi_i \cap S^2$ of closed κ_0 -curves c_i ($i = 1, 2, 3$): The paths c_i^* chosen in Fig. 1 consist of $n = 6, 4, 6$ circular arcs of central angle $2\pi/m$, which is the smallest central angle possible, respectively; none of these paths c_i^* is contained in a great circle of S^2 , and each of them has the center O^* of its supporting regular polyhedron Π_i as its center of gravity, for each of the curves c_1^*, c_3^* is symmetric with respect to the center O^* of Π_1, Π_3 , respectively, and the curve c_2^* is mapped onto itself by a rotary reflection ρ which is composed of the reflection with respect to the plane $ABCD$ and a $(\pi/2)$ - or $(-\pi/2)$ -rotation about the normal of this plane passing through the center O^* of Π_2 , which is the only fixed point of ρ . So each of the paths c_i^* ($i = 1, 2, 3$) in Fig. 1 is the *spherical image of nonplanar closed κ_0 -curves c_i* (Examples 1, 2, 3). The shape of these curves c_i can be derived using the Proposition, Eq. (2) and Section 4, which may be left to the reader. For additional examples of nonplanar closed κ_0 -curves, see the Examples 4–13 (Figs. 2–7), which are discussed in detail, and Example 14 in footnote 3.

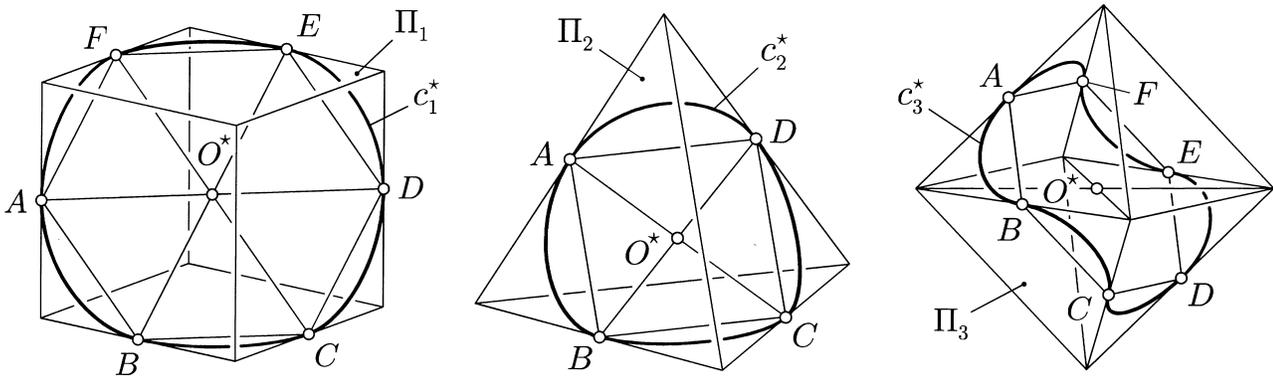


Figure 1: Examples of regular polyhedra carrying a tangent indicatrix of closed κ_0 -curves.

$$c_1^* : +[1/4]ABCDEF A, \quad c_2^* : +[1/3]ABCDA, \quad c_3^* : +[1/3]ABCDEF A$$

3.3.

More generally, the way of composing the tangent indicatrix c^* of closed κ_0 -curves c by n congruent circular arcs of length $k \cdot 2\pi/m$ ($k \in \mathbb{N}$) on the incircles of the faces (= regular m -gons, $m \in \{3, 4, 5\}$) of a regular polyhedron Π , can be described up to congruence and symmetry by a structural formula of the type (for $k = 1$, compare Fig. 1)

$$c^* : \pm[k/m]A_1A_2 \dots A_nA_1 \tag{4}$$

representing an algorithm of constructing c^* as follows. Looking at the outside of the polyhedron Π , each of the incircles of the faces of Π can be oriented either in the positive/counterclockwise or negative/clockwise sense.

