Tubular Surfaces of Finite Type Gauss map

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Abstract. In this study, we continue the classification of finite type Gauss map surfaces in the 3-dimensional Euclidean space \mathbb{E}^3 . To do this, we investigate an important family of surfaces, namely, tubular surfaces in \mathbb{E}^3 . We show that the Gauss map of a tubular surface is of an infinite type regarding the second fundamental form.

Key Words: tubular surface in Euclidean 3-space, surface of finite II-type, Laplace operator

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1 Introduction

The theory of surfaces of finite Chen type was introduced by B.-Y. Chen in the late 1970s. From that moment on, interest in this field became widespread by many differential geometers, and it remains until this moment.

Let \boldsymbol{x} be an isometric immersion of a surface S in the 3-dimensional Euclidean space \mathbb{E}^3 . We represent by Δ^I the Laplacian operator of S acting on the space of smooth functions $C^{\infty}(S)$. Then S is said to be of finite I-type, if the position vector \boldsymbol{x} of S can be decomposed as a finite sum of eigenvectors of Δ^I of S, that is

$$\boldsymbol{x} = \boldsymbol{c} + \boldsymbol{x}_1 + \boldsymbol{x}_2 + \dots + \boldsymbol{x}_k,$$

where

$$\Delta^I \boldsymbol{x}_i = \xi_i \, \boldsymbol{x}_i, \quad i = 1, \dots, k,$$

c is a fixed vector and $\xi_1, \xi_2, \ldots, \xi_k$ are eigenvalues of the operator Δ^I .

In the framework of surfaces of finite type S. Stamatakis and H. Al-Zoubi in [22] defined the notion of surfaces of finite type associated with the second or third fundamental form.

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For results concerning surfaces of finite type associated with the second or third fundamental form (see [1, 3, 5, 6, 8, 9, 12]).

Another generalization can be made by studying surfaces in \mathbb{E}^3 of coordinate finite type, that is, their position vector \boldsymbol{x} satisfying the relation

$$\Delta^J \boldsymbol{x} = A \boldsymbol{x}, \quad J = II, III, \tag{1}$$

where $A \in \mathbb{R}^{3 \times 3}$.

H. Al-Zoubi and S. Stamatakis in [13] studied ruled and quadric surfaces of coordinate finite type with respect to the third fundamental form satisfying

$$\Delta^{III} \boldsymbol{x} = A \boldsymbol{x}. \tag{2}$$

The same authors in [23] classified the class of surfaces of revolution satisfying condition (2). Later in [14], the translation surfaces were studied, and it was proved that Sherk's surface is the only translation surface satisfying (2). B. Senoussi and M. Bekkar, in [21] classified the Helicoidal surfaces with $\Delta^J r = Ar, J = I, II, III$.

On the other hand, H. Al-Zoubi, T. Hamadneh in [11] classified the class of surfaces of revolution satisfying

$$\Delta^{II} \boldsymbol{x} = A \boldsymbol{x}$$

where $A \in \mathbb{R}^{3 \times 3}$.

Similarly, we can apply the notion of surfaces of finite type to a smooth map, for example, the Gauss map of a surface. Here in this kind of research, many results can be found in ([2, 4, 7, 10, 15-18, 20]).

In this research, we will focus on surfaces of finite II-type. Firstly, we will define the second differential parameter of Beltrami with respect to the second fundamental form of M^2 . Further, we continue our study by proving infinite type Gauss map for an important class of surfaces, namely, tubes in \mathbb{E}^3 .

2 Preliminaries

Let $\boldsymbol{x} = \boldsymbol{x}(u^1, u^2)$ be a regular parametric representation of a surface M^2 in the Euclidean 3-space \mathbb{E}^3 referred to any coordinate system, which does not contain parabolic points. We denote by b_{ij} the components of the second fundamental form $II = b_{ij}du^i du^j$ of S. Let $\varphi(u^1, u^2)$ be a sufficient differentiable function on M^2 . Then the second differential parameter of Beltrami with respect to the second fundamental form of M^2 is defined by [20]

$$\Delta^{II}\varphi := -\frac{1}{\sqrt{|b|}} (\sqrt{|b|} b^{ij} \varphi_{i})_{j}, \qquad (3)$$

where (b^{ij}) denotes the inverse tensor of (b_{ij}) and $b := \det(b_{ij})$.