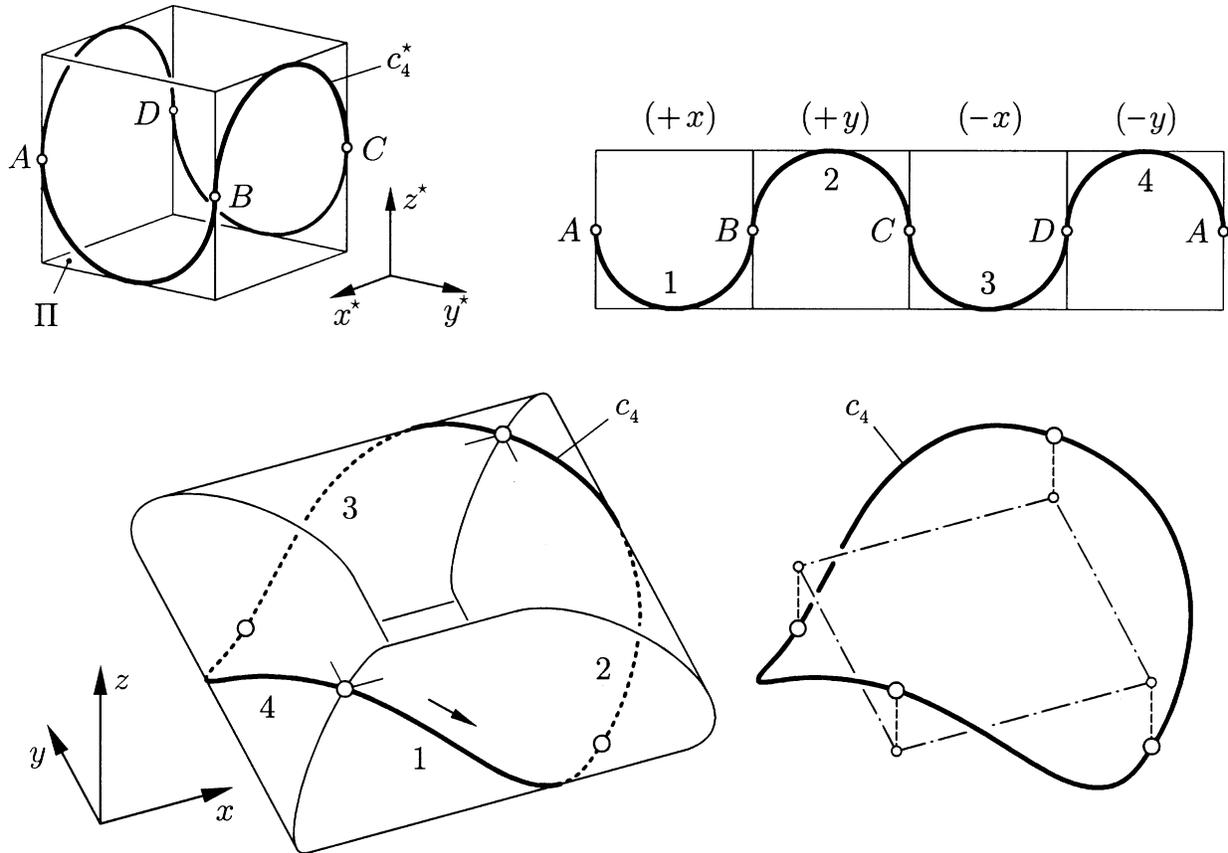


Figure 2: (Example 4) Closed κ_0 -curve c_4 of class C^2 , consisting of (the minimum number of) four congruent helical arcs. Structural formula of c_4^* : $+[1/2]ABCD A$

Eq. (4) tells us to construct a regular path $c^* \subset S^2$ of class C^1 by connecting, one after each other, each of the n pairs $\{A_1, A_2\}, \{A_2, A_3\}, \dots, \{A_n, A_1\}$ of edge-midpoints (= bisecting points of the edges) of Π by a circular arc which is uniquely determined by (i) lying in the unique face of Π which contains both edge-midpoints which are to be connected, (ii) having the central angle $2\pi \cdot k/m$, and (iii) having correct orientation. The correct orientation of the circular arcs is to be determined as follows: the first (“starting”) arc $\widehat{A_1A_2}$ of c^* is oriented in the sense corresponding to the sign $+$ or $-$, respectively, at the beginning of Eq. (4). Proceeding on c^* , any circular arc $\widehat{A_iA_{i+1}}$ ($i = 2, \dots, n \bmod n$) must be oriented in the same or the opposite way as its preceding arc $\widehat{A_{i-1}A_i}$, according to if one remains in the same face

of Π , which then contains the three edge-midpoints A_{i-1}, A_i, A_{i+1} , or if a new face of Π has to be entered (\Leftrightarrow the face of Π being uniquely determined by A_i, A_{i+1} is different from the face containing A_{i-1} and A_i).

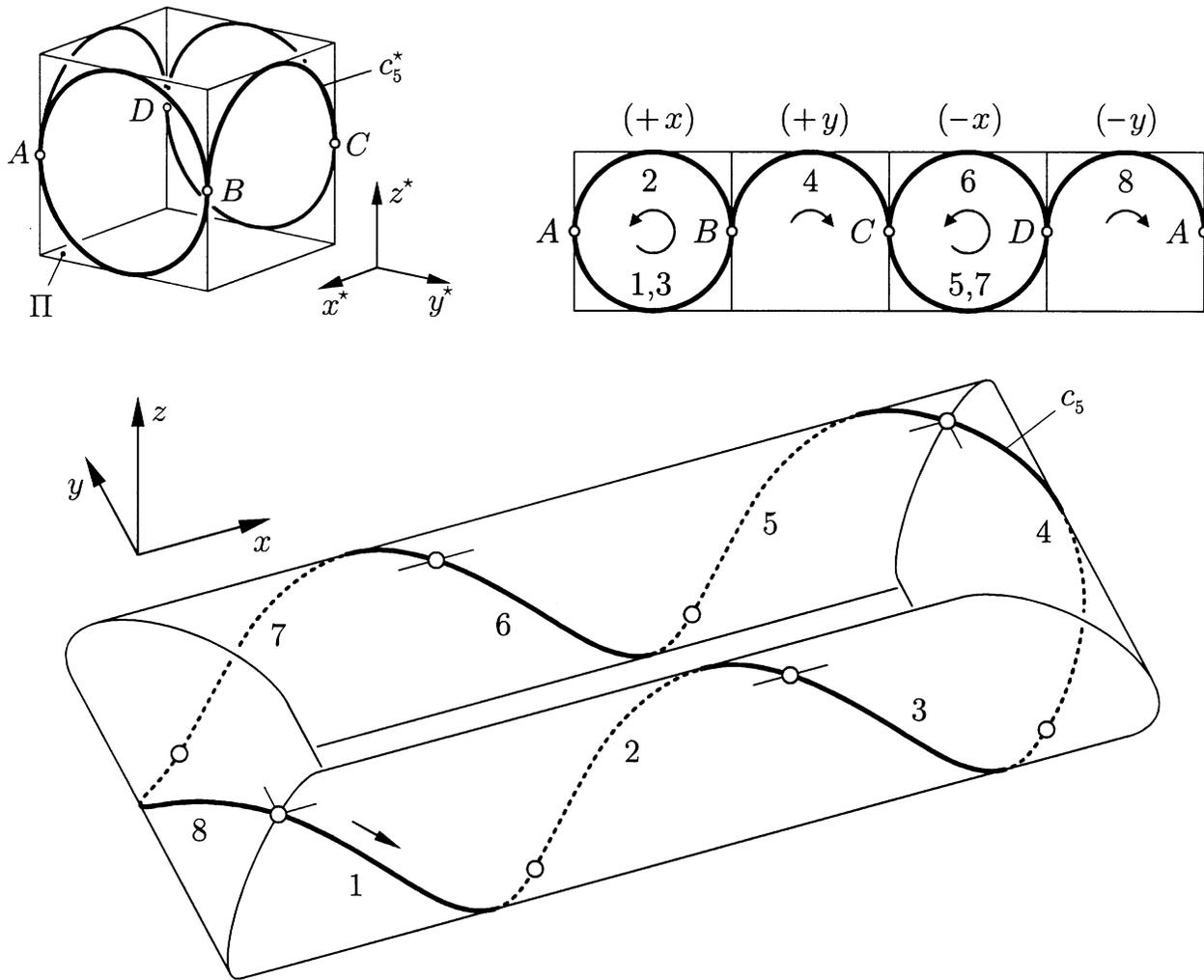


Figure 3: (Example 5) Closed κ_0 -curve c_5 of class C^2 , generated from Example 4 (Fig. 2) by insertion of a pair of congruent helical arcs 2, 3 and 6, 7 of the angle of rotation 2π . This can also be achieved by extending each of the helical arcs 1, 3 of c_4 to its threefold length.

Structural formula of c_5^* : $+ [1/2]ABABCDCDA = + [3/2]AB [1/2]BC [3/2]CD [1/2]DA$

This *rule of orientation* influences in the case $k/m \neq 1/2$ the selection of the next possible edge-midpoint A_{i+1} , too. This results from the demand that there are *no cusps* on the path $c^* := \widehat{A_1 A_2} \cup \widehat{A_2 A_3} \cup \dots \cup \widehat{A_n A_1}$, i.e., that c^* is a *regular path* (a regular closed curve of class C^1). Note that this rule of orientation must be satisfied for the transition from the last arc $\widehat{A_n A_1}$ to the starting arc $\widehat{A_1 A_2}$, too!

After having selected such a regular closed path $c^* \subseteq \mathcal{I}$ on Π , one has to check if the center of gravity G^* of the path c^* coincides with O^* . In most of the cases considered in this note, this property results more or less from symmetry. For instance, all of the paths c^* of the Figs. 1(a),(c), 5, 6, 7 and of footnote 3 (Example 14) are symmetric with respect to O^* , and all of the paths c^* of the Figs. 2, 3, 4 are symmetric at least to the line which is parallel to the z^* -axis and contains O^* . If $G^* = O^*$ — and only then — c^* can be interpreted as the

tangent indicatrix of closed κ_0 -curves which then are described by (2).

3.4.

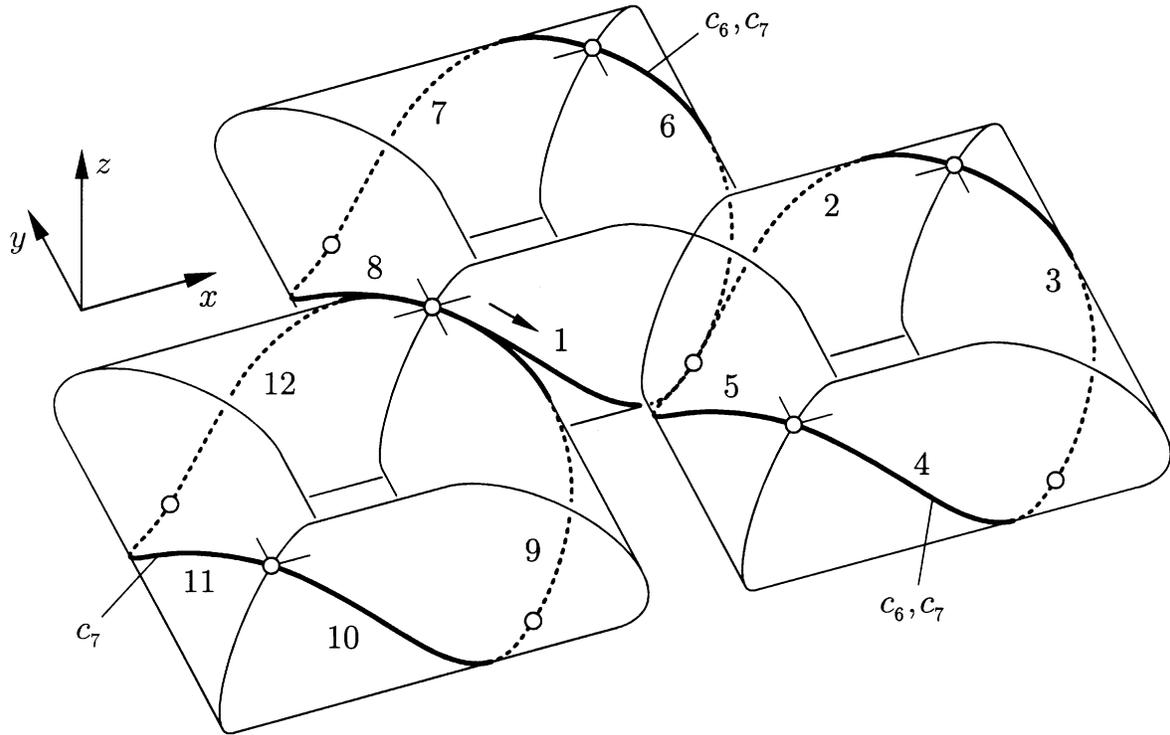
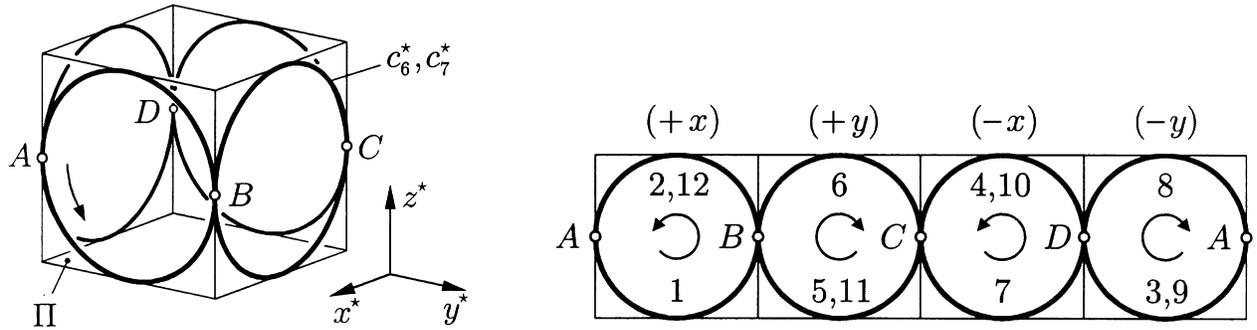


Figure 4: (Examples 6, 7) Closed κ_0 -curves c_6 (arcs 1, ..., 8) and c_7 (arcs 1, ..., 12) of class C^2 , generated by joining two or three copies, respectively, of Example 4 (Fig. 2);

$$c_6^* : +[1/2]ABADCBCDA = +[1/2]BADCB CDAB,$$

$$c_7^* : +[1/2]ABADCBCDADCBA = +[3/2]BA[1/2]ADCBCDADCB$$

In the most general case under consideration, we admit that c^* , being contained in the intersection of the faces of a regular polyhedron Π and its edge-sphere S^2 of radius 1, is composed from $n \geq 4$ circular arcs of *different lengths* $2\pi \cdot k_i/m$ ($k_i \in \mathbb{N}$, $i = 1, 2, \dots, n$; $n \geq 4$), see Figs. 3, 4, 6. The structural formula (4) now is to be generalized to expressions of the type

$$c^* : \pm[k_1/m]A_1A_2 \dots A_p[k_2/m]A_pA_{p+1} \dots A_nA_1 \tag{5}$$

containing two or more changes of the lengths of the circular arcs within c^* , by inserting one

or more *commands of length* $[k_1/m]$, $[k_2/m]$, and so on. Each of these commands determines the lengths of the following circular arcs until the next command of length appears.