Up to now, spheres are the only known surfaces of finite II-type in \mathbb{E}^3 . So one can ask:

Problem. Other than the spheres, which surfaces in \mathbb{E}^3 are of finite II-type?

This paper provides the first attempt at the study of finite type Gauss map of surfaces in \mathbb{E}^3 corresponding to the second fundamental form. In general when the Gauss map of M^2 is of finite type k, then there exists a polynomial $R(x) \neq 0$, such that $R(\Delta^{II})(\boldsymbol{n} - \boldsymbol{c}) = \boldsymbol{0}$. If $R(x) = x^k + \rho_1 x^{k-1} + \cdots + \rho_{k-1} x + \rho_k$, then coefficients ρ_i are given by

$$\rho_{1} = -(\xi_{1} + \xi_{2} + \dots + \xi_{k}),
\rho_{2} = (\xi_{1}\xi_{2} + \xi_{1}\xi_{3} + \dots + \xi_{1}\xi_{k} + \xi_{2}\xi_{3} + \dots + \xi_{2}\xi_{k} + \dots + \xi_{k-1}\xi_{k}),
\rho_{3} = -(\xi_{1}\xi_{2}\xi_{3} + \dots + \xi_{k-2}\xi_{k-1}\xi_{k}),
\dots
\rho_{k} = (-1)^{k}\xi_{1}\xi_{2} \cdots \xi_{k}.$$

Hence the Gauss map \boldsymbol{n} satisfies, (see [19])

$$(\Delta^{II})^k \boldsymbol{n} + \rho_1 (\Delta^{II})^{k-1} \boldsymbol{n} + \dots + \rho_k (\boldsymbol{n} - \boldsymbol{c}) = \boldsymbol{0}.$$
(4)

Our main result is the following

Theorem 1. All tubes in \mathbb{E}^3 are of infinite type Gauss map corresponding to the second fundamental form.

Our discussion is local, which means that we show in fact that any open part of the Gauss map of a tube is of infinite Chen type.

3 Tubes in \mathbb{E}^3

Let $\ell : \boldsymbol{q} = \boldsymbol{q}(u), u\epsilon(a, b)$ be a regular unit speed curve of finite length. Suppose that $\boldsymbol{t}, \boldsymbol{h}, \boldsymbol{b}$ is the Frenet frame and $\kappa > 0$ the curvature of the unit speed curve \boldsymbol{q} . Then a regular parametric representation of a tubular surface \mathfrak{F} of radius r satisfies $0 < r < \min \frac{1}{|\kappa|}$ is given by

$$\mathfrak{F}: \boldsymbol{x}(u, \psi) = \boldsymbol{q} + r \cos \psi \boldsymbol{h} + r \sin \psi \boldsymbol{b}.$$

One can find that fundamental forms I and II of \mathfrak{F} are given by

$$I = \left(\delta^2 + r^2\tau^2\right) du^2 + 2r^2\tau dud\psi + r^2 d\psi^2,$$

$$II = \left(-\kappa\delta\cos\psi + r\tau^2\right) du^2 + 2r\tau dud\psi + rd\psi^2,$$

where $\delta := (1 - r\kappa \cos \psi)$ and τ is the torsion of the curve q. The Gauss curvature of \mathfrak{F} is given by

$$K = -\frac{\kappa \cos \psi}{r\delta}$$

In the following we consider an open portion of the tube surface where $K \neq 0 \iff \cos \psi \neq 0$. From (3) the Laplace operator Δ^{II} of \mathfrak{F} is (see [1], formula (9))

$$\Delta^{II} = \frac{1}{\kappa\delta\cos\psi} \left[\frac{\partial^2}{\partial u^2} - 2\tau \frac{\partial^2}{\partial u\partial\psi} + \left(\tau^2 - \frac{\kappa\delta\cos\psi}{r}\right) \frac{\partial^2}{\partial\psi^2} + \frac{(1-2\delta)\beta}{2\kappa\delta\cos\psi} \frac{\partial}{\partial u} + \left(-\tau' + \frac{\tau\beta(2\delta-1)}{2\kappa\delta\cos\psi} + \frac{\kappa(2\delta-1)\sin\psi}{2r}\right) \frac{\partial}{\partial\psi} \right], \quad (5)$$

where $\beta := \kappa \cos \psi + \kappa \tau \sin \psi$ and $\dot{} := \frac{d}{du}$.

The Gauss map $\boldsymbol{n}(u, \psi)$ of \mathfrak{F} has parametric representation

$$\boldsymbol{n}(u,\psi) = -\cos\psi\boldsymbol{h} - \sin\psi\boldsymbol{b}.$$

Inserting \boldsymbol{n} in (5), we obtain

$$\Delta^{II}\boldsymbol{n} = \frac{\beta}{2\kappa\delta^2\cos\psi}\boldsymbol{t} + \left(\frac{\sin^2\psi}{2r\delta\cos\psi} + \frac{\cos\psi}{r\delta} - \frac{2\cos\psi}{r}\right)\boldsymbol{h} + \frac{(1-4\delta)\sin\psi}{2r\delta}\boldsymbol{b},\tag{6}$$

We distinguish two cases

Case I. $\beta \neq 0$. Relation (6) can be written

$$\Delta^{II} \boldsymbol{n} = \frac{\beta}{2\kappa\delta^2 \cos\psi} \boldsymbol{t} + \frac{1}{\kappa\delta \cos\psi} \boldsymbol{P}_1(\cos\psi, \sin\psi), \tag{7}$$

where $P_1(\cos\psi, \sin\psi)$ is a vector with components polynomials of the functions $\cos\psi$ and $\sin\psi$ with coefficients functions of the variable u.

After long calculations, $(\Delta^{II})^2 \boldsymbol{n}$ can be computed as follows

$$(\Delta^{II})^2 \boldsymbol{n} = \frac{(3\delta - 2)(12\delta - 7)\beta^3}{4\kappa^4 \delta^5 \cos^4 \psi} \boldsymbol{t} + \frac{1}{(\kappa\delta\cos\psi)^4} \boldsymbol{P}_2(\cos\psi, \sin\psi), \tag{8}$$

where $P_2(\cos \psi, \sin \psi)$ is a vector with components polynomials of the functions $\cos \psi$ and $\sin \psi$ with coefficients functions of the variable u. For later use we put

$$(3\delta - 2)(12\delta - 7) = h_2(\delta).$$
(9)

From (7), one can see that $h_1(\delta) = 1$.

We need the following lemma which can be proved directly by using (5).

Lemma 1. For any natural numbers m and n, we have

$$\Delta^{II}\left(\frac{h_k(\delta)\beta^m}{\delta^n(\kappa\cos\psi)^{n-1}}\right) = -\frac{h_{k+1}(\delta)\beta^{m+2}}{2\delta^{n+3}(\kappa\cos\psi)^{n+2}} + \frac{1}{(\kappa\delta\cos\psi)^{n+2}}Q(\cos\psi,\sin\psi), \quad (10)$$

where $h_k(\delta)$ is a polynomial in δ of degree d, Q is a polynomial in $\cos \psi$, $\sin \psi$ of degree n + 3 with functions in u as coefficients, $deg(h_{k+1}(\delta)) = d + 2$ and

$$h_{k+1}(\delta) = ((2n-1)\delta - n)(4(n+1)\delta - (2n+3))h_k(\delta).$$
(11)

So, it is easily verified that

$$(\Delta^{II})^{3}\boldsymbol{n} = \frac{(3\delta - 2)(12\delta - 7)(9\delta - 5)(24\delta - 13)\beta^{5}}{8\kappa^{7}\delta^{8}\cos^{7}\psi}\boldsymbol{t} + \frac{1}{(\kappa\delta\cos\psi)^{7}}\boldsymbol{P}_{3}(\cos\psi,\sin\psi), \quad (12)$$

where $P_3(\cos\psi, \sin\psi)$ is a vector with components polynomials of the functions $\cos\psi$ and $\sin\psi$ with coefficients functions of the variable u.

Moreover, by using Lemma 1, one can find

$$(\Delta^{II})^k \boldsymbol{n} = \frac{h_k(\delta)\beta^{2k-1}}{2^k \delta^{3k-1} (\kappa \cos \psi)^{3k-2}} \boldsymbol{t} + \frac{1}{(\kappa \delta \cos \psi)^{3k-2}} \boldsymbol{P}_k(\cos \psi, \sin \psi),$$
(13)

and

$$(\Delta^{II})^{k+1}\boldsymbol{n} = \frac{h_{k+1}(\delta)\beta^{2k+1}}{2^{k+1}\delta^{3k+2}(\kappa\cos\psi)^{3k+1}}\boldsymbol{t} + \frac{1}{(\kappa\delta\cos\psi)^{3k+1}}\boldsymbol{P}_{k+1}(\cos\psi,\sin\psi), \qquad (14)$$

where $P_k(\cos\psi, \sin\psi)$, $P_{k+1}(\cos\psi, \sin\psi)$ are vectors with components polynomials of the functions $\cos\psi$, $\sin\psi$ with coefficients functions of the variable u, and

$$h_{\lambda}(\delta) = \prod 12j\delta(4j-5) \neq 0, \quad j = 1, 2, \dots, \lambda - 1$$

$$(15)$$

for any positive integer λ .