4. Closed κ_0 -curves consisting of arcs of circular helices

In order to determine the shape and analytical representation of *nonplanar closed* κ_0 -curves c of class C^2 consisting of $n \geq 4$ *arcs of circular helices* we now have to start from their tangent indicatrices c^* . These special curves/paths c^* are characterized by (i) being closed regular curves of class C^1 on the unit sphere S^2 with center $O^*(0,0,0)$, which consist of n *circular arcs* h_i^* ($i = 1, \dots, n$) of S^2 and (ii) having O^* as their *center of gravity*.

1. *First step:* We determine the helical arc $h \subset c$ having a given circular arc $h^* \subset c^*$ with the central angle $\omega > 0$ and radius $r^* =: \sin \alpha$, $\alpha \in]0, \pi/2]$ as its tangent indicatrix. This is since $0 < r^* \leq 1$. Up to a proper or improper motion, a parametrization of h^* depending on its angle parameter t can be given with respect to the Cartesian $x^*y^*z^*$ -coordinate system by

$$h^* : \quad \mathfrak{r}_h^*(t) = \begin{pmatrix} \cos \alpha \\ \sin \alpha \cos t \\ \sin \alpha \sin t \end{pmatrix}, \quad t \in [0, \omega]; \quad (6)$$

thus h^* is contained in the plane $x^* = \cos \alpha$. The arc length parameter s^* of the curve $h^* \subset c^*$, defined by (6), is (without loss of generality) $s^*(t) = t \sin \alpha$; then, in respect of Proposition (a), the arc length parameter s of the κ_0 -curve $h \subset c$, corresponding to the parametrization (6) of h^* , is given by $s(t) = (\sin \alpha / \kappa_0)t$. Using (6) and $s^*(t)$, $s(t)$ the formula (2) yields the parametrization $\mathfrak{r}_h(t)$ of the curve h of constant curvature κ_0 depending on the parameter t :

$$h : \quad \mathfrak{r}_h(t) = \frac{\sin \alpha}{\kappa_0} \begin{pmatrix} t \cos \alpha \\ \sin \alpha \sin t \\ -\sin \alpha \cos t \end{pmatrix}, \quad t \in [0, \omega]. \quad (7)$$

Obviously h is an arc of a *circular helix*, including the special case of a *circular arc* if $\alpha = \pi/2$, having the radius

$$r = r(\alpha, \kappa_0) = \frac{\sin^2 \alpha}{\kappa_0}, \quad (8)$$

which equals the radius of the circular cylinder containing the helix h , and having the pitch $(\sin 2\alpha / \kappa_0)\pi$ (thus having the *angle of slope* $\pi/2 - \alpha$) and the angle of rotation ω ; the axis of h is parallel to the x -axis.

2. *Second step:* Each of the circular arcs $h_i^* \subset c^*$ having the radius $r_i^* =: \sin \alpha_i$ ($0 < \alpha_i \leq \pi/2$) and the central angle $\omega_i > 0$ is congruent by some motion μ_i , via $h_i^* = \mu_i h^*$, to the circular arc h^* in (6) if we choose $\alpha = \alpha_i$ and $\omega = \omega_i$ ($i = 1, \dots, n$). Then the helical arc $h_i \subset c$ corresponding to h_i^* is uniquely determined via $h_i = \tau_i \circ \mu_i h$, taking h according to (7) and setting $\alpha = \alpha_i$, $\omega = \omega_i$; furthermore, τ_i is a translation which is to be chosen uniquely in such a way that the endpoint with parameter $t = \omega_{i-1}$ of the helical arc h_{i-1} coincides with the starting point with parameter $t = 0$ of the helical arc h_i ($i = 1, \dots, n$). The “helical arc” h_0 formally appearing here is without loss of generality to be set as the single point O^* , which is both starting point *and* endpoint of h_0 .

The figures in this note have been produced using an algorithm based on the formulas and techniques from above.

5. Explicit examples of nonplanar closed κ_0 -curves, the tangent indicatrix of which lies on a cube

5.1. General considerations:

In this section, we consider closed κ_0 -curves c the tangent indicatrix c^* of which is contained as a point set in the union \mathcal{I} of the incircles of the faces of a *cube* Π of edge length $e = \sqrt{2}$, thus having an edge-sphere $S^2 \supset c^*$ of radius 1.

Using the method described in Section 3.1, various examples of spherical images $c_i^* \subseteq \Pi \cap S^2$ ($i = 1$ and $i = 4, \dots, 13$) of nonplanar closed κ_0 -curves c_i are presented, see the parts (a) of Figs. 1–6 for $i = 1; 4, \dots, 12$ and, for $i = 13$, also Fig. 7(a) in Section 6, where Π is replaced by a regular prism². The center O^* of S^2 and of the cube or prism Π , coincides with the center of gravity G_i^* of each curve c_i^* , and none of these curves is contained in a great circle of S^2 ($i = 1; 4, \dots, 13$). Thus the κ_0 -curve c_i corresponding to c_i^* by Proposition (a), Eq. (2) is *closed and nonplanar*³; it is of class C^2 since c_i^* is of class C^1 . Furthermore c_i consists of helical arcs which correspond to the circular arcs of c_i^* and can be explicitly found according to Section 4. In this context, the way how the *path* c_i^* is traced is essential: it is formally determined by the structural formula of c_i^* which is additionally visualized in Figs. 2–5 by a *planar diagram* of the path c_i^* , which is gained by developing those faces of the cube Π which contain arcs of c_i^* , and by numbering in the same way the circular arcs of c_i^* and their corresponding helical arcs of c_i (compare Figs. 2–5, parts (b), (c)).

In Fig. 6 the shape of the curve c_{12} , and how this curve is traced, is visualized — in a different way — by indicating the correspondence between the endpoints (linking points) A, \dots, K of the circular arcs of c_{12}^* and the pairs $\{A_1, A_2\}, \dots, \{K_1, K_2\}$ of corresponding image points of c_{12} . The fact that the condition $G_i^* = O^*$ is really satisfied for all of the curves/paths c_i^* ($i = 1, \dots, 14$) of this note can be deduced either from symmetry (for instance, O^* is the point of symmetry of c_i^* for $i = 1, 3, 8-14$) or directly from the planar diagram (see the curves c_i^* , $i = 4-8$, in the Figs. 2–5).