Now, we suppose that the tube \mathfrak{F} is of finite type, thus from (7)-(14), and (4) we find that

$$\frac{h_{k+1}(\delta)\beta^{2k+1}}{2^{k+1}\delta^{3k+2}(\kappa\cos\psi)^{3k+1}}\boldsymbol{t} + \frac{1}{(\kappa\delta\cos\psi)^{3k+1}}\boldsymbol{P}_{k+1} + \frac{\rho_1h_k(\delta)\beta^{2k-1}}{2^k\delta^{3k-1}(\kappa\cos\psi)^{3k-2}}\boldsymbol{t} + \frac{\rho_1}{(\kappa\delta\cos\psi)^{3k-2}}\boldsymbol{P}_k$$
$$+ \dots + \frac{\rho_{k-1}(3\delta-2)(12\delta-7)\beta^3}{4\kappa^4\delta^5\cos^4\psi}\boldsymbol{t} + \frac{\sigma_{k-1}}{(\kappa\delta\cos\psi)^4}\boldsymbol{P}_2 + \frac{\rho_k\beta}{2\kappa\delta^2\cos\psi}\boldsymbol{t} + \frac{\rho_k}{\kappa\delta\cos\psi}\boldsymbol{P}_1 = \boldsymbol{0}.$$

The above equation can be simply written as follows

$$\frac{h_{k+1}(\delta)\beta^{2k+1}}{\delta}\boldsymbol{t} = Q_1(\cos\psi,\sin\psi)\boldsymbol{t} + Q_2(\cos\psi,\sin\psi)\boldsymbol{h} + Q_3(\cos\psi,\sin\psi)\boldsymbol{b}, \qquad (16)$$

where $Q_i(\cos\psi, \sin\psi)$ are polynomials in $\cos\psi$ and $\sin\psi$.

Case I. $\beta \neq 0$. From (16), we have

$$\frac{h_{k+1}(\delta)\beta^{2k+1}}{\delta} = Q_1(\cos\psi, \sin\psi). \tag{17}$$

This is impossible for any $k \ge 1$ since $h_{k+1}(\delta) \ne 0$.

Case II. $\beta \equiv 0$. Then $\kappa' = 0$ and $\kappa \tau = 0$. Thus $\kappa = \text{const.} \neq 0$ and $\tau = 0$, therefore the curve \boldsymbol{q} is a plane circle and so, \mathfrak{F} is an anchor ring. In this case, the first fundamental form becomes

$$I = \delta^2 du^2 + r^2 d\psi^2,$$

while the second is

$$II = -\kappa\delta\cos\psi du^2 + rd\psi^2.$$

Hence, equation (5) reduces to

$$\Delta^{II} = \frac{1}{\kappa\delta\cos\psi} \left(\frac{\partial^2}{\partial u^2} - \frac{\kappa\delta\cos\psi}{r} \frac{\partial^2}{\partial\psi^2} + \frac{\kappa(2\delta-1)\sin\psi}{2r} \frac{\partial}{\partial\psi} \right).$$
(18)

Applying (18) for the position vector \boldsymbol{n} , one finds

$$\Delta^{II}\boldsymbol{n} = \left(\frac{\sin^2\psi}{2r\delta\cos\psi} + \frac{\cos\psi}{r\delta} - \frac{2\cos\psi}{r}\right)\boldsymbol{h} + \frac{(1-4\delta)\sin\psi}{2r\delta}\boldsymbol{b},$$

which can be written as follows

$$\Delta^{II} \boldsymbol{n} = \frac{\sin^2 \psi}{2r\delta \cos \psi} \boldsymbol{h} + \frac{1}{\delta} \boldsymbol{F}_1(\cos \psi, \sin \psi).$$
(19)

Consequently, we get

$$(\Delta^{II})^2 \boldsymbol{n} = -\frac{3\sin^4\psi}{4r^2\delta^3\cos^3\psi} \boldsymbol{h} + \frac{1}{\delta^2\cos^3\psi} \boldsymbol{F}_2(\cos\psi,\sin\psi), \qquad (20)$$

where $F_1(\cos\psi, \sin\psi)$, $F_2(\cos\psi, \sin\psi)$ are vectors with components polynomials of the functions $\cos\psi$, $\sin\psi$ with coefficients functions of the variable u.

One can easily prove that

$$\Delta^{II} \frac{\sin^m \psi}{(\delta \cos \psi)^n} = -\frac{3 \sin^{m+2} \psi}{2r (\delta \cos \psi)^{n+2}} + \frac{1}{(\delta \cos \psi)^{n+1}} Q(\cos \psi, \sin \psi),$$

where $Q(\cos\psi, \sin\psi)$ is a polynomial in $\cos\psi, \sin\psi$ with coefficients functions of the variable u. Therefore, we find that

$$(\Delta^{II})^{k} \boldsymbol{n} = (-1)^{k-1} \frac{3^{k-1} \sin^{2k} \psi}{(2r)^{k} (\delta \cos \psi)^{2k-1}} \boldsymbol{h} + \frac{1}{\delta^{2k-1} \cos^{2k-2} \psi} \boldsymbol{F}_{k}(\cos \psi, \sin \psi)$$
(21)

and

$$(\Delta^{II})^{k+1}\boldsymbol{n} = (-1)^k \frac{3^k \sin^{2k+2} \psi}{(2r)^{k+1} (\delta \cos \psi)^{2k+1}} \boldsymbol{h} + \frac{1}{\delta^{2k+1} \cos^{2k} \psi} \boldsymbol{F}_{k+1}(\cos \psi, \sin \psi), \qquad (22)$$

where $F_k(\cos\psi, \sin\psi)$, $F_{k+1}(\cos\psi, \sin\psi)$ are vectors with components polynomials of the functions $\cos\psi$, $\sin\psi$ with coefficients functions of the variable u.

On account of (19), (20), (21), (22) and (4), we conclude that

$$(-1)^{k} \frac{3^{k} \sin^{2k+2} \psi}{(2r)^{k+1} (\delta \cos \psi)^{2k+1}} \boldsymbol{h} + \frac{1}{\delta^{2k+1} \cos^{2k} \psi} \boldsymbol{F}_{k+1} (\cos \psi, \sin \psi) + (-1)^{k-1} \rho_{1} \frac{3^{k-1} \sin^{2k} \psi}{(2r)^{k} (\delta \cos \psi)^{2k-1}} \boldsymbol{h} + \rho_{1} \frac{1}{\delta^{2k-1} \cos^{2k-2} \psi} \boldsymbol{F}_{k} (\cos \psi, \sin \psi) + \dots - \rho_{k-1} \frac{3 \sin^{4} \psi}{4r^{2} \delta^{3} \cos^{3} \psi} \boldsymbol{h} + \rho_{k-1} \frac{1}{\delta^{3} \cos^{2} \psi} \boldsymbol{F}_{2} (\cos \psi, \sin \psi) + \rho_{k} \frac{\sin^{2} \psi}{2r \delta \cos \psi} \boldsymbol{h} + \rho_{k} \frac{1}{\delta} \boldsymbol{F}_{1} (\cos \psi, \sin \psi) = \boldsymbol{\theta}.$$
(23)

For simplicity, equation (23) can be written as follows

$$\frac{3^k \sin^{2k+2} \psi}{(2r)^{k+1} \cos \psi} \boldsymbol{h} = Q_1(\cos \psi, \sin \psi) \boldsymbol{h} + Q_2(\cos \psi, \sin \psi) \boldsymbol{b},$$
(24)

where $Q_i(\cos\psi, \sin\psi)$, i = 1, 2 are polynomials in $\cos\psi, \sin\psi$ with coefficients functions of the variable u. Therefore, we find that

$$\frac{3^k \sin^{2k+2} \psi}{(2r)^{k+1} \cos \psi} = Q_1(\cos \psi, \sin \psi).$$
(25)

This is impossible, since the right side hand Q_1 is a polynomial in $\cos \psi$, $\sin \psi$ while the left side hand is not. Thus, our theorem is proved.

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