For practical reasons the two cases $c_i^* \neq \mathcal{I}$ and $c_i^* = \mathcal{I}$ are now to be distinguished in the following Sections 5.2, 5.3 which deal with the Examples 1, 4–12, referring to a cube Π .

5.2. Case $c^* \neq \mathcal{I}$

The simplest of the Examples 1, 4–8 (Figs. 1(a), 2–5) of this case are the nonplanar closed κ_0 -curves of the Examples 1 (Fig. 1(a)), 4 (Fig. 2) and 8 (Fig. 5) which consist of *congruent* helical arcs, the congruent circular arcs of the corresponding tangent indicatrix having the central angle $\pi/2$, π and $3\pi/2$, respectively. Further examples of closed κ_0 -curves can be derived from the above curves by *insertion* of a pair of helical arcs being congruent (by translation, see Example 5 in Fig. 3, or by reflection with respect to the axis of the first helical arc and translation, see Example 12 in Section 5.3) and by *joining* two or more closed κ_0 -curves (Examples 6, 7 in Fig. 4; see Examples 9–11 in Section 5.3, too). Note: the insertion

²For further examples c_i^* ($i = 2, 3, 14$) of spherical images of nonplanar closed κ_0 -curves c_i see Section 3.2, Fig. 1(b),(c) for $i = 2, 3$, and footnote 3 for $i = 14$.

³and, moreover, no arc of c_i ($i = 1, \dots, 13$) lies in a plane. On the other hand, there also are nonplanar closed κ_0 -curves c of class C^2 being composed of planar and nonplanar arcs, e.g. ≥ 2 circular arcs and ≥ 2 helical arcs. The spherical image $c^* =: c_{14}^*$ of a closed κ_0 -curve $c =: c_{14}$ of this kind (Example 14) may be composed, for example, as a path $c_{14}^* := s_1 \cup g_1 \cup s_2 \cup g_2$ consisting of a pair of semicircles g_1, g_2 of a great circle $g \subset S^2$ and two small circles s_1, s_2 on S^2 each of which is tangent to g at one of the two common endpoints of g_1, g_2 in such a way that s_2 is symmetric to s_1 with respect to the center O^* of S^2 .

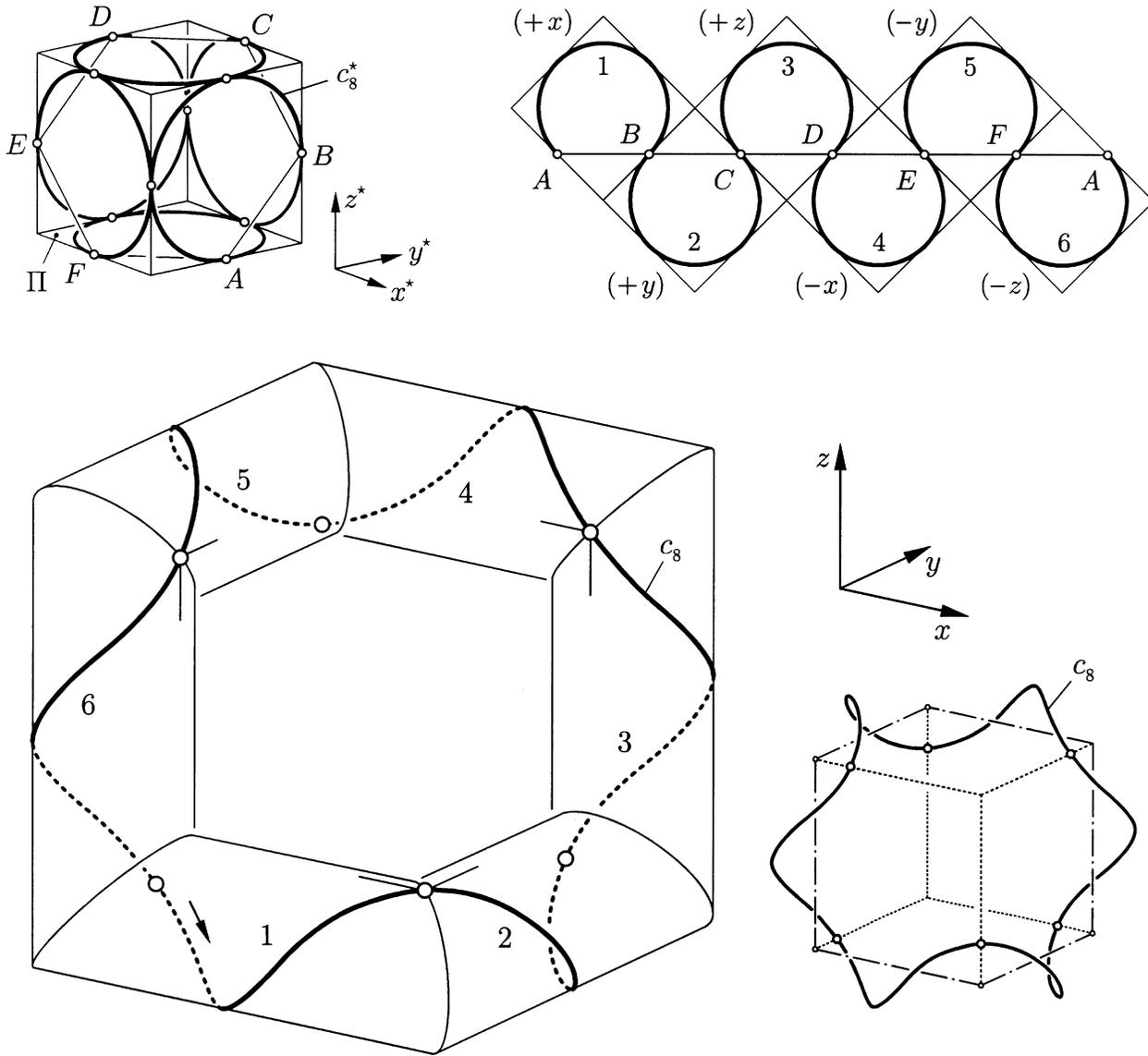


Figure 5: (Example 8) Closed κ_0 -curve c_8 of class C^2 , consisting of six congruent helical arcs having three pairwise orthogonal axial directions; $c_8^* : -[3/4]ABCDEFA$

of a pair of helical arcs, being congruent as described above and having the angle of rotation $l \cdot 2\pi$ ($l \in \mathbb{N}$), into a closed κ_0 -curve c is *equivalent* to the insertion a pair of complete incircles — each of them being covered l times — of opposite faces of the cube Π into the tangent indicatrix c^* of c ; this action does not change the center of gravity $G^* = O^*$ of c^* .

5.3. Case $c^* = \mathcal{I}$:

Finally, we show that there are closed κ_0 -curves having a spherical image c^* lying in a cube Π of edge length $e = \sqrt{2}$ and having the property $c^* = \mathcal{I}$ in the following sense: Except for the 12 edge-midpoints of Π , each of which then will be covered twice, the path c^* covers each point of \mathcal{I} , which equals the union of the six incircles of the faces of the cube Π , once and only once. Referring to Fig. 6(a), one can easily verify that each of the four curves $c_i^* \subseteq \mathcal{I}$

($i = 9, 10, 11, 12$), the path on $\Pi \cap S^2$ of which is described by the structural formula:

$$\begin{aligned} c_9^* &: -[3/4]ABCDEF A[1/4]AFEDCBA = -[1/4]BA[3/4]ABCDEF A[1/4]AFEDCB \\ &= -[1/2]\underline{BKB}[3/4]BCDEF[1/2]\underline{FJF}[1/4]FEDCB, \\ c_{10}^* &: +[1/2]AHDGA[1/4]AJ[1/2]\underline{JCJ}[1/4]JG[1/2]GDH[1/4]HK[1/2]\underline{KEK}[1/4]KA, \\ c_{11}^* &: +[1/2]AHD\underline{GAG}[1/4]GE[1/2]\underline{EKE}[1/4]EDC[1/2]\underline{CJC}[1/4]CH[1/2]HA, \\ c_{12}^* &: +[1/4]AB[1/2]\underline{BIB}[1/4]BH[1/2]HD\underline{GAG}DH[1/4]HK[1/2]\underline{KEK}[1/4]KA, \end{aligned}$$

respectively (complete circles are underlined), satisfies the property $c_i^* = \mathcal{I}$. Therefore the center O^* of the cube Π coincides with the center of gravity of the path c_i^* ($i = 9, 10, 11, 12$), too. Consequently, each of these pathes c_i^* is the tangent indicatrix of closed κ_0 -curves c_i . These *four examples* 9, 10, 11, 12 of closed κ_0 -curves the tangent indicatrix of which is $c_9^*, c_{10}^*, c_{11}^*, c_{12}^*$, respectively, are quite different one from each other. Each of the three curves $c_9^*, c_{10}^*, c_{11}^*$ can be separated into a pair $c_i^* =: a_i^* \cup b_i^*$ ($i = 9, 10, 11$) of independent tangent indicatrices of closed κ_0 -curves being characterized by the structural formulas (referring to Fig. 6(a)):

$$\begin{aligned} a_9^* &: -[3/4]ABCDEF A, & b_9^* &: +[1/4]AFEDCBA; \\ a_{10}^* &: +[1/2]AHDGA, \\ b_{10}^* &: -[1/4]AJ[1/2]\underline{JCJ}[1/4]JG[1/2]GDH[1/4]HK[1/2]\underline{KEK}[1/4]KA; \\ a_{11}^* &= a_{10}^*, & b_{11}^* &: -[1/2]AG[1/4]GE[1/2]\underline{EKE}[1/4]EDC[1/2]\underline{CJC}[1/4]CH[1/2]HA. \end{aligned}$$

Complete circles are underlined. One can easily verify that O^* is the center of gravity of each of the six curves a_i^*, b_i^* ($i = 9, 10, 11$), too. Note that curves like a_9^*, b_9^* and $a_{10}^* = a_{11}^*$ have already occurred (except for $a_9^* = c_8^*$, with different notation) in the Examples 8, 1, 4 (see Figs. 5, 1(a), 2), respectively.

The spherical images b_{10}^* or b_{11}^* from above obviously arise from a spherical curve c^* of type $-[1/2]AGDHA$ by inserting a pair of (complete) circles lying in opposite faces ($z^* = \pm e/2 = \pm 1/\sqrt{2}$) of the cube Π , namely the circles being described by $+ [1/2]JCJ$, $- [1/2]KEK$ or $- [1/2]EKE$, $+ [1/2]CJC$, respectively. Compare here Example 4 in Fig. 2; note that the path $- [1/2]AGDHA$ arises from a_{10}^* by reflection with respect to the plane being parallel to the z^* -axis and passing through A, D)

Hence follows that each of the closed κ_0 -curves b_{10} or b_{11} , the tangent indicatrix of which is b_{10}^* or b_{11}^* , respectively, arises from a curve c of Example 4, having the same constant curvature κ_0 , by inserting — in different ways — a pair of congruent arcs of circular helices of curvature κ_0 and angle of rotation 2π , the axes of which are parallel to the z -axis and thus *orthogonal* to the axes of the helical arcs of c , which are parallel to the x - or y -axis, respectively. Consequently, the curves b_{10} and b_{11} are (other than the curves a_{10} and a_{11} corresponding to a_{10}^* and a_{11}^* , respectively) *new examples* of closed κ_0 -curves, being different — though generated by “insertion”, too — from those of Example 5 in Fig. 3. The explicit drawing of a closed κ_0 -curve having c_9^*, c_{10}^* or c_{11}^* as its tangent indicatrix may be left to the reader.

The curve c_{12}^* and the corresponding closed κ_0 -curves c_{12} do not separate: according to the structural formula of c_{12}^* and/or Fig. 6(b), the curve c_{12} can obviously be generated from a closed κ_0 -curve c_6 as Example 6 (Fig. 4) being characterized, with respect to Fig. 6(a),

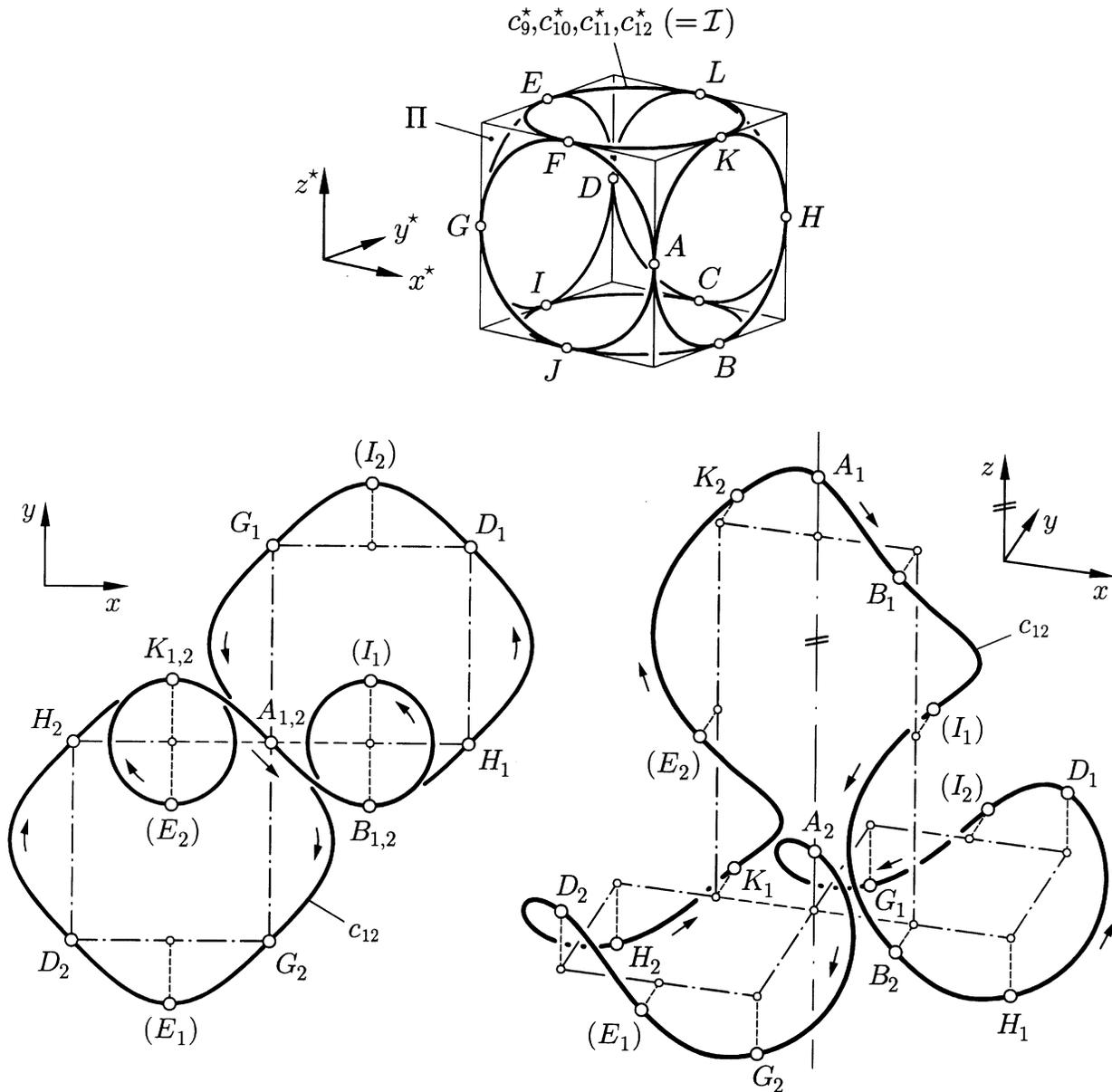


Figure 6: (Examples 9, 10, 11, 12) Closed “separating” κ_0 -curves c_9, c_{10}, c_{11} (not shown in this figure) and the “non-separating” closed κ_0 -curve c_{12} , each of them of class C^2 , having the common tangent indicatrix $c_i^* = \mathcal{I}$ ($i = 9, \dots, 12$): except for the 12 edge midpoints of the cube Π — each of which is covered twice — c_i^* covers each point of the six incircles of the faces of Π once and only once. The curve c_{12} is symmetric with respect to the line A_1A_2

by the rewritten structural formula⁴ $c_6^* : +[1/2]AHDGAGDHA$ by inserting two congruent helical arcs $\widehat{B_1(I_1)B_2}$, $\widehat{K_1(E_2)K_2}$, corresponding to the pair of complete circles $-[1/2]BIB$, $-[1/2]KEK$ of c^* , at the midpoint — corresponding to B or K — of the helical arc of c_6 which corresponds to $+[1/2]AH = +[1/4]ABH$ or $+[1/2]HA = +[1/4]HKA$, respectively. The shape and the course of a closed κ_0 -curve c_{12} corresponding to c_{12}^* can be recognized, for instance, by drawing a pair of orthographic views of c_{12} , compare the top view of c_{12} in

⁴The points A, B, C, D of c_6^* in Fig. 4(a),(b) now are to be replaced by H, A, G, D , respectively.

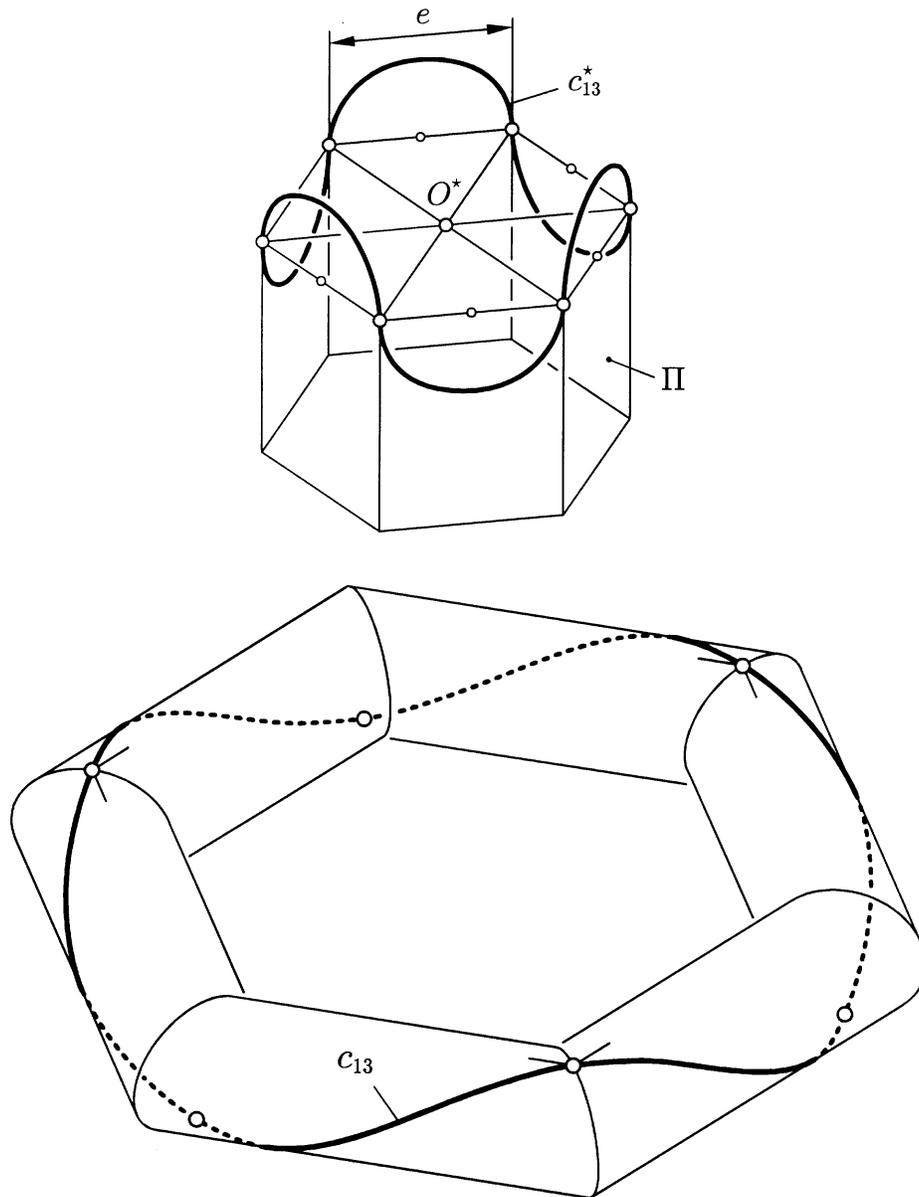


Figure 7: (Example 13) Closed κ_0 -curve c_{13} of class C^2 , consisting of six congruent helical arcs having three complanar axial directions

Fig. 6(b). Note that the helical arcs of c_{12} in our case ($\alpha = \pi/4$; orthogonal projection with respect to a coordinate plane) project into arcs of either *circles* of (with respect to (8)) radius $1/(2\kappa_0)$ or of *sinusoidal curves* having π/κ_0 as *length of period* and the *amplitude* $1/(2\kappa_0)$.

Fig. 6 shows in (b) the normal projection of c_{12} into the plane $z = 0$ (top view) and in (c) an axonometric representation of c_{12} . The closed κ_0 -curve c_{12} is composed of 12 arcs (see below) of a pair of helices being inversely congruent (anti-congruent). Note that all of the *circular arcs* of c_{12}^* being contained in a *pair of opposite faces* $x^* = \pm e / y^* = \pm e / z^* = \pm e$ of Π are *oriented in the same sense* $+/- -/-$, respectively, thus corresponding to arcs of c_{12} which belong to *circular helices* being directly congruent, the axes of which are parallel to the x -/ y -/ z -axis, respectively. As a point of c_{12}^* , each of the 8 edge-midpoints A, B, D, E, G, H, I, K of the cube Π appearing in the formula of c_{12}^* has a *pair of image*

points $\{A_1, A_2\}, \dots, \{K_1, K_2\}$ on c_{12} . Using 12 of these points, corresponding to the six points A, B, D, G, H, K of c_{12}^* , the course of the closed κ_0 -curve c_{12} is determined by the sequence of the points $A_1 B_1 B_2 H_1 D_1 G_1 A_2 G_2 D_2 H_2 K_1 K_2 A_1$: c_{12} is composed of 12 helical arcs $\widehat{A_1 B_1}, \widehat{B_1 B_2}, \dots, \widehat{K_2 A_1}$ being numerated by $1, 2, \dots, 12$, each two consecutive arcs having *anti-congruent supporting circular helices* and thus *differing in the sign of the torsion*. With respect to the positive z -direction, the six helical arcs #1-3, 5, 7, 9 of c_{12} are *descending*, the other six arcs #4, 6, 8, 10-12 are *ascending*. To ease the understanding, the Figs. 6(b),(c) additionally show the four points I_1, I_2, E_1, E_2 of c_{12} which correspond to the points I, E of c_{12}^* . More in detail, the course of c_{12} now is described by the sequence of the points $A_1 B_1 (I_1) B_2 H_1 D_1 (I_2) G_1 A_2 G_2 (E_1) D_2 H_2 K_1 (E_2) K_2 A_1$: the four additional points I_1, I_2, E_1, E_2 — which are put in brackets in the point sequence and in the Figs. 6(b),(c) since they are no endpoints of helical arcs of c_{12} — are the midpoints of the helical arcs # 2, 5, 8, 11 respectively. These are the arcs $\widehat{B_1 B_2}, \widehat{D_1 G_1}, \widehat{G_2 D_2}, \widehat{K_1 K_2}$.

6. Outlook: Further possibilities of constructing closed κ_0 -curves

In Fig. 2 all of the circular arcs of the spherical curve c_4^* are contained in the $n := 4$ “vertical” faces of the cube Π , being parallel to the z^* -axis. More generally, the cube Π can be replaced by a *right prism* Π with center O^* , its lateral edges being parallel to the z^* -axis and its bases, lying in the parallel planes $z^* = \pm 1$, being regular n -gons ($n \geq 3$) of circumradius 1, which can be represented by the congruent regular n -gon $A_1 A_2 \dots A_n$ cut from Π by the plane $z^* = 0$ (and generalizing the square = regular 4-gon $ABCD$ in Fig. 2(a)). Let \mathcal{I} denote the intersection of the right prism Π and the sphere S^2 , having the center O^* and the radius 1; so \mathcal{I} consists of a chain of n congruent complete circles. Then any regular curve/path $c^* \subseteq \mathcal{I}$ of class C^1 having O^* as its center of gravity can be chosen to be the tangent indicatrix of nonplanar κ_0 -curves of class C^2 consisting of helical arcs, the axes being parallel to the plane $z = 0$. In the simplest case, c^* consists of n , if n is even, or $2n$ if n is odd, congruent semi-circles: then the path c^* can be described by the structural formula $\pm[1/2]A_1 A_2 \dots A_n A_1$ (n even) or $\pm[1/2]A_1 A_2 \dots A_n A_1 A_2 \dots A_n A_1$ (n odd), respectively. For $n = 4$ and $n = 6$, see Example 4 (Fig. 2) and Example 13 (Fig. 7), respectively.

Nonplanar closed κ_0 -curves of class C^r ($r \geq 3$), in particular of class C^ω , can also be determined, for instance by analytic representations using *elliptic* integrals, using Proposition and certain properties of symmetry of the tangent indicatrix c^* . Explicit examples of *nonplanar closed κ_0 -curves of class C^ω* will be presented in a forthcoming note.

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Received April 28, 1998; final form June 18, 1998